

Poisson Learning: Graph-based semi-supervised learning at very low label rates

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Outline

1 Introduction

- Graph-based semi-supervised learning
- Laplace learning/Label propagation
- Degeneracy in Laplace learning

2 Poisson learning

- Random walk perspective
- Variational interpretation

3 Experimental results

- Algorithmic details
- Datasets and algorithms
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Graph-based semi-supervised learning

Graph: $G = (X, W)$

- $X = \{x_1, \dots, x_n\}$ are the vertices of the graph
- $W = (w_{ij})_{i,j=1}^n$ are **nonnegative** and **symmetric** ($w_{ij} = w_{ji}$) edge weights.
- $w_{ij} \approx 1$ if x_i, x_j similar, and $w_{ij} \approx 0$ when dissimilar.

Labels: We assume the first $m \ll n$ vertices are given labels

$$y_1, y_2, \dots, y_m \in \{\mathbf{e}_1, \mathbf{e}_2, \dots, \mathbf{e}_k\} \in \mathbb{R}^k.$$

Task: Extend the labels to the rest of the vertices x_{m+1}, \dots, x_n .

Semi-supervised smoothness assumption

Similar points $x_i, x_j \in X$ in **high density** regions of the graph should have similar labels.

Laplace Learning/Label Propagation:

- Original work [Zhu et al., 2003]
- Learning [Zhou et al., 2005][Ando and Zhang, 2007]
- Manifold ranking [He et al., 2006] [Zhou et al., 2011] [Xu et al., 2011]

Laplace learning/Label propagation

Laplacian regularized semi-supervised learning solves the Laplace equation

$$\begin{cases} \mathcal{L}u(x_i) = 0, & \text{if } m + 1 \leq i \leq n, \\ u(x_i) = y_i, & \text{if } 1 \leq i \leq m, \end{cases}$$

where $u : X \rightarrow \mathbb{R}^k$, and \mathcal{L} is the graph Laplacian

$$\mathcal{L}u(x_i) = \sum_{j=1}^n w_{ij} (u(x_i) - u(x_j)).$$

The label decision for vertex x_i is determined by the largest component of $u(x_i)$

$$\ell(x_i) = \operatorname{argmax}_{j \in \{1, \dots, k\}} \{u_j(x)\}.$$

Label propagation

The solution of Laplace learning satisfies

$$\mathcal{L}u(x_i) = \sum_{j=1}^n w_{ij} (u(x_i) - u(x_j)) = 0. \quad (m+1 \leq i \leq n)$$

Re-arranging, we see that u satisfies the mean-property

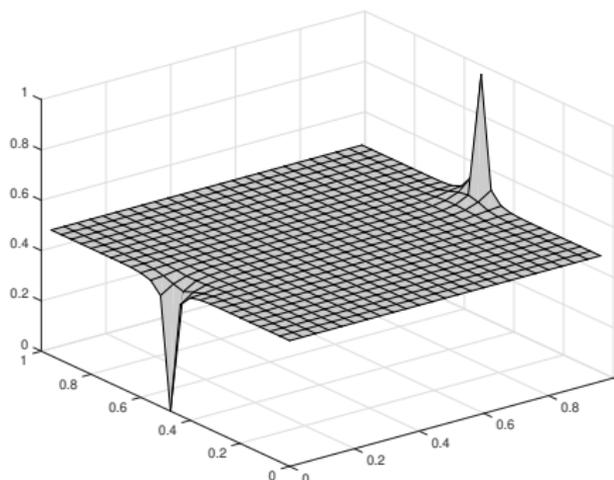
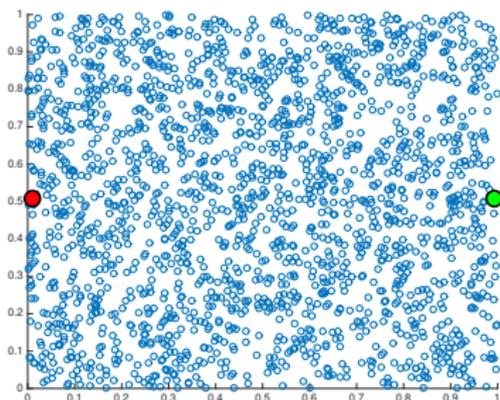
$$u(x_i) = \frac{\sum_{j=1}^n w_{ij} u(x_j)}{\sum_{j=1}^n w_{ij}}.$$

Label propagation [Zhu 2005] iterates

$$u^{k+1}(x_i) = \frac{\sum_{j=1}^n w_{ij} u^k(x_j)}{\sum_{j=1}^n w_{ij}},$$

and at convergence is equivalent to Laplace learning.

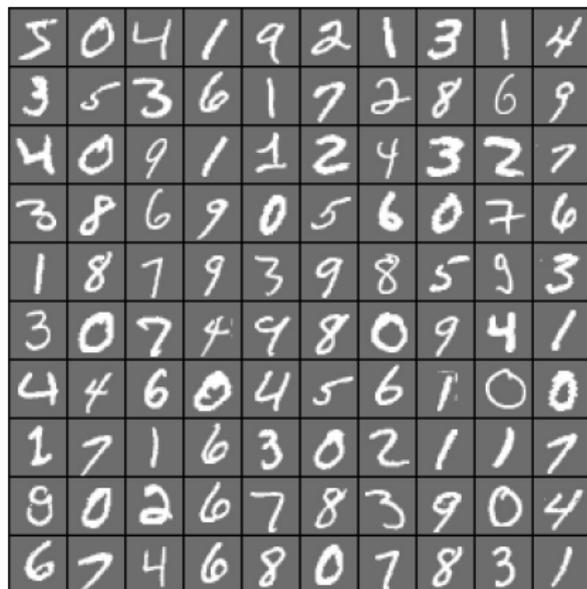
Ill-posed with small amount of labeled data



- Graph is $n = 10^5$ i.i.d. random variables uniformly drawn from $[0, 1]^2$.
- $w_{xy} = 1$ if $|x - y| < 0.01$ and $w_{xy} = 0$ otherwise.
- Two labels: $y_1 = 0$ at the Red point and $y_2 = 1$ at the Green point.
- Over 95% of labels in $[0.4975, 0.5025]$.

[Nadler et al., 2009][El Alaoui et al., 2016]

MNIST (70,000 28×28 pixel images of digits 0-9)



[Y. LeCun, L. Bottou, Y. Bengio, and P. Haffner. "Gradient-based learning applied to document recognition." Proceedings of the IEEE, 86(11):2278-2324, November 1998.]

Laplace learning on MNIST

# Labels/class	1	2	3	4	5
Laplace	16.1 (6.2)	28.2 (10)	42.0 (12)	57.8 (12)	69.5 (12)
Graph NN	58.8 (5.6)	66.6 (2.8)	70.2 (4)	71.3 (2.6)	73.4 (1.9)

# Labels/class	10	50	100	500	1000
Laplace	93.2 (2.3)	96.9 (0.1)	97.1 (0.1)	97.6 (0.1)	97.7 (0.0)
Graph NN	82.3 (1.0)	89.0 (0.5)	90.6 (0.4)	93.4 (0.1)	93.7 (0.1)

Average accuracy over 10 trials with standard deviation in brackets.

Graph NN: 1-nearest neighbor using graph geodesic distance.

Recent work

The low-label rate problem was originally identified in [Nadler 2009].

A lot of recent work has attempted to address this issue with new graph-based classification algorithms at low label rates.

- Higher-order regularization: [Zhou and Belkin, 2011], [Dunlop et al., 2019]
- p -Laplace regularization: [Alaoui et al., 2016], [Calder 2018,2019], [Slepcev & Thorpe 2019]
- Re-weighted Laplacians: [Shi et al., 2017], [Calder & Slepcev, 2019]
- Centered kernel method: [Mai & Couillet, 2018]

While we have lots of new models, the problem with Laplace learning at low label rates was still not well-understood.

In this talk:

- 1 We explain the degeneracy in terms of random walks.
- 2 We propose a new algorithm: **Poisson learning**.

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Poisson learning

We propose to replace Laplace learning

$$(1) \quad (\text{Laplace equation}) \quad \begin{cases} \mathcal{L}u(x_i) = 0, & \text{if } m + 1 \leq i \leq n, \\ u(x_i) = y_i, & \text{if } 1 \leq i \leq m, \end{cases}$$

with Poisson learning

$$(\text{Poisson equation}) \quad \mathcal{L}u(x_i) = \sum_{j=1}^m (y_j - c) \delta_{ij} \quad \text{for } i = 1, \dots, n$$

subject to $\sum_{i=1}^n d_i u(x_i) = 0$, where $c = \frac{1}{m} \sum_{i=1}^m y_i$.

In both cases, the label decision is the same:

$$\ell(x_i) = \operatorname{argmax}_{j \in \{1, \dots, k\}} \{u_j(x)\}.$$

Poisson learning

We propose to replace Laplace learning

$$(2) \quad (\text{Laplace equation}) \quad \begin{cases} \mathcal{L}u(x_i) = 0, & \text{if } m + 1 \leq i \leq n, \\ u(x_i) = y_i, & \text{if } 1 \leq i \leq m, \end{cases}$$

with Poisson learning

$$(\text{Poisson equation}) \quad \mathcal{L}u(x_i) = \sum_{j=1}^m (y_j - c)\delta_{ij} \quad \text{for } i = 1, \dots, n$$

subject to $\sum_{i=1}^n d_i u(x_i) = 0$, where $c = \frac{1}{m} \sum_{i=1}^m y_i$.

For Poisson learning, unbalanced class sizes can be incorporated:

$$\ell(x_i) = \operatorname{argmax}_{j \in \{1, \dots, k\}} \left\{ \frac{p_j}{n_j} u_j(x) \right\},$$

p_j = Fraction of data in class j

n_j = Fraction of training data from class j .

Random Walk Perspective

Suppose u solves the Laplace learning equation

$$\begin{cases} \mathcal{L}u(x_i) = 0, & \text{if } m + 1 \leq i \leq n, \\ u(x_i) = y_i, & \text{if } 1 \leq i \leq m. \end{cases}$$

Let $x \in X$ and let X_0, X_1, X_2, \dots be a random walk on X with transition probabilities

$$\mathbb{P}(X_k = x_j \mid X_{k-1} = x_i) = \frac{w_{ij}}{d_i} \quad \text{where } d_i = \sum_{j=1}^n w_{ij}.$$

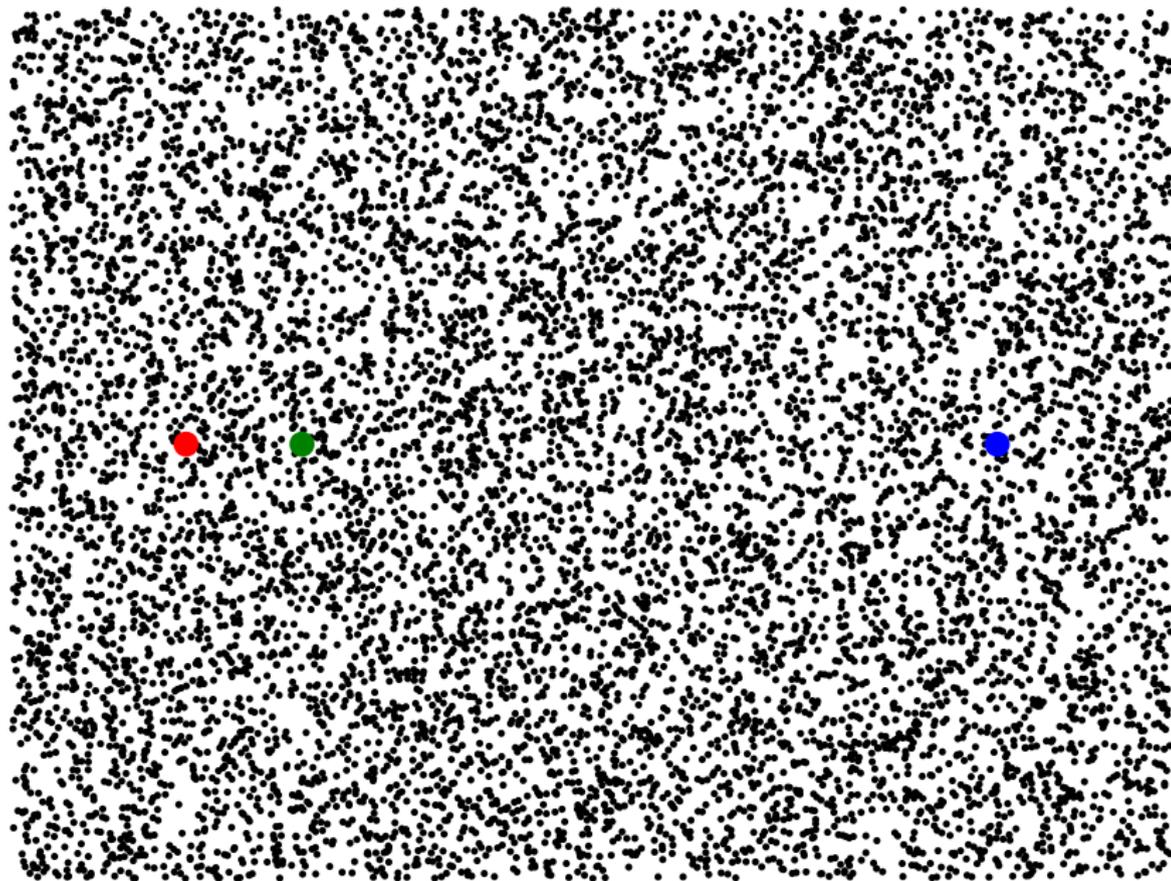
Define the stopping time to be the first time the walk hits a label, that is

$$\tau = \inf\{k \geq 0 : X_k \in \{x_1, x_2, \dots, x_m\}\}.$$

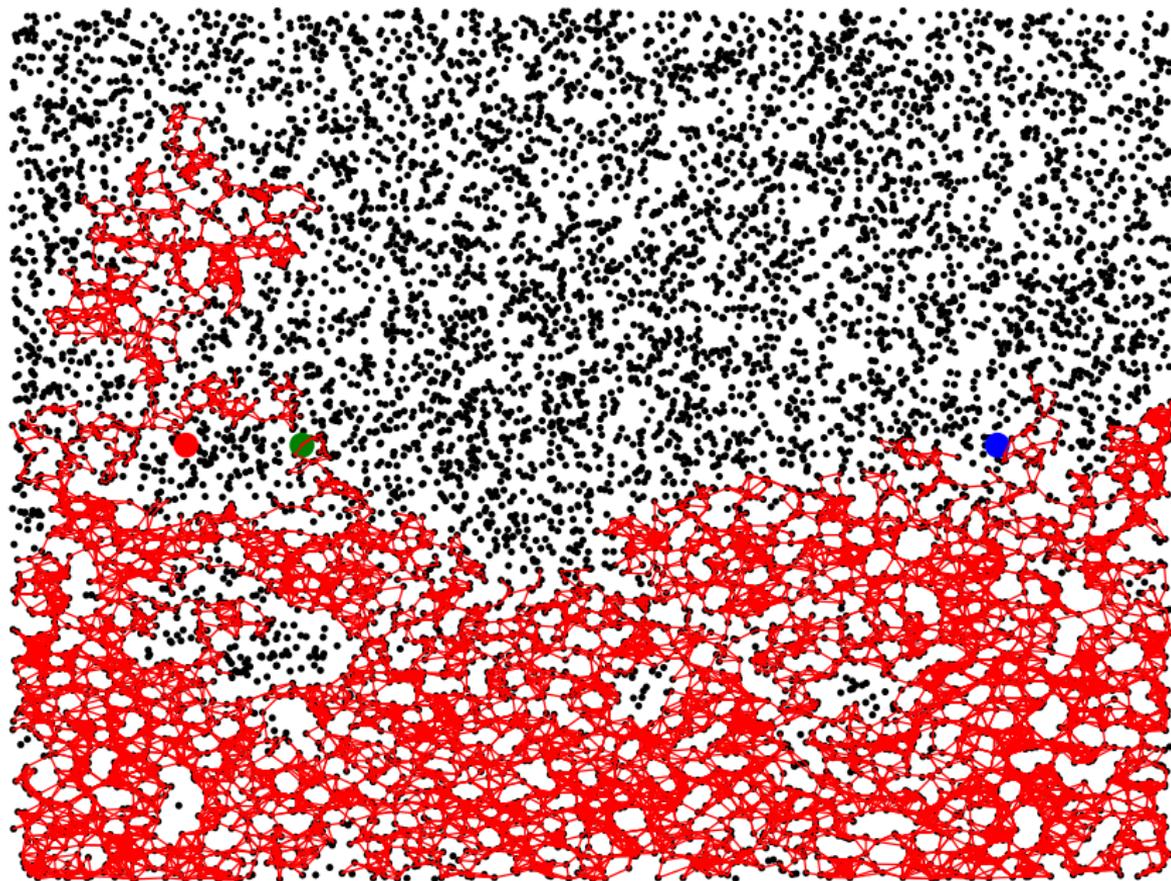
Let $i_\tau \leq m$ so that $X_\tau = x_{i_\tau}$. Then (by Doob's optimal stopping theorem)

$$(3) \quad \boxed{u(x) = \mathbb{E}[y_{i_\tau} \mid X_0 = x].}$$

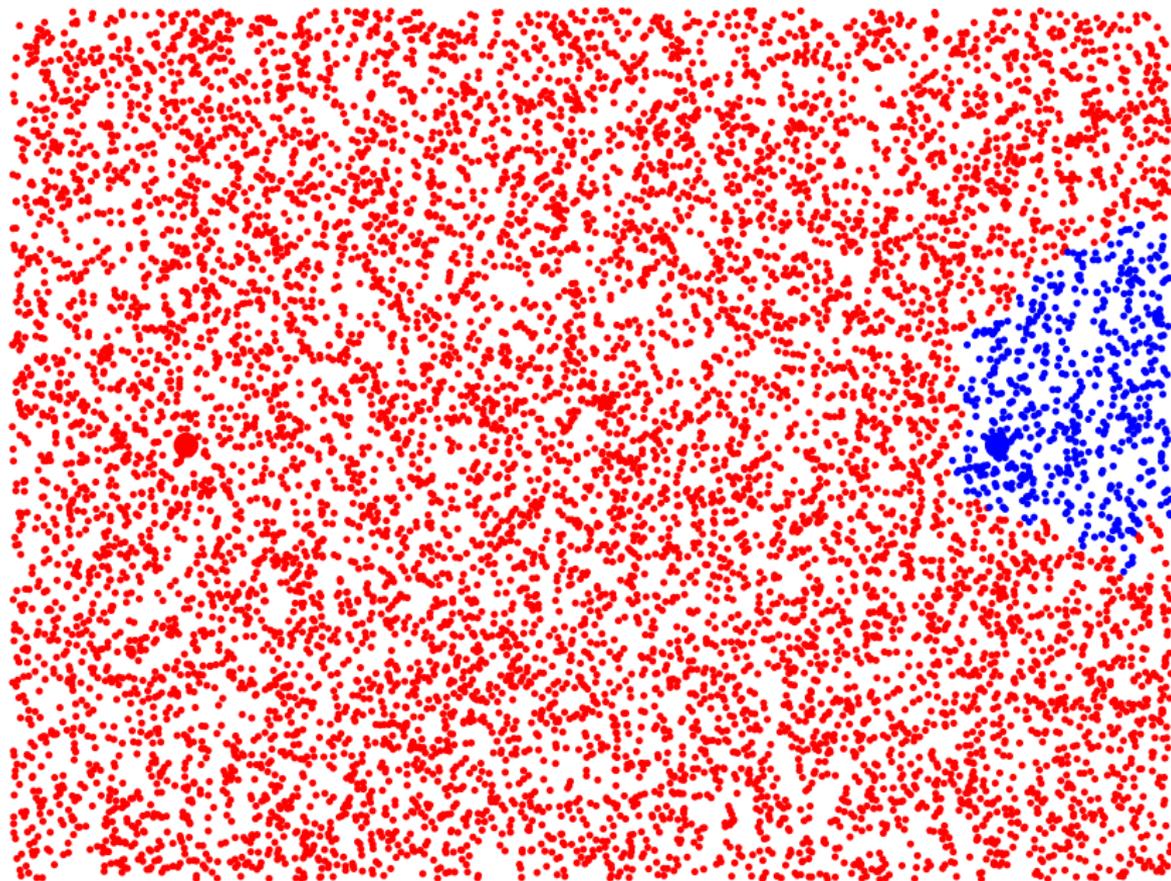
Classification experiment



Random walk experiment



Classification experiment



The Random walk perspective

At low label rates, the random walker reaches the **mixing time** before hitting a label.

- The label eventually hit is largely independent of where the walker starts.

After walking for a long time, the probability distribution of the walker approaches the **invariant distribution** π given by

$$\pi_i = \frac{d_i}{\sum_{j=1}^n d_j}.$$

Thus, the solution of Laplace learning is approximately

$$u(x_i) = \mathbb{E}[y_{i_\tau} \mid X_0 = x_i] \approx \frac{\sum_{j=1}^n d_j y_j}{\sum_{j=1}^n d_j} =: c \in \mathbb{R}^k.$$

Bottom line: Nearly everything is labeled by the one-hot vector closest to c !

The random walk perspective

Let $X_0^{x_j}, X_1^{x_j}, X_2^{x_j}$ be a random walk on the graph X starting from $x_j \in X$, and define

$$u_T(x_i) = \mathbb{E} \left[\sum_{k=0}^T \sum_{j=1}^m y_j \mathbb{1}_{\{X_k^{x_j} = x_i\}} \right].$$

Idea: We release random walkers from the **labeled nodes**, and record how often each label's walker visits x_i .

We can write

$$u_T(x_i) = \sum_{j=1}^m y_j \sum_{k=0}^T \mathbb{P}(X_k^{x_j} = x_i).$$

The inner term is a **Green's function** for a random walk. As $T \rightarrow \infty$, $u_T \rightarrow \infty$.

We center u_T by its mean value:

$$\sum_{i=1}^n u_T(x_i) = \sum_{k=0}^T \sum_{j=1}^m y_j = \sum_{k=0}^T mc, \quad \text{where } c = \frac{1}{m} \sum_{j=1}^m y_j.$$

The random walk perspective

Subtracting off the mean of u_T , and normalizing by d_i , we arrive at

$$u_T(x_i) := \mathbb{E} \left[\sum_{k=0}^T \frac{1}{d_i} \sum_{j=1}^m (y_j - c) \mathbb{1}_{\{X_k^{x_j} = x_i\}} \right], \quad \text{where } c = \frac{1}{m} \sum_{j=1}^m y_j.$$

Theorem

For every $T \geq 0$ we have

$$u_{T+1}(x_i) = u_T(x_i) + \frac{1}{d_i} \left(\sum_{j=1}^m (y_j - c) \delta_{ij} - \mathcal{L}u_T(x_i) \right).$$

If the graph G is connected and the Markov chain induced by the random walk is aperiodic, then $u_T \rightarrow u$ as $T \rightarrow \infty$, where $u : X \rightarrow \mathbb{R}$ is the solution of

$$\mathcal{L}u(x_i) = \sum_{j=1}^m (y_j - c) \delta_{ij} \quad \text{for } i = 1, \dots, n$$

satisfying $\sum_{i=1}^n d_i u(x_i) = 0$.

The variational interpretation

We define the space of weighted mean-zero functions

$$\ell_0^2(X) = \left\{ u : X \rightarrow \mathbb{R} : \sum_{i=1}^n d_i u(x_i) = 0 \right\}.$$

Consider the variational problem

$$(4) \quad \min_{u \in \ell_0^2(X)} \left\{ \sum_{i,j=1}^n w_{ij} |u(x_i) - u(x_j)|^2 - \sum_{j=1}^m (y_j - c) \cdot u(x_j) \right\},$$

where $c = \frac{1}{m} \sum_{i=1}^m y_i$.

Theorem

Assume G is connected. Then there exists a unique solution $u \in \ell_0^2(X)$ of (4), and furthermore, u satisfies the Poisson equation

$$\mathcal{L}u(x_i) = \sum_{j=1}^m (y_j - c) \delta_{ij}.$$

Poisson vs Laplace

The variational interpretation of **Poisson learning** is

$$\min_{u \in \ell_0^2(X)} \left\{ \sum_{i,j=1}^n w_{ij} |u(x_i) - u(x_j)|^2 - \sum_{j=1}^m (y_j - c) \cdot u(x_j) \right\}.$$

We compare this with the variational interpretation for **Laplace learning**, which is

$$\min_{u \in \ell^2(X)} \left\{ \sum_{i,j=1}^n w_{ij} |u(x_i) - u(x_j)|^2 : u(x_i) = y_i \text{ for } i = 1, \dots, m \right\}.$$

Takeaway: Instead of hard constraints, Poisson equations use soft constraints that are **affine** functions of the label values.

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Code Online

All code is on GitHub as part of the GraphLearning package:

<https://github.com/jwcalder/GraphLearning>

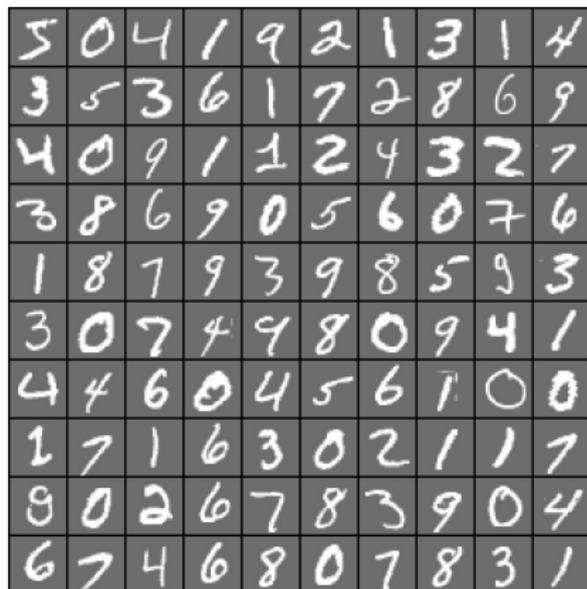
Easy to add volume constraints

Algorithm 2 Poisson MBO

```
1: Input:  $\mathbf{W}, \mathbf{F}, N_{\text{inner}}, N_{\text{outer}}, \mathbf{b}, \mu, T > 0$   
2: Output:  $\mathbf{U} \in \mathbb{R}^{n \times k}$   
3:  $\mathbf{U} \leftarrow \text{PoissonLearning}(\mathbf{W}, \mathbf{F}, \mathbf{b}, T)$   
4:  $dt \leftarrow 1 / \max_{1 \leq i \leq n} \mathbf{D}_{ii}$   
5: for  $i = 1$  to  $N_{\text{outer}}$  do  
6:   for  $j = 1$  to  $N_{\text{inner}}$  do  
7:      $\mathbf{U} \leftarrow \mathbf{U} - dt(\mathbf{L}\mathbf{U} - \mu\mathbf{B}^T)$   
8:   end for  
9:    $\mathbf{U} \leftarrow \text{VolumeConstrainedLabelProjection}(\mathbf{U}, \mathbf{b})$   
10: end for
```

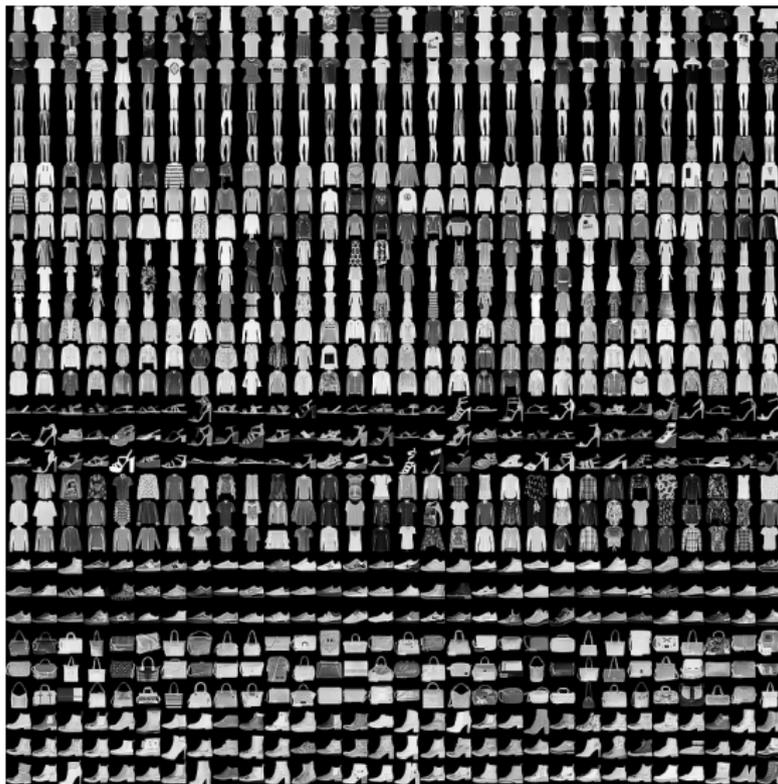
- ① The iterations in Steps 7-9 are **volume preserving**.

MNIST (70,000 28×28 pixel images of digits 0-9)



[Y. LeCun, L. Bottou, Y. Bengio, and P. Haffner. "Gradient-based learning applied to document recognition." Proceedings of the IEEE, 86(11):2278-2324, November 1998.]

FashionMNIST (70,000 28×28 images of fashion items)



[Xiao, Han, Kashif Rasul, and Roland Vollgraf. "Fashion-mnist: a novel image dataset for benchmarking machine learning algorithms." arXiv preprint arXiv:1708.07747 (2017).]

CIFAR-10

airplane



automobile



bird



cat



deer



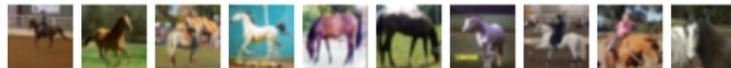
dog



frog



horse



ship



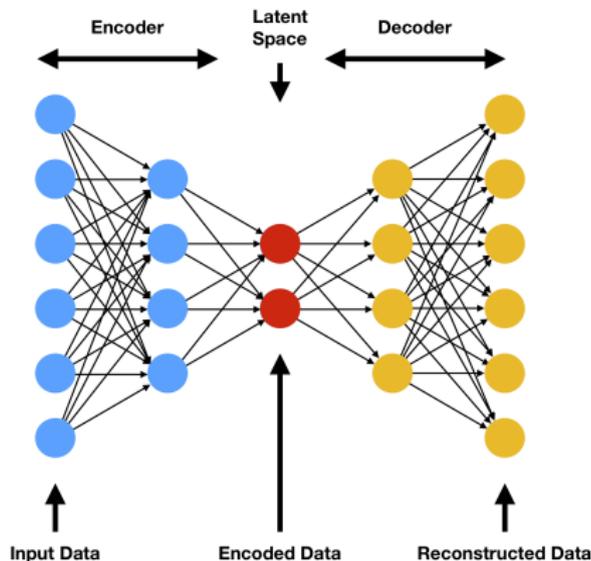
truck



[Krizhevsky, Alex, and Geoffrey Hinton. "Learning multiple layers of features from tiny images." (2009): 7.]

Autoencoders

For each dataset, we build the graph by training autoencoders.



www.compthree.com

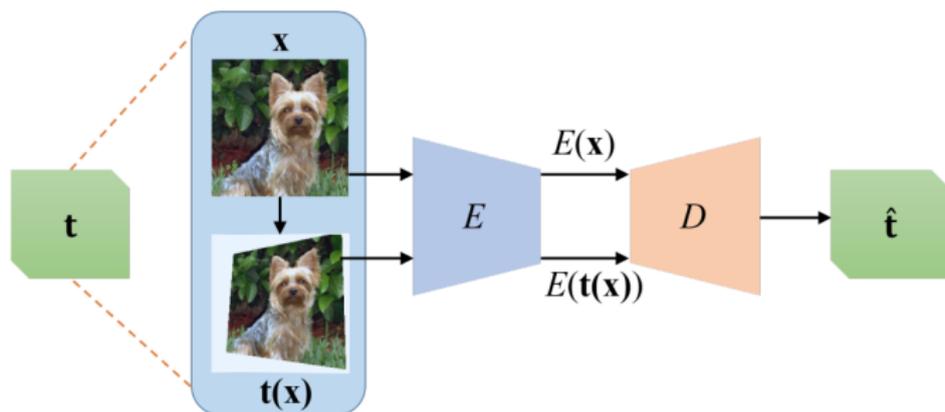
Autoencoders are “Nonlinear versions of PCA”

Building graphs from autoencoders

For MNIST and FashionMNIST, we use a 4-layer variational autoencoder with 20 (MNIST) and 30 (FashionMNIST) latent variables:

[Kingma and Welling. Auto-encoding variational Bayes. ICML 2014]

For CIFAR-10, we use the autoencoding framework from [Zhang et al. AutoEncoding Transformations (AET), CVPR 2019] with thousands of latent features.



Building graphs from autoencoders

After training autoencoders, we build a $k = 10$ nearest neighbor graphs in the latent space with Gaussian weights

$$w_{ij} = \exp\left(-\frac{4|x_i - x_j|^2}{d_k(x_i)^2}\right),$$

where $d_k(x_i)$ is the distance in the latent space between x_i and its k^{th} nearest neighbor. The weight matrix was then symmetrized by replacing W with $W + W^T$.

For CIFAR-10, the latent feature vectors were normalized to unit norm (equivalent to using an angular similarity).

Other algorithms

We compared against many algorithms:

- Graph nearest neighbor for a baseline
- Laplace/Label propagation: [Zhu et al., 2003]
- Lazy random walks: [Zhou et al., 2004]
- Mutli-class MBO: [Garcia-Cardona et al., 2014]
- Sparse Label Propagation: [Jung et al., 2016]
- Volume constrained MBO: [Jacobs et al., 2017]
- Weighted Nonlocal Laplacian (WNLL): [Shi et al., 2017]
- Centered kernel method: [Mai & Couillet, 2018]
- p -Laplace regularization: [Flores et al. 2019]

MNIST results

Table: Average (standard deviation) classification accuracy over 100 trials.

# Labels per class	1	2	3	4	5
Laplace/LP	16.1 (6.2)	28.2 (10.3)	42.0 (12.4)	57.8 (12.3)	69.5 (12.2)
Nearest Neighbor	55.8 (5.1)	65.0 (3.2)	68.9 (3.2)	72.1 (2.8)	74.1 (2.4)
Random Walk	66.4 (5.3)	76.2 (3.3)	80.0 (2.7)	82.8 (2.3)	84.5 (2.0)
MBO	19.4 (6.2)	29.3 (6.9)	40.2 (7.4)	50.7 (6.0)	59.2 (6.0)
VolumeMBO	89.9 (7.3)	95.6 (1.9)	96.2 (1.2)	96.6 (0.6)	96.7 (0.6)
WNLL	55.8 (15.2)	82.8 (7.6)	90.5 (3.3)	93.6 (1.5)	94.6 (1.1)
Centered Kernel	19.1 (1.9)	24.2 (2.3)	28.8 (3.4)	32.6 (4.1)	35.6 (4.6)
Sparse LP	14.0 (5.5)	14.0 (4.0)	14.5 (4.0)	18.0 (5.9)	16.2 (4.2)
p-Laplace	72.3 (9.1)	86.5 (3.9)	89.7 (1.6)	90.3 (1.6)	91.9 (1.0)
Poisson	90.2 (4.0)	93.6 (1.6)	94.5 (1.1)	94.9 (0.8)	95.3 (0.7)
PoissonMBO	96.5 (2.6)	97.2 (0.1)	97.2 (0.1)	97.2 (0.1)	97.2 (0.1)

FashionMNIST results

Table: Average (standard deviation) classification accuracy over 100 trials.

# Labels per class	1	2	3	4	5
Laplace/LP	18.4 (7.3)	32.5 (8.2)	44.0 (8.6)	52.2 (6.2)	57.9 (6.7)
Nearest Neighbor	44.5 (4.2)	50.8 (3.5)	54.6 (3.0)	56.6 (2.5)	58.3 (2.4)
Random Walk	49.0 (4.4)	55.6 (3.8)	59.4 (3.0)	61.6 (2.5)	63.4 (2.5)
MBO	15.7 (4.1)	20.1 (4.6)	25.7 (4.9)	30.7 (4.9)	34.8 (4.3)
VolumeMBO	54.7 (5.2)	61.7 (4.4)	66.1 (3.3)	68.5 (2.8)	70.1 (2.8)
WNLL	44.6 (7.1)	59.1 (4.7)	64.7 (3.5)	67.4 (3.3)	70.0 (2.8)
Centered Kernel	11.8 (0.4)	13.1 (0.7)	14.3 (0.8)	15.2 (0.9)	16.3 (1.1)
Sparse LP	14.1 (3.8)	16.5 (2.0)	13.7 (3.3)	13.8 (3.3)	16.1 (2.5)
p-Laplace	54.6 (4.0)	57.4 (3.8)	65.4 (2.8)	68.0 (2.9)	68.4 (0.5)
Poisson	60.8 (4.6)	66.1 (3.9)	69.6 (2.6)	71.2 (2.2)	72.4 (2.3)
PoissonMBO	62.0 (5.7)	67.2 (4.8)	70.4 (2.9)	72.1 (2.5)	73.1 (2.7)

Note: Compare to clustering result of **67.2%** [McConville et al., 2019]

CIFAR-10 results

Table: Average (standard deviation) classification accuracy over 100 trials.

# Labels per class	1	2	3	4	5
Laplace/LP	10.4 (1.3)	11.0 (2.1)	11.6 (2.7)	12.9 (3.9)	14.1 (5.0)
Nearest Neighbor	31.4 (4.2)	35.3 (3.9)	37.3 (2.8)	39.0 (2.6)	40.3 (2.3)
Random Walk	36.4 (4.9)	42.0 (4.4)	45.1 (3.3)	47.5 (2.9)	49.0 (2.6)
MBO	14.2 (4.1)	19.3 (5.2)	24.3 (5.6)	28.5 (5.6)	33.5 (5.7)
VolumeMBO	38.0 (7.2)	46.4 (7.2)	50.1 (5.7)	53.3 (4.4)	55.3 (3.8)
WNLL	16.6 (5.2)	26.2 (6.8)	33.2 (7.0)	39.0 (6.2)	44.0 (5.5)
Centered Kernel	15.4 (1.6)	16.9 (2.0)	18.8 (2.1)	19.9 (2.0)	21.7 (2.2)
Sparse LP	11.8 (2.4)	12.3 (2.4)	11.1 (3.3)	14.4 (3.5)	11.0 (2.9)
p-Laplace	26.0 (6.7)	35.0 (5.4)	42.1 (3.1)	48.1 (2.6)	49.7 (3.8)
Poisson	40.7 (5.5)	46.5 (5.1)	49.9 (3.4)	52.3 (3.1)	53.8 (2.6)
PoissonMBO	41.8 (6.5)	50.2 (6.0)	53.5 (4.4)	56.5 (3.5)	57.9 (3.2)

Note: Compare to clustering result of **41.2%** [Mukherjee et al., ClusterGAN, CVPR 2019].

FashionMNIST at moderate label rates

Table: Average (standard deviation) classification accuracy over 100 trials.

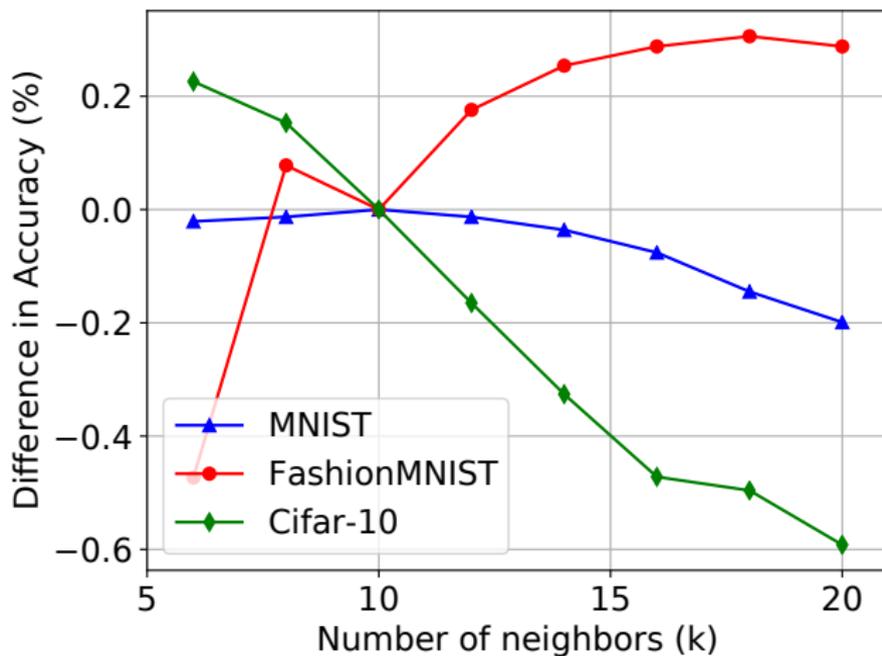
# Labels per class	10	20	40	80	160
Laplace/LP	70.6 (3.1)	76.5 (1.4)	79.2 (0.7)	80.9 (0.5)	82.3 (0.3)
Nearest Neighbor	62.9 (1.7)	66.9 (1.1)	70.0 (0.8)	72.5 (0.6)	74.7 (0.4)
Random Walk	68.2 (1.6)	72.0 (1.0)	75.0 (0.7)	77.4 (0.5)	79.5 (0.3)
MBO	52.7 (4.1)	67.3 (2.0)	75.7 (1.1)	79.6 (0.7)	81.6 (0.4)
VolumeMBO	74.4 (1.5)	77.4 (1.0)	79.5 (0.7)	81.0 (0.5)	82.1 (0.3)
WNLL	74.4 (1.6)	77.6 (1.1)	79.4 (0.6)	80.6 (0.4)	81.5 (0.3)
Centered Kernel	20.6 (1.5)	27.8 (2.3)	37.9 (2.6)	51.3 (3.3)	64.3 (2.6)
Sparse LP	15.2 (2.5)	15.9 (2.0)	14.5 (1.5)	13.8 (1.4)	51.9 (2.1)
p-Laplace	73.0 (0.9)	76.2 (0.8)	78.0 (0.3)	79.7 (0.5)	80.9 (0.3)
Poisson	75.2 (1.5)	77.3 (1.1)	78.8 (0.7)	79.9 (0.6)	80.7 (0.5)
PoissonMBO	76.1 (1.4)	78.2 (1.1)	79.5 (0.7)	80.7 (0.6)	81.6 (0.5)

Cifar-10 at moderate label rates

Table: Average (standard deviation) classification accuracy over 100 trials.

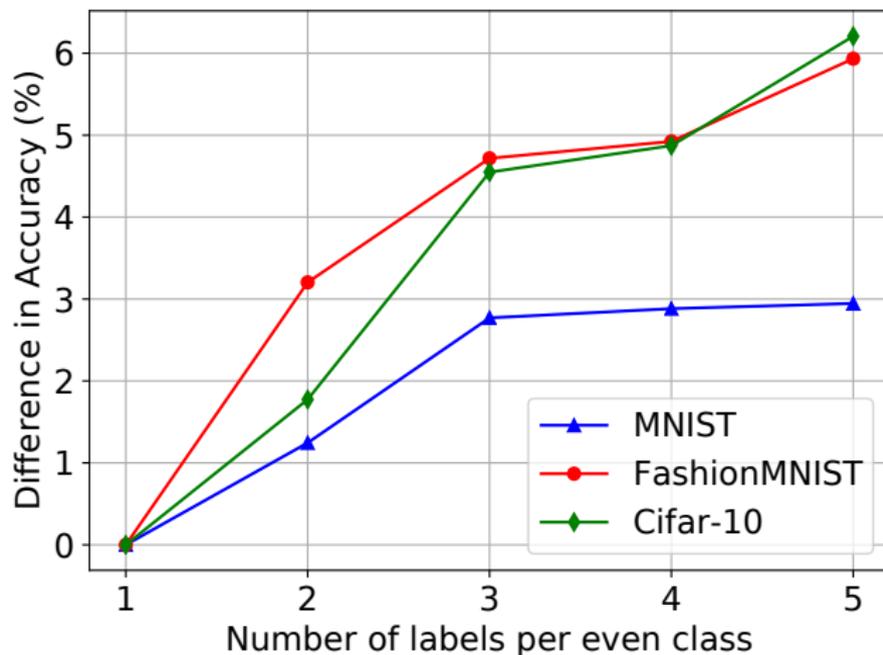
# Labels per class	10	20	40	80	160
Laplace/LP	21.8 (7.4)	38.6 (8.2)	54.8 (4.4)	62.7 (1.4)	66.6 (0.7)
Nearest Neighbor	43.3 (1.7)	46.7 (1.2)	49.9 (0.8)	52.9 (0.6)	55.5 (0.5)
Random Walk	53.9 (1.6)	57.9 (1.1)	61.7 (0.6)	65.4 (0.5)	68.0 (0.4)
MBO	46.0 (4.0)	56.7 (1.9)	62.4 (1.0)	65.5 (0.8)	68.2 (0.5)
VolumeMBO	59.2 (3.2)	61.8 (2.0)	63.6 (1.4)	64.5 (1.3)	65.8 (0.9)
WNLL	54.0 (2.8)	60.3 (1.6)	64.2 (0.7)	66.6 (0.6)	68.2 (0.4)
Centered Kernel	27.3 (2.1)	35.4 (1.8)	44.9 (1.8)	53.7 (1.9)	60.1 (1.5)
Sparse LP	15.6 (3.1)	17.4 (3.9)	20.0 (1.9)	21.7 (1.3)	15.0 (1.1)
p-Laplace	56.4 (1.8)	60.4 (1.2)	63.8 (0.6)	66.3 (0.6)	68.7 (0.3)
Poisson	58.3 (1.7)	61.5 (1.3)	63.8 (0.8)	65.6 (0.6)	67.3 (0.4)
PoissonMBO	61.8 (2.2)	64.5 (1.6)	66.9 (0.8)	68.7 (0.6)	70.3 (0.4)

Varying number of neighbors k



5 labels per class for all classes.

Unbalanced training data



Odd numbered classes got 1 label per class.

Outline

1 Introduction

- Graph-based semi-supervised learning
- Laplace learning/Label propagation
- Degeneracy in Laplace learning

2 Poisson learning

- Random walk perspective
- Variational interpretation

3 Experimental results

- Algorithmic details
- Datasets and algorithms
- Results

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