

Spectral Frank-Wolfe Algorithm: Strict Complementarity and Linear Convergence

Lijun Ding

Joint work with Yingjie Fei, Qiantong Xu, and Chengrun Yang

June 15, 2020

1 Introduction

- Problem setup
- Past algorithms

2 SpecFW and strict complementarity

- Spectral Frank-Wolfe (SpecFW)
- Strict complementarity

3 Numerics

- Experimental setup
- Numerical results

Convex smooth minimization over a spectrahedron

Main optimization problem:

Main optimization problem:

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- function g strongly convex and smooth

Convex smooth minimization over a spectrahedron

Main optimization problem:

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- function g strongly convex and smooth
- linear map \mathcal{A} and matrix $C \in \mathbf{S}^n$

Convex smooth minimization over a spectrahedron

Main optimization problem:

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- function g strongly convex and smooth
- linear map \mathcal{A} and matrix $C \in \mathbf{S}^n$
- trace $\mathbf{tr}(\cdot)$, sum of diagonals

Convex smooth minimization over a spectrahedron

Main optimization problem:

$$\begin{array}{ll} \text{minimize} & f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n} & \\ \text{subject to} & \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{array} \quad (\text{M})$$

- function g strongly convex and smooth
- linear map \mathcal{A} and matrix $C \in \mathbf{S}^n$
- trace $\mathbf{tr}(\cdot)$, sum of diagonals
- positive semidefinite matrices \mathbf{S}_+^n , i.e., symmetric matrices with non-negative eigenvalues

Convex smooth minimization over a spectrahedron

Main optimization problem:

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- function g strongly convex and smooth
- linear map \mathcal{A} and matrix $C \in \mathbf{S}^n$
- trace $\mathbf{tr}(\cdot)$, sum of diagonals
- positive semidefinite matrices \mathbf{S}_+^n , i.e., symmetric matrices with non-negative eigenvalues
- **unique** optimal solution X_*

$$\begin{array}{ll} \text{minimize} & f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n} & \\ \text{subject to} & \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{array} \quad (\text{M})$$

$$\begin{array}{ll} \text{minimize} & f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n} & \\ \text{subject to} & \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{array} \quad (\text{M})$$

- matrix sensing [RFP10]

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- matrix sensing [RFP10]
- matrix completion [CR09, JS10]

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- matrix sensing [RFP10]
- matrix completion [CR09, JS10]
- phase retrieval [CESV15, YUTC17]

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- matrix sensing [RFP10]
- matrix completion [CR09, JS10]
- phase retrieval [CESV15, YUTC17]
- one-bit matrix completion [DPVDBW14]

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- matrix sensing [RFP10]
- matrix completion [CR09, JS10]
- phase retrieval [CESV15, YUTC17]
- one-bit matrix completion [DPVDBW14]
- blind deconvolution [ARR13]

$$\begin{aligned} & \underset{X \in \mathbf{S}^n \subset \mathbf{R}^{n \times n}}{\text{minimize}} && f(X) := g(\mathcal{A}X) + \mathbf{tr}(CX) \\ & \text{subject to} && \mathbf{tr}(X) = 1, \quad \text{and} \quad X \in \mathbf{S}_+^n, \end{aligned} \tag{M}$$

- matrix sensing [RFP10]
- matrix completion [CR09, JS10]
- phase retrieval [CESV15, YUTC17]
- one-bit matrix completion [DPVDBW14]
- blind deconvolution [ARR13]

Expect rank $r_\star = \mathbf{rank}(X_\star) \ll n!$

Projected Gradient (PG)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

Projected Gradient (PG)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- orthogonal projection: $\mathcal{P}_{\mathcal{SP}^n}(X) = \arg \min_V \|X - V\|_F$

Projected Gradient (PG)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- orthogonal projection: $\mathcal{P}_{\mathcal{SP}^n}(X) = \arg \min_V \|X - V\|_F$
- PG: Choose $X_0 \in \mathcal{SP}^n$ and $\eta > 0$, iterate

$$X_{t+1} = \mathcal{P}_{\mathcal{SP}^n}(X_t - \eta \nabla f(X_t)). \quad (\text{PG})$$

Projected Gradient (PG)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- orthogonal projection: $\mathcal{P}_{\mathcal{SP}^n}(X) = \arg \min_V \|X - V\|_F$
- PG: Choose $X_0 \in \mathcal{SP}^n$ and $\eta > 0$, iterate

$$X_{t+1} = \mathcal{P}_{\mathcal{SP}^n}(X_t - \eta \nabla f(X_t)). \quad (\text{PG})$$

- iteration complexity $\mathcal{O}(\frac{1}{\epsilon})$

Projected Gradient (PG)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- orthogonal projection: $\mathcal{P}_{\mathcal{SP}^n}(X) = \arg \min_V \|X - V\|_F$
- PG: Choose $X_0 \in \mathcal{SP}^n$ and $\eta > 0$, iterate

$$X_{t+1} = \mathcal{P}_{\mathcal{SP}^n}(X_t - \eta \nabla f(X_t)). \quad (\text{PG})$$

- iteration complexity $\mathcal{O}(\frac{1}{\epsilon})$
- accelerated PG, $\mathcal{O}(\frac{1}{\sqrt{\epsilon}})$

Projected Gradient (PG)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- orthogonal projection: $\mathcal{P}_{\mathcal{SP}^n}(X) = \arg \min_V \|X - V\|_F$
- PG: Choose $X_0 \in \mathcal{SP}^n$ and $\eta > 0$, iterate

$$X_{t+1} = \mathcal{P}_{\mathcal{SP}^n}(X_t - \eta \nabla f(X_t)). \quad (\text{PG})$$

- iteration complexity $\mathcal{O}(\frac{1}{\epsilon})$
- accelerated PG, $\mathcal{O}(\frac{1}{\sqrt{\epsilon}})$

Bottleneck: $\mathcal{O}(n^3)$ per iteration due to FULL EVD in $\mathcal{P}_{\mathcal{SP}^n}$!

Projection free method: Frank-Wolfe (FW)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\mathbf{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

Projection free method: Frank-Wolfe (FW)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\mathbf{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- FW: choose $X_0 \in \mathcal{SP}^n$, iterate

(LOO) Linear Optimization Oracle: $V_t = \arg \min_{V \in \mathcal{SP}^n} \mathbf{tr}(V \nabla f(X_t))$.

Projection free method: Frank-Wolfe (FW)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\mathbf{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- FW: choose $X_0 \in \mathcal{SP}^n$, iterate
- (LOO) Linear Optimization Oracle: $V_t = \arg \min_{V \in \mathcal{SP}^n} \mathbf{tr}(V \nabla f(X_t))$.
- (LS) Line Search: X_{t+1} solves $\min_{X = \eta X_t + (1-\eta)V_t, \eta \in [0,1]} f(X)$.
- **Low per iteration complexity:** LOO only needs to compute one eigenvector of $\nabla f(X_t)$!

Projection free method: Frank-Wolfe (FW)

$$\text{minimize}_{X \in \mathbf{S}^n} f(X) \quad \text{subject to} \quad \underbrace{\text{tr}(X) = 1, X \in \mathbf{S}_+^n}_{\mathcal{SP}^n}, \quad (\text{M})$$

- FW: choose $X_0 \in \mathcal{SP}^n$, iterate
- (LOO) Linear Optimization Oracle: $V_t = \arg \min_{V \in \mathcal{SP}^n} \text{tr}(V \nabla f(X_t))$.
- (LS) Line Search: X_{t+1} solves $\min_{X = \eta X_t + (1-\eta)V_t, \eta \in [0,1]} f(X)$.
- **Low per iteration complexity:** LOO only needs to compute one eigenvector of $\nabla f(X_t)$!

Bottleneck: Slow convergence, $\mathcal{O}(\frac{1}{\epsilon})$ iteration complexity in both theory and practice!

Many variants:

- Randomized regularized FW [Gar16]
- In-face direction FW [FGM17]
- BlockFW [AZHHL17]
- FW with $r_\star = \mathbf{rank}(X_\star) = 1$ [Gar19]

**Shortage: No linear convergence or sensitive to input rank estimate
or $r_\star = 1$.**

- 1 Introduction
 - Problem setup
 - Past algorithms
- 2 SpecFW and strict complementarity
 - Spectral Frank-Wolfe (SpecFW)
 - Strict complementarity
- 3 Numerics
 - Experimental setup
 - Numerical results

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.
- k Spectral Search (k SS): $X_{t+1} = \eta_* X_t + VS_*V^\top$, in which $\eta_* \in \mathbf{R}, S_* \in \mathbf{S}^k$ solves

$$\min f(\eta X_t + VSV^\top) \quad \text{s.t.} \quad S \in \mathbf{S}_+^k, \eta + \mathbf{tr}(S) = 1, \eta \geq 0.$$

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.
- k Spectral Search (k SS): $X_{t+1} = \eta_* X_t + VS_* V^\top$, in which $\eta_* \in \mathbf{R}, S_* \in \mathbf{S}^k$ solves

$$\min f(\eta X_t + VSV^\top) \quad \text{s.t.} \quad S \in \mathbf{S}_+^k, \eta + \mathbf{tr}(S) = 1, \eta \geq 0.$$

Both procedure are easy to solve for small k !

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.
- k Spectral Search (k SS): $X_{t+1} = \eta_* X_t + VS_* V^\top$, in which $\eta_* \in \mathbf{R}, S_* \in \mathbf{S}^k$ solves

$$\min f(\eta X_t + VSV^\top) \quad \text{s.t.} \quad S \in \mathbf{S}_+^k, \eta + \mathbf{tr}(S) = 1, \eta \geq 0.$$

Both procedure are easy to solve for small k !

Moreover...

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.
- k Spectral Search (k SS): $X_{t+1} = \eta_* X_t + VS_* V^\top$, in which $\eta_* \in \mathbf{R}, S_* \in \mathbf{S}^k$ solves

$$\min f(\eta X_t + VSV^\top) \quad \text{s.t.} \quad S \in \mathbf{S}_+^k, \eta + \mathbf{tr}(S) = 1, \eta \geq 0.$$

Both procedure are easy to solve for small k !

Moreover...

- $\mathcal{O}(\frac{1}{\epsilon})$ convergence for general k .

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.
- k Spectral Search (k SS): $X_{t+1} = \eta_* X_t + VS_* V^\top$, in which $\eta_* \in \mathbf{R}, S_* \in \mathbf{S}^k$ solves

$$\min f(\eta X_t + VSV^\top) \quad \text{s.t.} \quad S \in \mathbf{S}_+^k, \eta + \mathbf{tr}(S) = 1, \eta \geq 0.$$

Both procedure are easy to solve for small k !

Moreover...

- $\mathcal{O}(\frac{1}{\epsilon})$ convergence for general k .
- **Linear convergence if $k \geq r_*$!**

Spectral Frank-Wolfe (SpecFW)

Spectral Frank-Wolfe: choose $X_0 \in \mathcal{SP}^n$, a rank estimate $k > 0$, iterate

- k LOO: Compute bottom k eigenvectors $V = [v_1, \dots, v_k] \in \mathbf{R}^{n \times k}$ of $\nabla f(X_t)$.
- k Spectral Search (k SS): $X_{t+1} = \eta_* X_t + VS_* V^\top$, in which $\eta_* \in \mathbf{R}, S_* \in \mathbf{S}^k$ solves

$$\min f(\eta X_t + VSV^\top) \quad \text{s.t.} \quad S \in \mathbf{S}_+^k, \eta + \mathbf{tr}(S) = 1, \eta \geq 0.$$

Both procedure are easy to solve for small k !

Moreover...

- $\mathcal{O}(\frac{1}{\epsilon})$ convergence for general k .
- **Linear convergence if $k \geq r_*$!** (also needs strict complementarity)

Comparison with FW

Two stronger subproblem oracles:

Table: Comparison with FW

FW	SpecFW
LOO: Compute one eigenvector v	k LOO: Compute k eigenvectors V

Comparison with FW

Two stronger subproblem oracles:

Table: Comparison with FW

FW	SpecFW
LOO: Compute one eigenvector v	k LOO: Compute k eigenvectors V
Line Search (LS): $\min f(\eta X_t + (1 - \eta)vv^\top)$ s.t. $\eta \in [0, 1]$	k Spectral Search (k SS): $\min f(\eta X_t + VSV^\top)$ s.t. $\eta \geq 0, S \in \mathbf{S}_+^k, \text{tr}(S) + \eta = 1$

Comparison with FW

Two stronger subproblem oracles:

Table: Comparison with FW

FW	SpecFW
LOO: Compute one eigenvector v	k LOO: Compute k eigenvectors V
Line Search (LS): $\min f(\eta X_t + (1 - \eta)vv^\top)$ s.t. $\eta \in [0, 1]$	k Spectral Search (k SS): $\min f(\eta X_t + VSV^\top)$ s.t. $\eta \geq 0, S \in \mathbf{S}_+^k, \mathbf{tr}(S) + \eta = 1$

In fact, when $k = 1$, SpecFW is FW!

Comparison with FW

Two stronger subproblem oracles:

Table: Comparison with FW

FW	SpecFW
LOO: Compute one eigenvector v	k LOO: Compute k eigenvectors V
Line Search (LS): $\min f(\eta X_t + (1 - \eta)vv^\top)$ s.t. $\eta \in [0, 1]$	k Spectral Search (k SS): $\min f(\eta X_t + VSV^\top)$ s.t. $\eta \geq 0, S \in \mathbf{S}_+^k, \text{tr}(S) + \eta = 1$

In fact, when $k = 1$, SpecFW is FW! Expect *at least* $\mathcal{O}(\frac{1}{\epsilon})$ convergence even if $k \leq r_*$.

Comparison with FW

Two stronger subproblem oracles:

Table: Comparison with FW

FW	SpecFW
LOO: Compute one eigenvector v	k LOO: Compute k eigenvectors V
Line Search (LS): $\min f(\eta X_t + (1 - \eta)vv^\top)$ s.t. $\eta \in [0, 1]$	k Spectral Search (k SS): $\min f(\eta X_t + VSV^\top)$ s.t. $\eta \geq 0, S \in \mathbf{S}_+^k, \mathbf{tr}(S) + \eta = 1$

In fact, when $k = 1$, SpecFW is FW! Expect *at least* $\mathcal{O}(\frac{1}{\epsilon})$ convergence even if $k \leq r_*$.

How about linear convergence when $k \geq r_*$?

Comparison with FW

Two stronger subproblem oracles:

Table: Comparison with FW

FW	SpecFW
LOO: Compute one eigenvector v	k LOO: Compute k eigenvectors V
Line Search (LS): $\min f(\eta X_t + (1 - \eta)vv^\top)$ s.t. $\eta \in [0, 1]$	k Spectral Search (k SS): $\min f(\eta X_t + VSV^\top)$ s.t. $\eta \geq 0, S \in \mathbf{S}_+^k, \mathbf{tr}(S) + \eta = 1$

In fact, when $k = 1$, SpecFW is FW! Expect *at least* $\mathcal{O}(\frac{1}{\epsilon})$ convergence even if $k \leq r_\star$.

How about linear convergence when $k \geq r_\star$?
What is strict complementarity?

Strict complementarity

Eigenspace of $\nabla f(X_*)$ for the smallest eigenvalue, $\mathbf{EV}(\nabla f(X_*)) \subset \mathbf{R}^n$

Strict complementarity

Eigenspace of $\nabla f(X_*)$ for the smallest eigenvalue, $\mathbf{EV}(\nabla f(X_*)) \subset \mathbf{R}^n$

$$\text{KKT} \implies \mathbf{range}(X_*) \subset \mathbf{EV}(\nabla f(X_*))$$

Strict complementarity

Eigenspace of $\nabla f(X_*)$ for the smallest eigenvalue, $\mathbf{EV}(\nabla f(X_*)) \subset \mathbf{R}^n$

$$\begin{aligned} \text{KKT} &\implies \mathbf{range}(X_*) \subset \mathbf{EV}(\nabla f(X_*)) \\ &\implies \underbrace{\dim(\mathbf{range}(X_*))}_{=:r_*} \leq \underbrace{\dim(\mathbf{EV}(\nabla f(X_*)))}_{=:k_*} \end{aligned}$$

Note that the smallest eigenvalue has multiplicity at least r_* :

$$\lambda_{n-r_*+1}(\nabla f(X_*)) = \cdots = \lambda_n(\nabla f(X_*)).$$

Here $\lambda_{n-i+1}(\nabla f(X_*))$ is the i -th smallest eigenvalue.

Strict complementarity

Eigenspace of $\nabla f(X_*)$ for the smallest eigenvalue, $\mathbf{EV}(\nabla f(X_*)) \subset \mathbf{R}^n$

$$\begin{aligned} \text{KKT} &\implies \mathbf{range}(X_*) \subset \mathbf{EV}(\nabla f(X_*)) \\ &\implies \underbrace{\dim(\mathbf{range}(X_*))}_{=:r_*} \leq \underbrace{\dim(\mathbf{EV}(\nabla f(X_*)))}_{=:k_*} \end{aligned}$$

Note that the smallest eigenvalue has multiplicity at least r_* :

$$\lambda_{n-r_*+1}(\nabla f(X_*)) = \cdots = \lambda_n(\nabla f(X_*)).$$

Here $\lambda_{n-i+1}(\nabla f(X_*))$ is the i -th smallest eigenvalue.

Strict complementarity (st. comp.) is $r_* = k_*$.

Strict complementarity

Eigenspace of $\nabla f(X_*)$ for the smallest eigenvalue, $\mathbf{EV}(\nabla f(X_*)) \subset \mathbf{R}^n$

$$\begin{aligned} \text{KKT} &\implies \mathbf{range}(X_*) \subset \mathbf{EV}(\nabla f(X_*)) \\ &\implies \underbrace{\dim(\mathbf{range}(X_*))}_{=:r_*} \leq \underbrace{\dim(\mathbf{EV}(\nabla f(X_*)))}_{=:k_*} \end{aligned}$$

Note that the smallest eigenvalue has multiplicity at least r_* :

$$\lambda_{n-r_*+1}(\nabla f(X_*)) = \cdots = \lambda_n(\nabla f(X_*)).$$

Here $\lambda_{n-i+1}(\nabla f(X_*))$ is the i -th smallest eigenvalue.

Strict complementarity (st. comp.) is $r_* = k_*$.

More concretely, st. comp. is an eigengap condition on r_* -th and $r_* + 1$ -th smallest eigenvalue:

$$\lambda_{n-r_*}(\nabla f(X_*)) - \lambda_{n-r_*+1}(\nabla f(X_*)) > 0.$$

Intuition of linear convergence

Under strict complementarity $r_\star = k_\star$:

Intuition of linear convergence

Under strict complementarity $r_\star = k_\star$:

① $\text{range}(X_\star) = \mathbf{EV}(\nabla f(X_\star))$

Intuition of linear convergence

Under strict complementarity $r_\star = k_\star$:

- 1 **range** $(X_\star) = \mathbf{EV}(\nabla f(X_\star))$
- 2 Compute $V_\star = [v_1, \dots, v_{k_\star}]$, the bottom eigenvectors of $\nabla f(X_\star)$.

Intuition of linear convergence

Under strict complementarity $r_\star = k_\star$:

- 1 **range** $(X_\star) = \mathbf{E}\mathbf{V}(\nabla f(X_\star))$
- 2 Compute $V_\star = [v_1, \dots, v_{k_\star}]$, the bottom eigenvectors of $\nabla f(X_\star)$.
- 3 $X_\star = V_\star S_\star V_\star^\top$ for some $S_\star \in \mathbf{S}_+^{r_\star}$, $\mathbf{tr}(S) = 1$

Under strict complementarity $r_\star = k_\star$:

- 1 **range** $(X_\star) = \mathbf{E}\mathbf{V}(\nabla f(X_\star))$
- 2 Compute $V_\star = [v_1, \dots, v_{k_\star}]$, the bottom eigenvectors of $\nabla f(X_\star)$.
- 3 $X_\star = V_\star S_\star V_\star^\top$ for some $S_\star \in \mathbf{S}_+^{r_\star}$, $\mathbf{tr}(S) = 1$
- 4 Obtain S_\star by solving

$$\text{minimize } f(V_\star S V_\star^\top) \quad \text{s.t. } S \in \mathbf{S}_+^{r_\star}, \mathbf{tr}(S) = 1. \quad (\text{reduced M})$$

- 5 Problem (M) is solved given $\nabla f(X_\star)$!

Intuition of linear convergence

Under strict complementarity $r_\star = k_\star$:

- 1 **range** $(X_\star) = \mathbf{E}\mathbf{V}(\nabla f(X_\star))$
- 2 Compute $V_\star = [v_1, \dots, v_{k_\star}]$, the bottom eigenvectors of $\nabla f(X_\star)$.
- 3 $X_\star = V_\star S_\star V_\star^\top$ for some $S_\star \in \mathbf{S}_+^{r_\star}$, $\mathbf{tr}(S) = 1$
- 4 Obtain S_\star by solving

$$\text{minimize } f(V_\star S_\star V_\star^\top) \quad \text{s.t. } S \in \mathbf{S}_+^{r_\star}, \mathbf{tr}(S) = 1. \quad (\text{reduced M})$$

- 5 Problem (M) is solved given $\nabla f(X_\star)$!

SpecFW is simply algorithmic procedures for step 2 and 4!

- 1 Introduction
 - Problem setup
 - Past algorithms
- 2 SpecFW and strict complementarity
 - Spectral Frank-Wolfe (SpecFW)
 - Strict complementarity
- 3 Numerics
 - Experimental setup
 - Numerical results

Experimental setup: Quadratic sensing

Quadratic Sensing [CCG15]: recover a rank $r_b = 3$ matrix $U_b \in \mathbf{R}^{n \times r_b}$ with $\|U_b\|_F^2 = 1$ from quadratic measurement $y \in \mathbf{R}^m$

Experimental setup: Quadratic sensing

Quadratic Sensing [CCG15]: recover a rank $r_b = 3$ matrix $U_b \in \mathbf{R}^{n \times r_b}$ with $\|U_b\|_F^2 = 1$ from quadratic measurement $y \in \mathbf{R}^m$

① random standard gaussian measurements a_i

② $y_0(i) = \left\| U_b^T a_i \right\|_F^2, i = 1, \dots, m, m = 15nr_b$

Experimental setup: Quadratic sensing

Quadratic Sensing [CCG15]: recover a rank $r_b = 3$ matrix $U_b \in \mathbf{R}^{n \times r_b}$ with $\|U_b\|_F^2 = 1$ from quadratic measurement $y \in \mathbf{R}^m$

- 1 random standard gaussian measurements a_i
- 2 $y_0(i) = \left\| U_b^\top a_i \right\|_F^2, i = 1, \dots, m, m = 15nr_b$
- 3 $y = y_0 + c \|y_0\|_2 v$, c is the inverse signal-to-noise ratio, v is a random unit vector

Experimental setup: Quadratic sensing

Quadratic Sensing [CCG15]: recover a rank $r_b = 3$ matrix $U_b \in \mathbf{R}^{n \times r_b}$ with $\|U_b\|_F^2 = 1$ from quadratic measurement $y \in \mathbf{R}^m$

- 1 random standard gaussian measurements a_i
- 2 $y_0(i) = \left\| U_b^\top a_i \right\|_F^2, i = 1, \dots, m, m = 15nr_b$
- 3 $y = y_0 + c \|y_0\|_2 v$, c is the inverse signal-to-noise ratio, v is a random unit vector

Optimization problem:

$$\text{minimize } f(X) := \frac{1}{2} \sum_{i=1}^m \left(a_i^\top X a_i - y_i \right)^2 \quad (\text{Quadratic Sensing})$$

$$\text{subject to } \mathbf{tr}(X) = \tau, \quad X \succeq 0.$$

Set $\tau = \frac{1}{2}$ and $c = 0.5$ in numerics.

Low rank solution and strict complementarity

Dimension n	Avg. gap	Avg. recovery error
100	288.06	0.0013
200	505.16	0.00064
400	961.09	0.00031
600	1358.62	0.00021

Table: Verification of low rankness and strict complementarity. Rank $r_* = 3$ in all experiments. The recovery error is measured by $\frac{\|X_* - U_b U_b^T\|_F}{\|U_b U_b^T\|_F}$. The gap is measured by $\lambda_{n-3}(\nabla f(X_*)) - \lambda_n(\nabla f(X_*))$. All the results are averaged over 20 iid trials.

Numerical results $k > r_*$

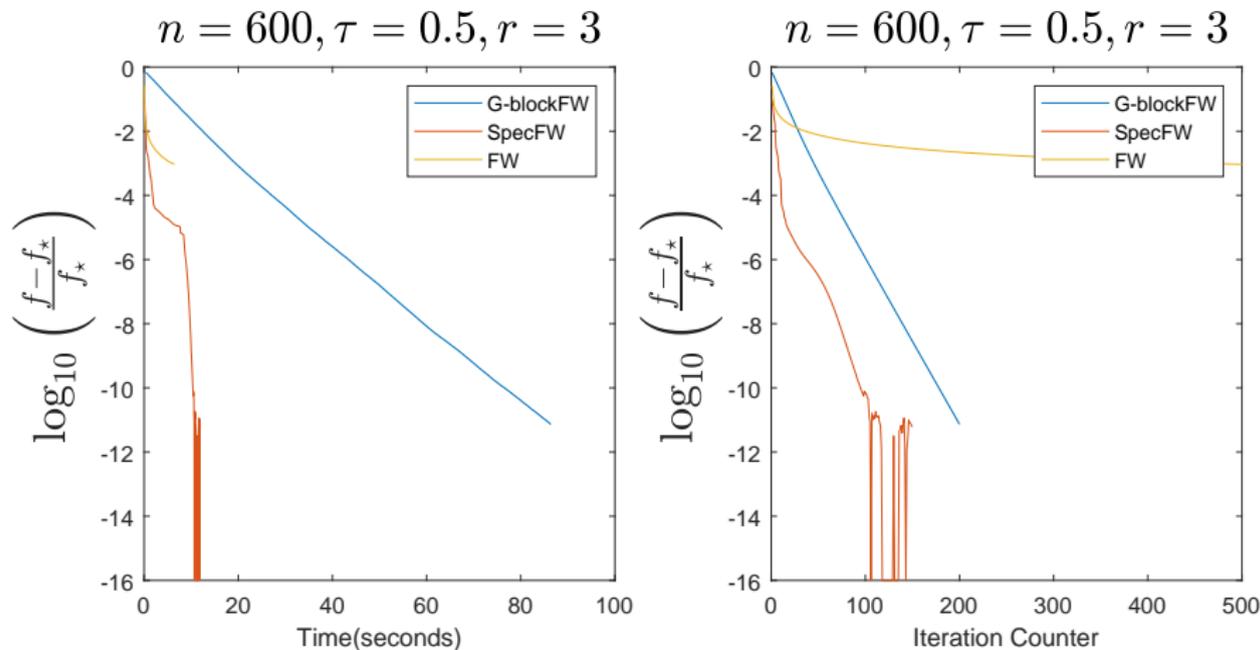


Figure: $k > r_*$. comparison of algorithms FW, G-blockFW [AZHHL17], and SpecFW. Left: accuracy vs time. Right: accuracy vs iteration.

Numerical results $k < r_*$

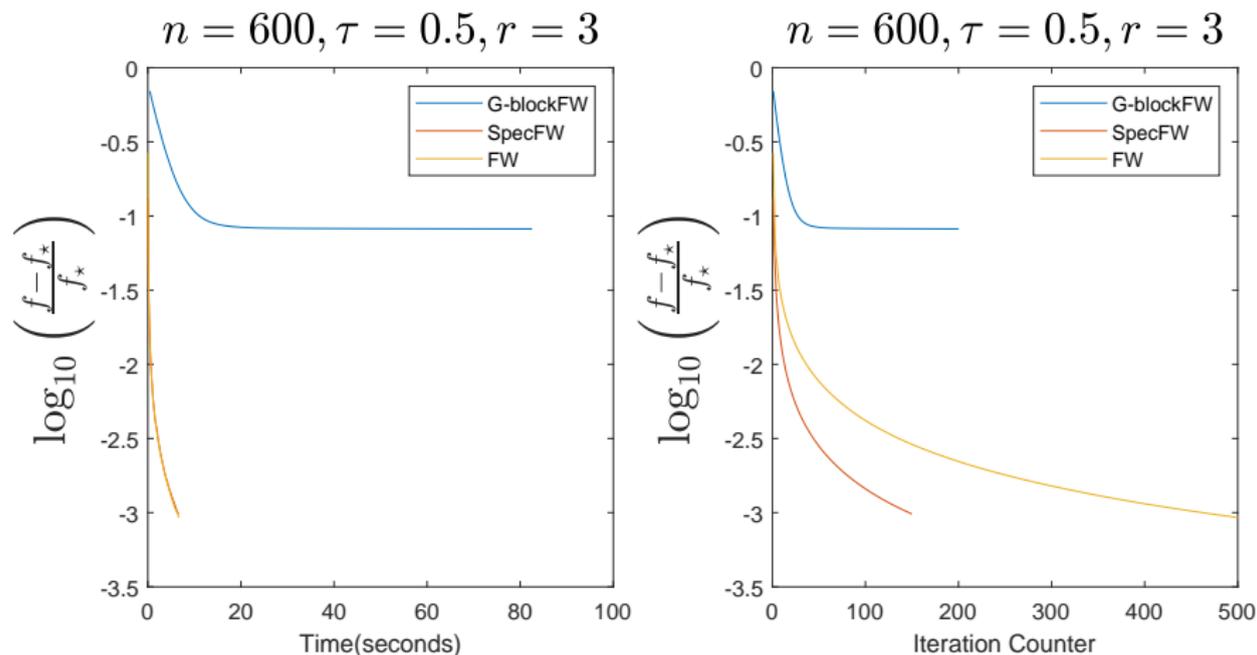


Figure: $k < r_*$. comparison of algorithms FW, G-blockFW [AZHHL17], and SpecFW. Left: accuracy vs time. Right: accuracy vs iteration.

References I

-  Ali Ahmed, Benjamin Recht, and Justin Romberg.
Blind deconvolution using convex programming.
IEEE Transactions on Information Theory, 60(3):1711–1732, 2013.
-  Zeyuan Allen-Zhu, Elad Hazan, Wei Hu, and Yuanzhi Li.
Linear convergence of a frank-wolfe type algorithm over trace-norm balls.
In *Advances in Neural Information Processing Systems*, pages 6191–6200, 2017.
-  Yuxin Chen, Yuejie Chi, and Andrea J Goldsmith.
Exact and stable covariance estimation from quadratic sampling via convex programming.
IEEE Transactions on Information Theory, 61(7):4034–4059, 2015.

References II



Emmanuel J Candes, Yonina C Eldar, Thomas Strohmer, and Vladislav Voroninski.

Phase retrieval via matrix completion.
SIAM review, 57(2):225–251, 2015.



Emmanuel J Candès and Benjamin Recht.

Exact matrix completion via convex optimization.
Foundations of Computational mathematics, 9(6):717, 2009.



Mark A Davenport, Yaniv Plan, Ewout Van Den Berg, and Mary Wootters.

1-bit matrix completion.
Information and Inference: A Journal of the IMA, 3(3):189–223, 2014.

References III



Robert M Freund, Paul Grigas, and Rahul Mazumder.

An extended frank-wolfe method with “in-face” directions, and its application to low-rank matrix completion.

SIAM Journal on optimization, 27(1):319–346, 2017.



Dan Garber.

Faster projection-free convex optimization over the spectrahedron.

In *Advances in Neural Information Processing Systems*, pages 874–882, 2016.



Dan Garber.

Linear convergence of frank-wolfe for rank-one matrix recovery without strong convexity.

arXiv preprint arXiv:1912.01467, 2019.



Martin Jaggi and Marek Sulovský.

A simple algorithm for nuclear norm regularized problems.
2010.



Benjamin Recht, Maryam Fazel, and Pablo A Parrilo.

Guaranteed minimum-rank solutions of linear matrix equations via nuclear norm minimization.
SIAM review, 52(3):471–501, 2010.



Alp Yurtsever, Madeleine Udell, Joel Tropp, and Volkan Cevher.

Sketchy decisions: Convex low-rank matrix optimization with optimal storage.
In *Artificial Intelligence and Statistics*, pages 1188–1196, 2017.