



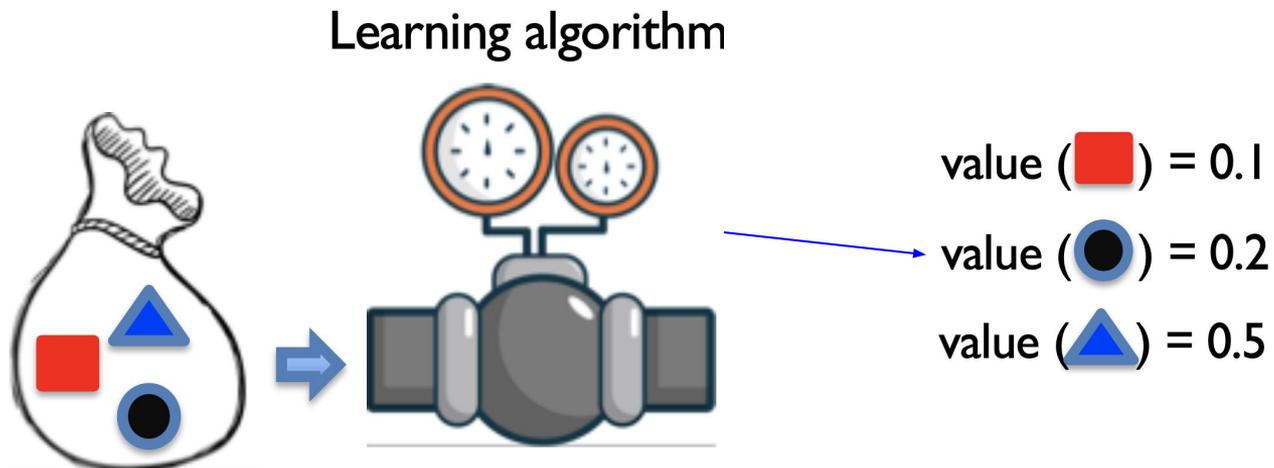
# Data Valuation using Reinforcement Learning

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**Google Cloud AI**

# Problem Definition

- What is data valuation?
  - How much does each data contribute to the trained model

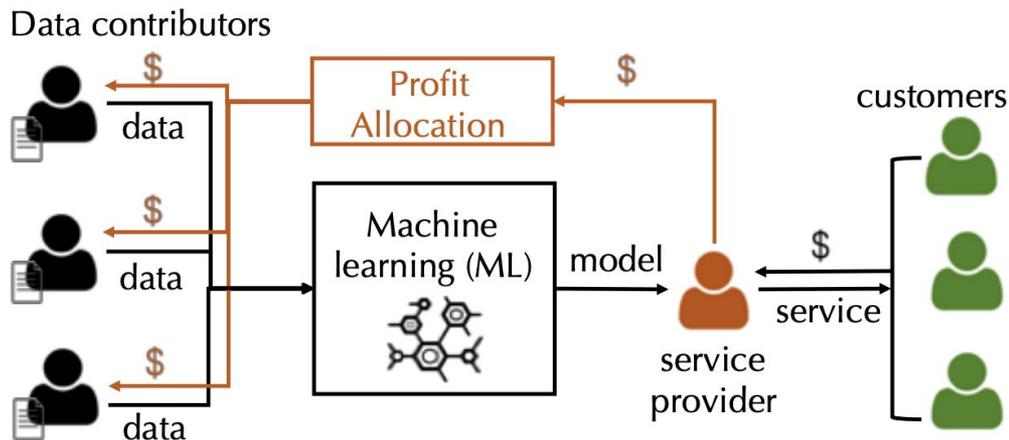


# Objective & Use-cases

- *Learn in reliable way*

- **Data valuation**

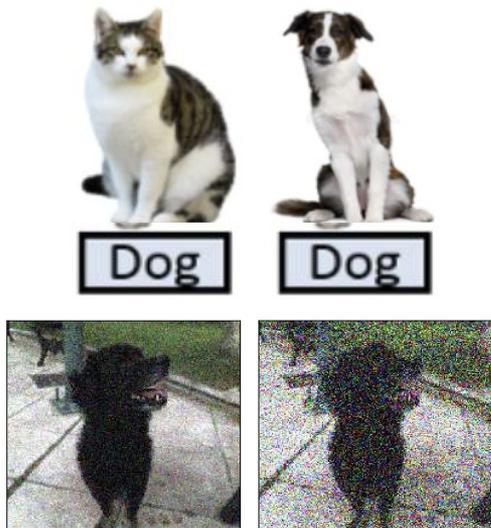
- Fair valuation for the labelers and data provider
- Insights about the dataset



# Objective & Use-cases

- *Learn in reliable way*

- **Corrupted sample discovery**



**High-value samples**



**Low-value samples**



# Objective & Use-cases

- *Learn in reliable way*

- **Robust learning with noisy (or cheaply-acquired) datasets**
  - Augmented learning



**Cheaply-acquired samples**

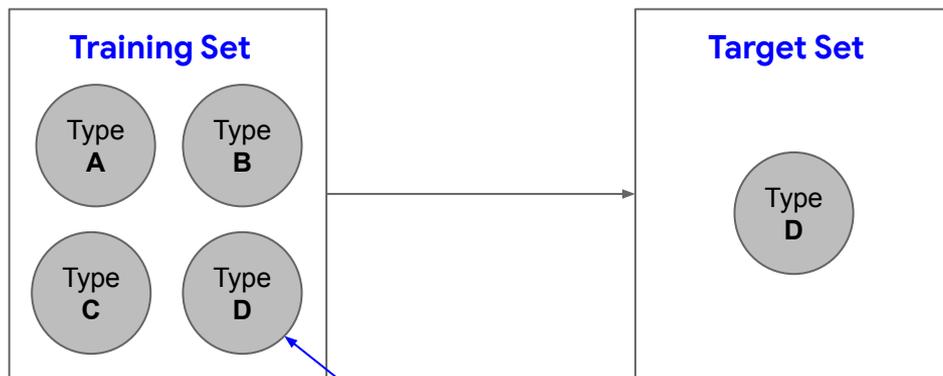
**High valued samples**

# Objective & Use-cases

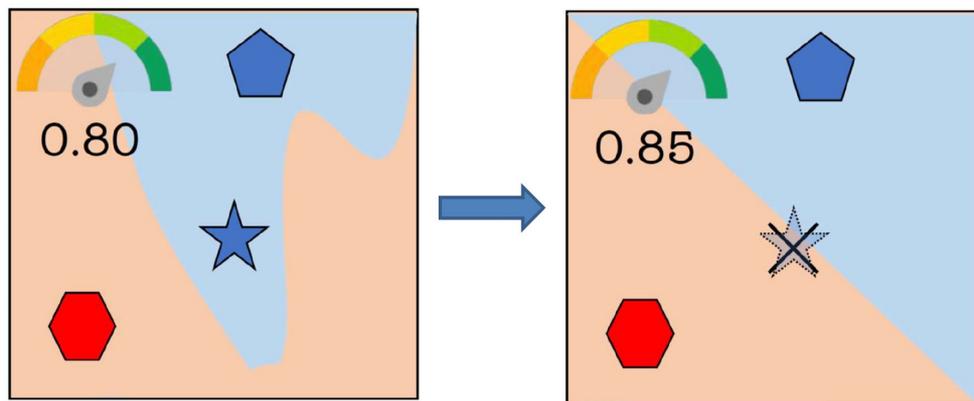
- *Learn in reliable way*

- **Domain adaptation**

- Assigns higher values on the samples from the target distribution



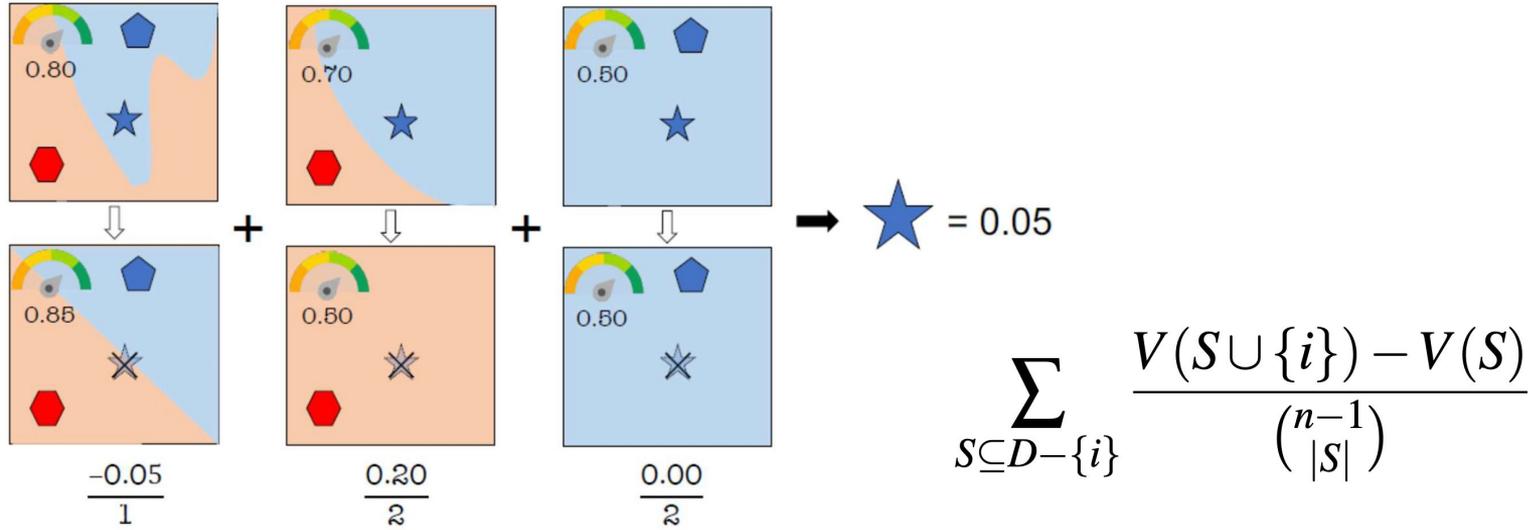
## Related works - Leave-one-out



$$V(D) - V(D - \{i\})$$

- Not reasonable when there are two similar training samples.

# Related works - Data Shapley

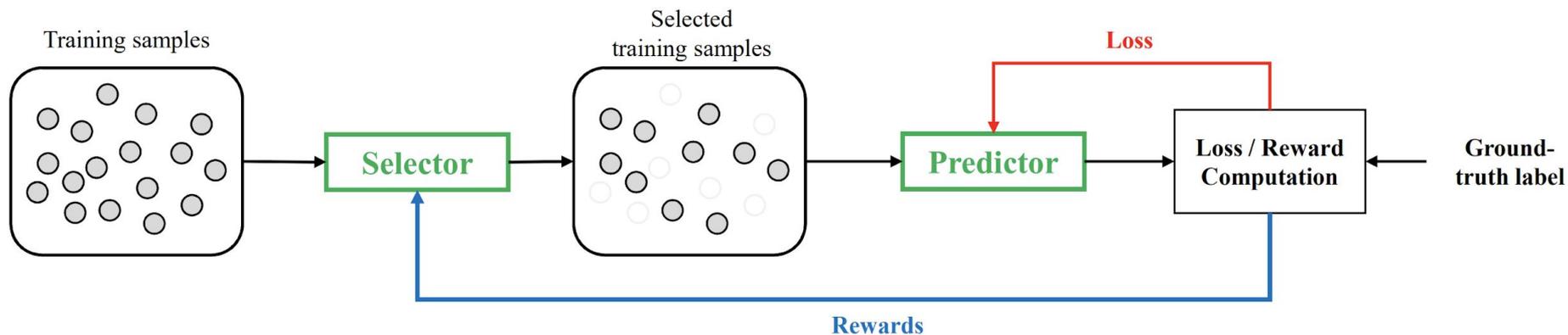


- **Computational complexity is exponential** with the number of samples.

# Challenges & Motivation

- **The search space is extremely large.**
  - Impossible to explore the entire space.
- **Training processes can be non-differentiable**
  - Selection operation (i.e. sampler block) is non-differentiable.
  - Performance metrics can be non-differentiable (accuracy, AUC).
  - End-to-end back-propagation may not be possible.
- **Reinforcement learning** is an efficient way to explore large search space and to handle non-differentiable process.

# High-level figure for DVRL



- Jointly train **selector** and **predictor** in an end-to-end way.

# Problem formulation

To minimize the validation loss

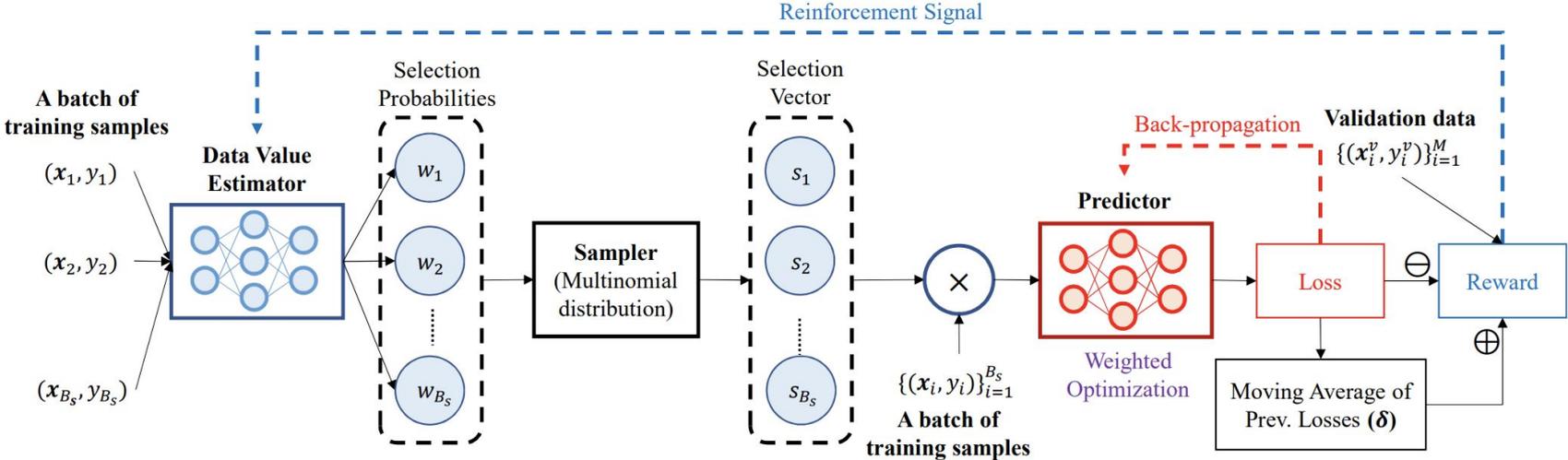
$$\begin{aligned} \min_{h_\phi} & \quad \mathbb{E}_{(\mathbf{x}^v, y^v) \sim \mathcal{P}^t} \left[ \mathcal{L}_h(f_\theta(\mathbf{x}^v), y^v) \right] \\ \text{s.t.} & \quad f_\theta = \arg \min_{\hat{f} \in \mathcal{F}} \mathbb{E}_{(\mathbf{x}, y) \sim \mathcal{P}} \left[ h_\phi(\mathbf{x}, y) \cdot \mathcal{L}_f(\hat{f}(\mathbf{x}), y) \right] \end{aligned}$$

- Components

- Training set:  $\mathcal{D} = \{(\mathbf{x}_i, y_i)\}_{i=1}^N \sim \mathcal{P}$
- Validation set:  $\mathcal{D}^v = \{(\mathbf{x}_k^v, y_k^v)\}_{k=1}^L \sim \mathcal{P}^t$
- Predictor model:  $f_\theta : \mathcal{X} \rightarrow \mathcal{Y}$
- Data valuation model:  $h_\phi : \mathcal{X} \cdot \mathcal{Y} \rightarrow [0, 1]$

Weighted optimization for predictor

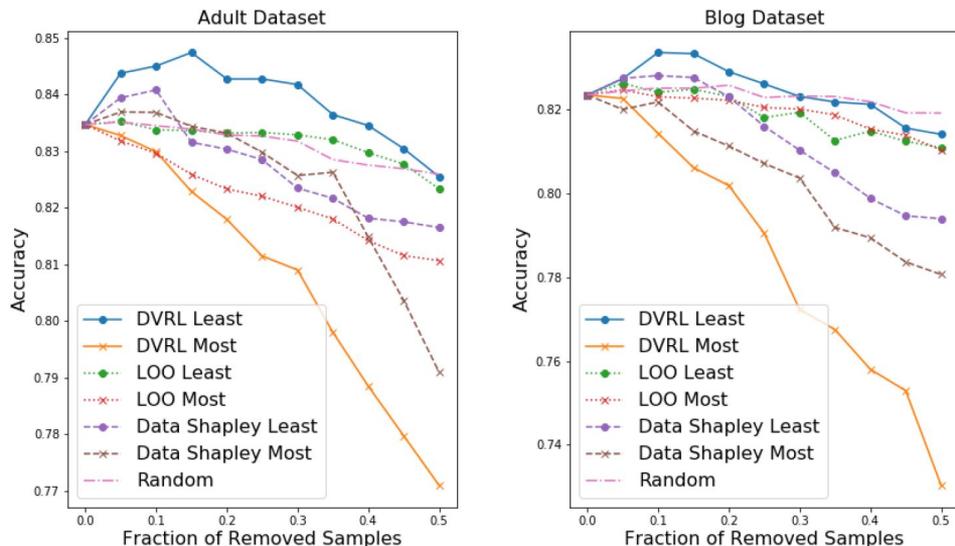
# Block diagram



## Experiments - How to **quantitatively** evaluate the data valuation?

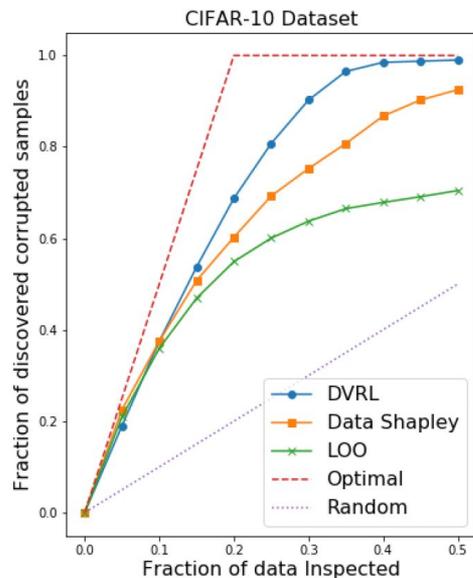
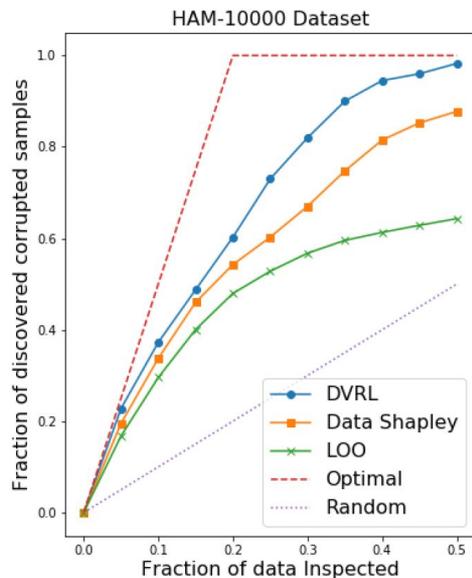
- Remove high / low valued samples
- Corrupted sample discovery
- Robust learning with noisy data
- Domain adaptation

# Results - Remove high / low valued samples



- **Standard supervised learning setting** (train, validation, test datasets come from the same distribution)
- Remove **high** valued samples: **Fastest** performance degradation
- Remove **low** valued samples: **Slowest** performance degradation

# Results - Corrupted sample discovery



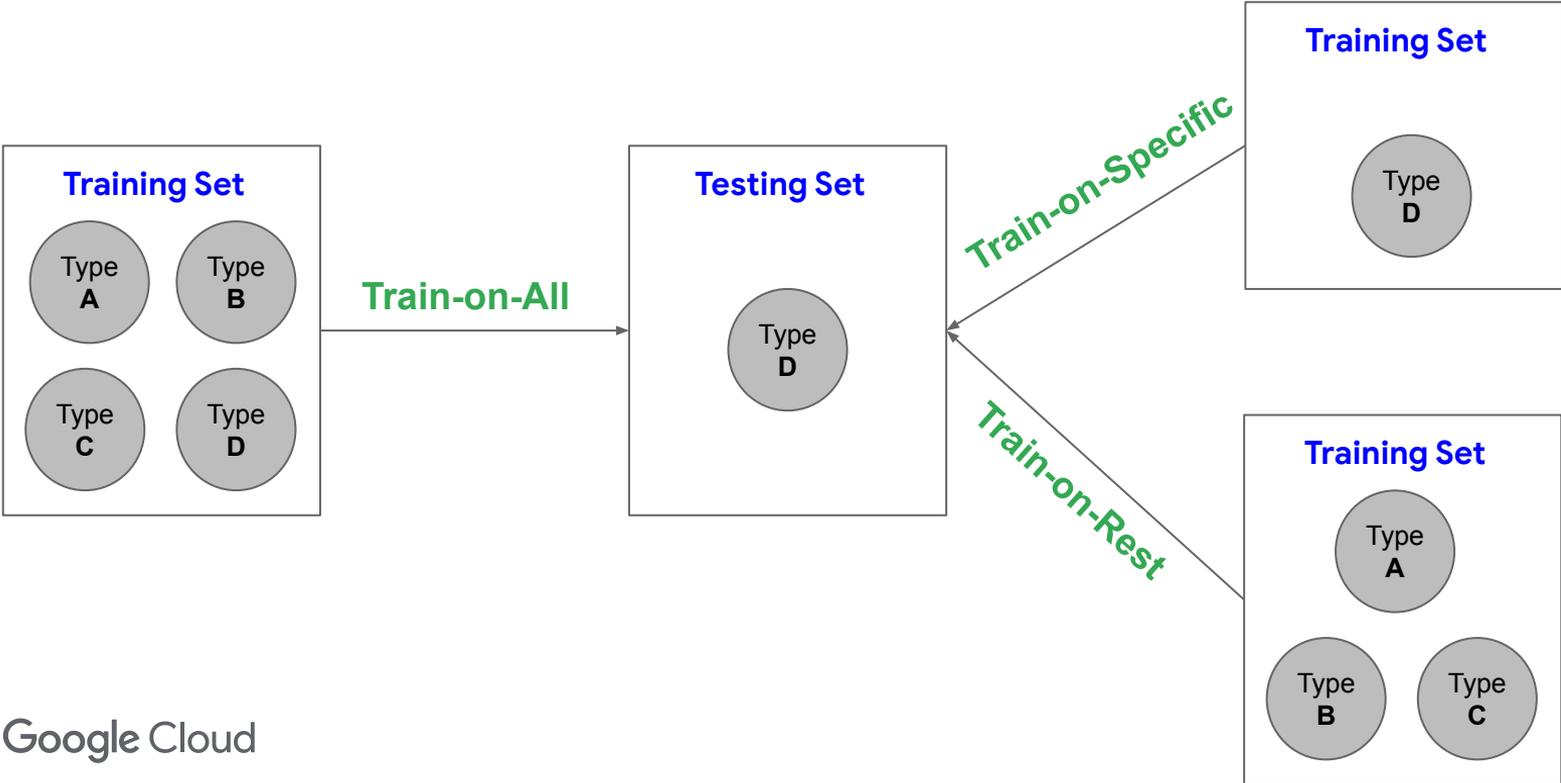
- Corrupted sample setting (20% of label noise)
- **Highest True Positive Rate (TPR)** for corrupted sample discovery

# Results - Robust learning with noisy labels (40%)

Noise (predictor model)	<b>Uniform</b> (WideResNet-28-10)		<b>Background</b> (ResNet-32)	
Datasets	CIFAR-10	CIFAR-100	CIFAR-10	CIFAR-100
Validation Set Only	46.64 ± 3.90	9.94 ± 0.82	15.90 ± 3.32	8.06 ± 0.76
Baseline	67.97 ± 0.62	50.66 ± 0.24	59.54 ± 2.16	37.82 ± 0.69
Baseline + Fine-tuning	78.66 ± 0.44	54.52 ± 0.40	82.82 ± 0.93	54.23 ± 1.75
MentorNet + Fine-tuning	78.00	59.00	-	-
Learning to Reweight	86.92 ± 0.19	61.34 ± 2.06	86.73 ± 0.48	59.30 ± 0.60
<b>DVRL</b>	<b>89.02 ± 0.27</b>	<b>66.56 ± 1.27</b>	<b>88.07 ± 0.35</b>	<b>60.77 ± 0.57</b>
Clean Only (60% Data)	94.08 ± 0.23	74.55 ± 0.53	90.66 ± 0.27	63.50 ± 0.33
Zero Noise	95.78 ± 0.21	78.32 ± 0.45	92.68 ± 0.22	68.12 ± 0.21

- Proves **scalability** of DVRL in terms of **complex models** (WideResNet-28-10 and ResNet-32) and **large datasets** (CIFAR)
- **State-of-the-art** robust learning performance

# Results - Domain adaptation on Retail dataset



# Results - Domain adaptation on Retail dataset

Predictor Model	Store	<i>Train on All</i>		<i>Train on Rest</i>		<i>Train on Specific</i>	
(Metric: RMSPE)	Type	<i>Baseline</i>	DVRL	<i>Baseline</i>	DVRL	<i>Baseline</i>	DVRL
XGBoost	A	0.1736	<b>0.1594</b>	0.2369	<b>0.2109</b>	0.1454	<b>0.1430</b>
	B	0.1996	<b>0.1422</b>	0.7716	<b>0.3607</b>	0.0880	<b>0.0824</b>
	C	0.1839	<b>0.1502</b>	0.2083	<b>0.1551</b>	0.1186	<b>0.1170</b>
	D	0.1504	<b>0.1441</b>	0.1922	<b>0.1535</b>	0.1349	<b>0.1221</b>
Neural Networks	A	0.1531	<b>0.1428</b>	0.3124	<b>0.2014</b>	0.1181	<b>0.1066</b>
	B	0.1529	<b>0.0979</b>	0.8072	<b>0.5461</b>	0.0683	<b>0.0682</b>
	C	0.1620	<b>0.1437</b>	0.2153	<b>0.1804</b>	0.0682	<b>0.0677</b>
	D	0.1459	<b>0.1295</b>	0.2625	<b>0.1624</b>	0.0759	<b>0.0708</b>

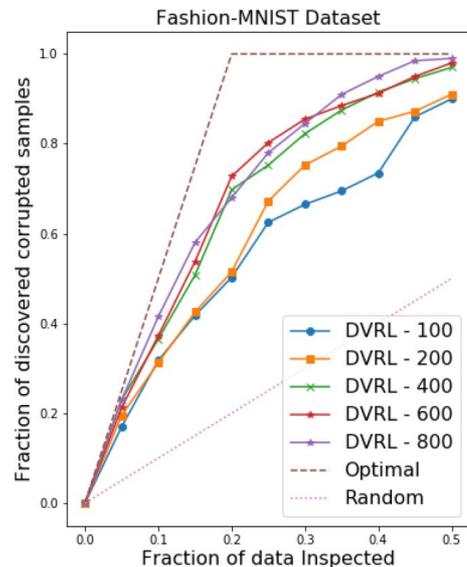
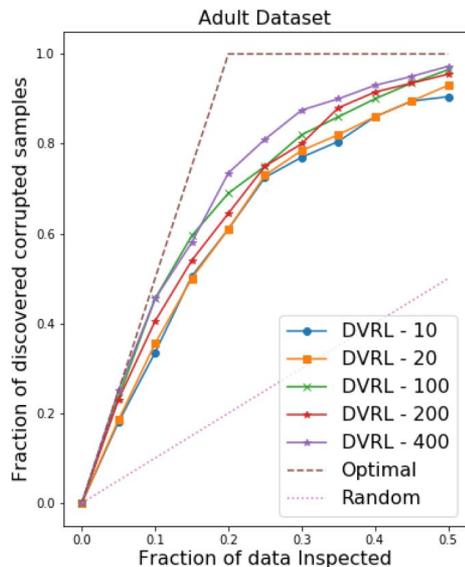
- **Significant gain** on Train on Rest setting (**largest domain mismatch**)
- **Reasonable gain** on Train on All setting (**most common setting**)
- **Marginal gain** on Train on Specific setting (**no domain mismatch**)

## Results - Domain adaptation in other domains

Source	Target	Task	<i>Baseline</i>	Data Shapley	<b>DVRL</b>
Google	HAM10000	Skin Lesion Classification	.296	.378	<b>.448</b>
MNIST	USPS	Digit Recognition	.308	.391	<b>.472</b>
Email	SMS	Spam Detection	.684	.864	<b>.903</b>

- **Main source of gain:**
  - DVRL **jointly optimizes** the data valuator and corresponding predictor model

# Discussion: How many validation samples are needed?



- **A small number of validation samples** are enough for DVRL training.
- Reasonable performances even with **10 validation samples** on Adult data.



# Codebase of DVRL

## **DVRL - Github:**

<https://github.com/google-research/google-research/tree/master/dvrl>

## **DVRL- AI-Hub:**

<https://aihub.cloud.google.com/u/0/p/products%2Fcb6b588c-1582-4868-a944-dc70ebe61a36>