

Mind the entropy bias in regularized OT :

Debiased Sinkhorn barycenters

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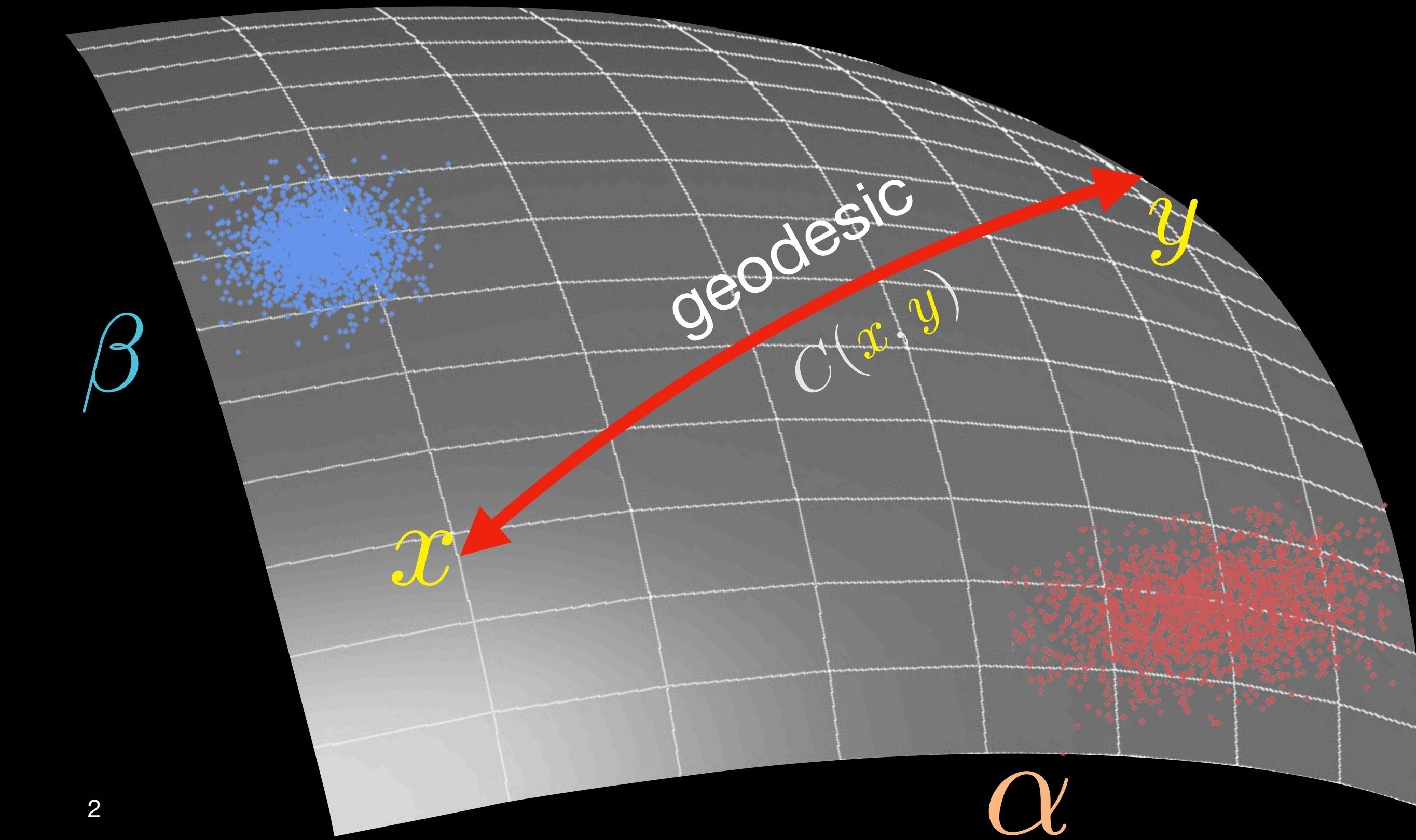
Inria Saclay

a metric space (\mathcal{X}, C)

$$C(x, y) d\pi(x, y)$$

“unit transport cost”

$$\alpha, \beta \in \mathcal{P}(\mathcal{X})$$

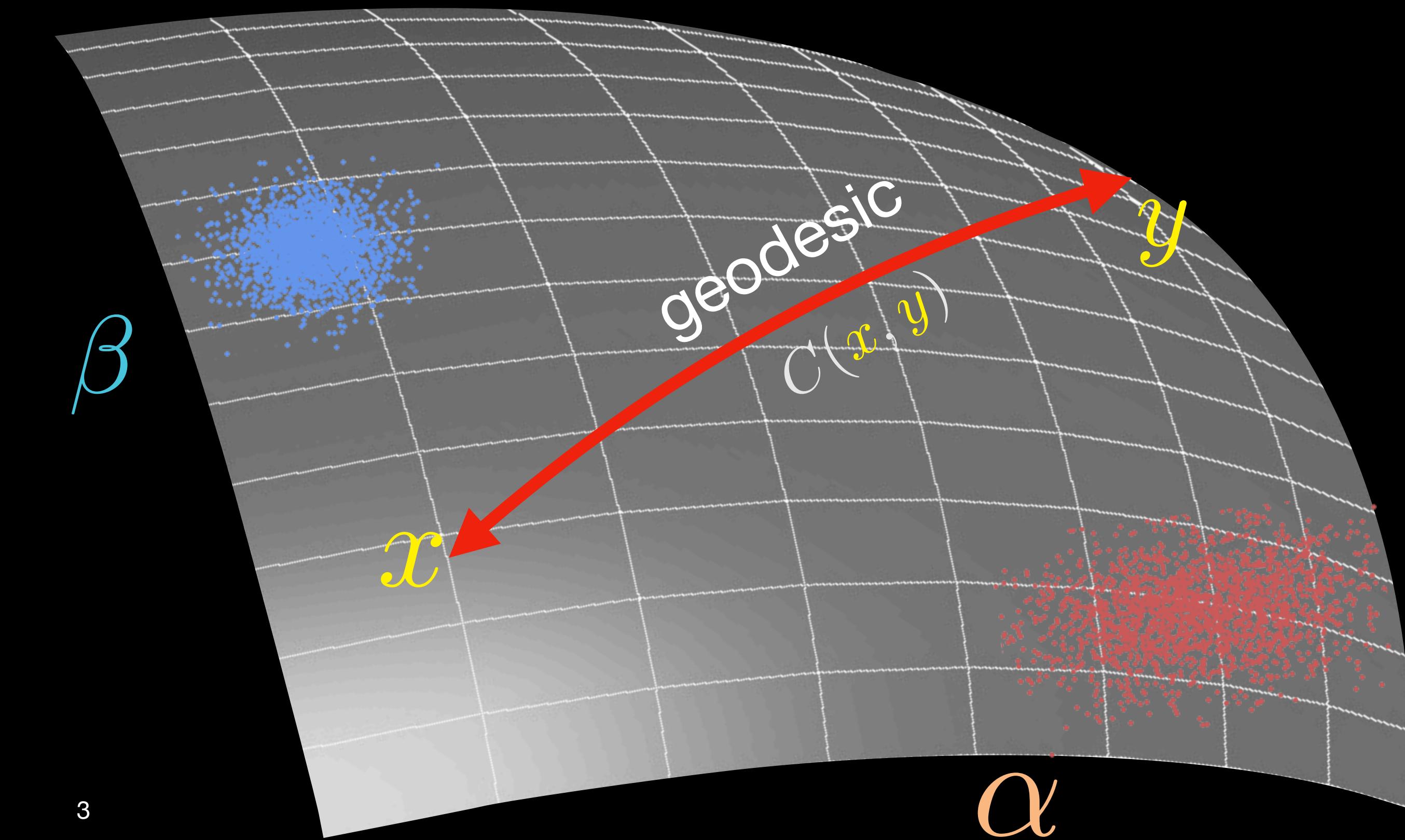


a metric space (\mathcal{X}, C)

$$\text{OT}(\alpha, \beta) \stackrel{\text{def}}{=} \min_{\substack{\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X}) \\ \pi_1 = \alpha, \pi_2 = \beta}} \int_{\mathcal{X} \times \mathcal{X}} C(x, y) d\pi(x, y)$$

“Wasserstein distance”
 Linear program
 $O(n^3)$

$$\alpha, \beta \in \mathcal{P}(\mathcal{X})$$



Entropy regularized OT

$$\text{OT}_\varepsilon(\alpha, \beta) \stackrel{\text{def}}{=} \min_{\substack{\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X}) \\ \pi_1 = \alpha, \pi_2 = \beta}} \int_{\mathcal{X} \times \mathcal{X}} C(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi \| m_1 \otimes m_2)$$

regularizer: relative entropy

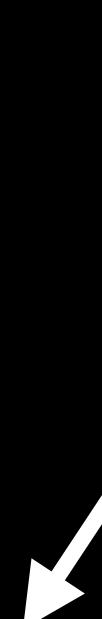
$m_1, m_2 \in$ reference measures in $\mathcal{P}(\mathcal{X})$

+ Computational cost: cubic \rightarrow quadratic

+ Breaks the curse of dimension

- Entropy bias

- Not a metric



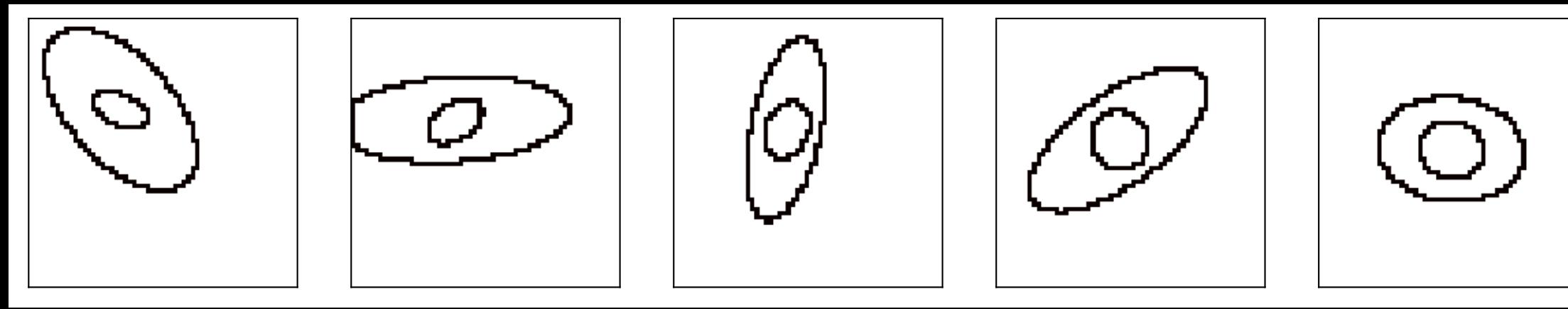
$$\arg \min_{\alpha} \text{OT}_\varepsilon(\alpha, \beta) \neq \beta$$

Entropy OT barycenters and bias

\mathcal{X} finite

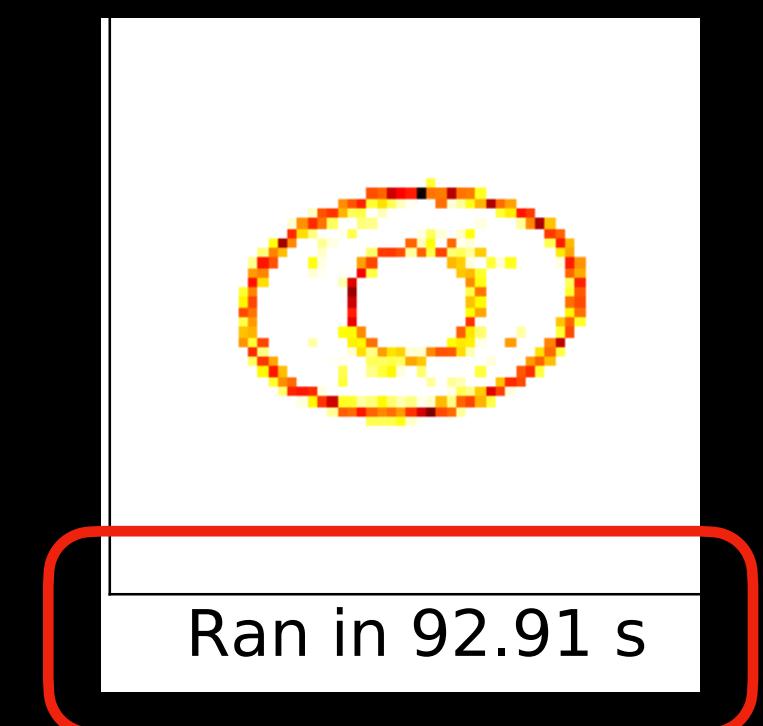
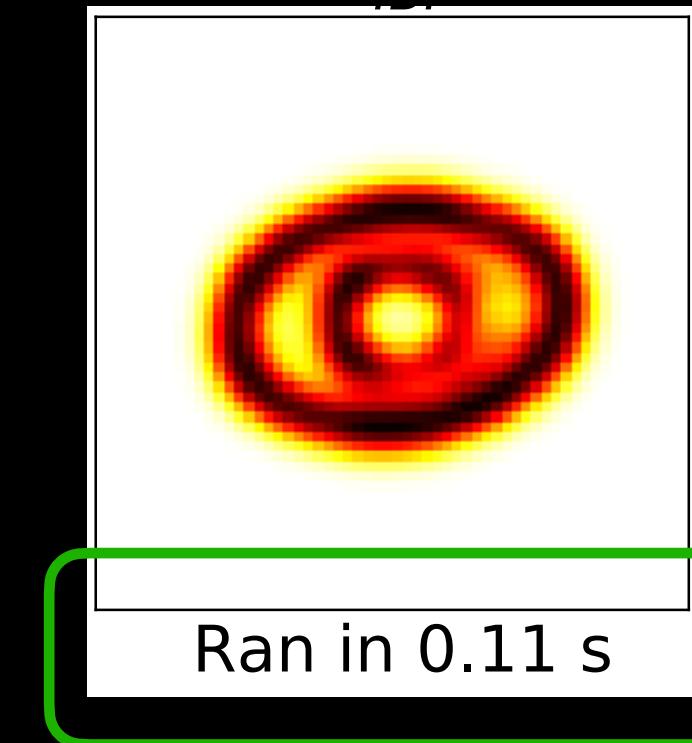
$m_1, m_2 = \mathcal{U}(\mathcal{X})$

$\alpha_1, \alpha_2 \dots$



$$\arg \min_{\alpha} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}(\alpha_k, \alpha)$$

$$\alpha \quad \varepsilon = 0.5 \quad \varepsilon = 0$$



Using Sinkhorn's algorithm

(Benamou et al, 15')

Entropy regularized OT

$$\text{OT}_\varepsilon(\alpha, \beta) \stackrel{\text{def}}{=} \min_{\substack{\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X}) \\ \pi_1 = \alpha, \pi_2 = \beta}} \int_{\mathcal{X} \times \mathcal{X}} C(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi | m_1 \otimes m_2)$$

regularizer: relative entropy

$m_1, m_2 \in$ reference measures in $\mathcal{P}(\mathcal{X})$

+ Computational cost: cubic \rightarrow quadratic

+ Breaks the curse of dimension

- Entropy bias

- Not a metric

(Feydy et al, 19): \mathcal{X} is compact $m_1 = \alpha$ $m_2 = \beta$

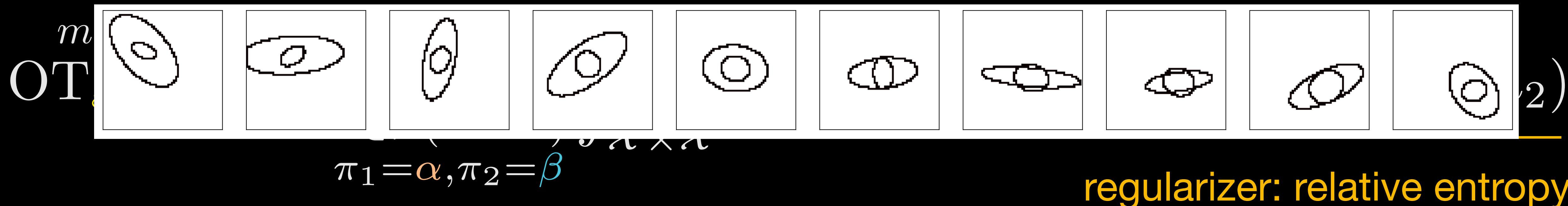
$$S_\varepsilon(\alpha, \beta) \stackrel{\text{def}}{=} \text{OT}_\varepsilon(\alpha, \beta) - \frac{1}{2}(\text{OT}_\varepsilon(\alpha, \alpha) + \text{OT}_\varepsilon(\beta, \beta))$$

~~- Entropy bias~~

+ $S_\varepsilon(\alpha, \beta) \geq 0;$

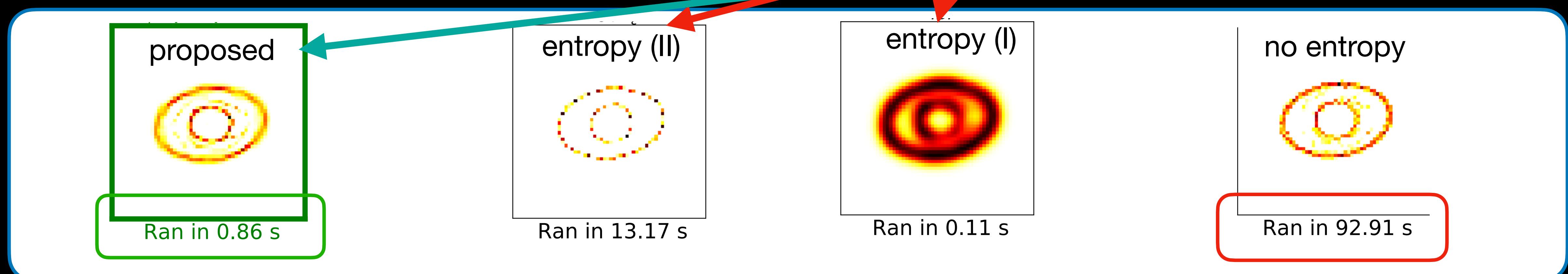
+ $S_\varepsilon(\alpha, \beta) = 0 \Rightarrow \alpha = \beta$

Entropy regularized OT



Contributions:

- 1) S_ε and OT_ε are convex and differentiable on non compact spaces ($\mathcal{X} = \mathbb{R}^d$)
- 2) Depending on m_1, m_2 the entropy bias can be blurring or shrinking
- 3) a Fast modified Sinkhorn algorithm to compute debiased barycenters



Entropy regularized OT

$$\text{OT}_{\varepsilon}^{m_1, m_2}(\alpha, \beta) \stackrel{\text{def}}{=} \frac{\min_{\substack{\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X}) \\ \pi_1 = \alpha, \pi_2 = \beta}} \int_{\mathcal{X} \times \mathcal{X}} C(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi | m_1 \otimes m_2)}{\text{regularizer: relative entropy}}$$

$m_1, m_2 \in$ reference measures in $\mathcal{P}(\mathcal{X})$

$$\text{KL}(\pi | r) \stackrel{\text{def}}{=} \int_{\mathcal{X} \times \mathcal{X}} \log \left(\frac{d\pi}{dr} \right) d\pi \quad \text{if } \pi \ll r \quad \text{else } +\infty$$

(0) Discrete case $\mathcal{X} = \{x_1, \dots, x_n\}$

$$\alpha, \beta \in \Delta_n \stackrel{\text{def}}{=} \{x \in \mathbb{R}_+^d \mid \sum_{i=1}^n x_i = 1\}$$

$$\text{OT}_{\varepsilon}^{\mathcal{U}}(\alpha, \beta) = \min_{\substack{\pi \in \mathbb{R}_+^{n \times n} \\ \pi \mathbf{1} = \alpha, \pi^\top \mathbf{1} = \beta}} \langle (C(x_i, x_j)_{ij}), \pi \rangle + \varepsilon \langle \pi, \log(\pi) - 1 \rangle$$

(Cuturi, Neurips 13')

(I) Lebesgue continuous case

$$\text{OT}_{\varepsilon}^{\mathcal{L}}(\alpha, \beta) \stackrel{\text{def}}{=} \min_{\substack{\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X}) \\ \pi_1 = \alpha, \pi_2 = \beta}} \int_{\mathcal{X} \times \mathcal{X}} C(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi \mid \mathcal{L} \otimes \mathcal{L})$$

(II) General case

$$\text{OT}_{\varepsilon}^{\otimes}(\alpha, \beta) \stackrel{\text{def}}{=} \min_{\substack{\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X}) \\ \pi_1 = \alpha, \pi_2 = \beta}} \int_{\mathcal{X} \times \mathcal{X}} C(x, y) d\pi(x, y) + \varepsilon \text{KL}(\pi \mid \alpha \otimes \beta)$$

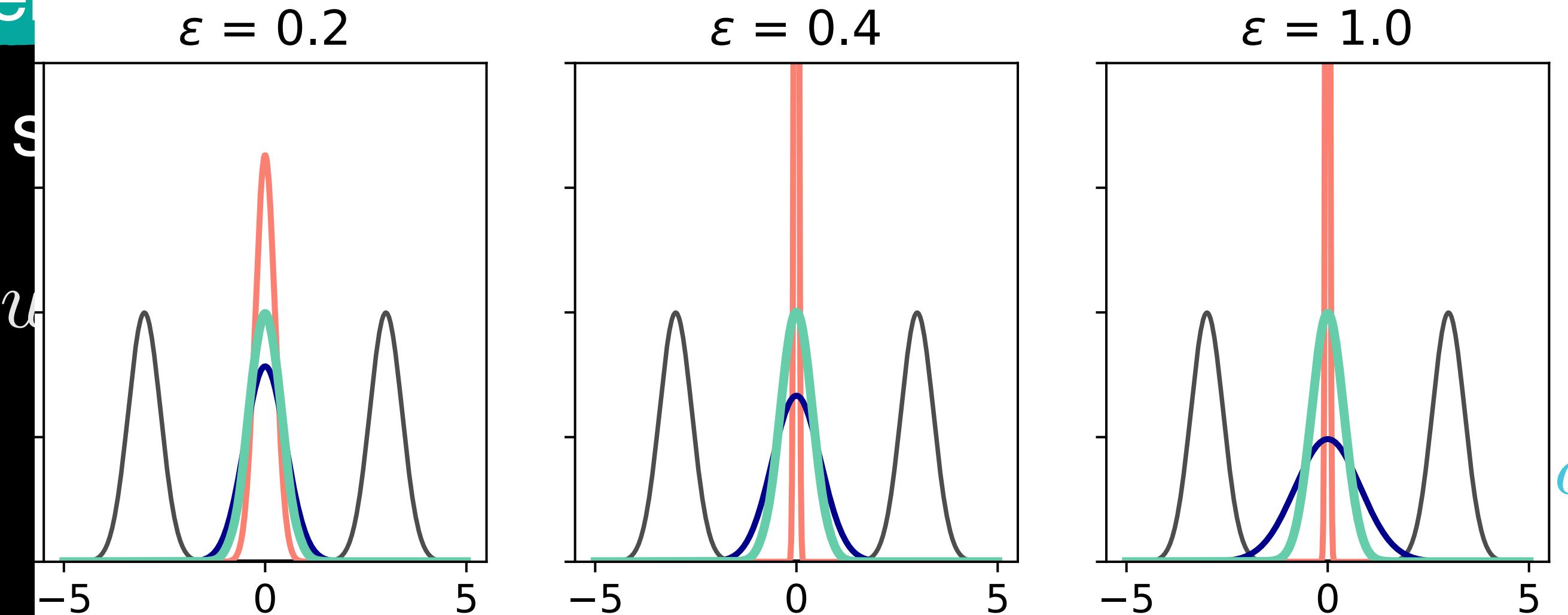
(Genevay 18', Feydy 19')

Quantifying the entropy bias

Theorem 1

Let \mathcal{G} the set

$$\bar{\mu} = \sum_{k=1}^K w_k \alpha_k$$



$$\mathcal{N}(\mu_k, \sigma^2)$$

α^L

α^X

α^{ideal}

smoothing

$$\alpha^L \stackrel{\text{def}}{=} \arg \min_{\beta \in \mathcal{G}} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}^L(\alpha_k, \beta) \sim \mathcal{N}\left(\bar{\mu}, \sigma^2 + \frac{\varepsilon^2}{2}\right)$$



(II) General case

$$\alpha^{\otimes} \stackrel{\text{def}}{=} \arg \min_{\beta \in \mathcal{G}} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}^{\otimes}(\alpha_k, \beta) \sim \mathcal{N}\left(\bar{\mu}, \left(\sigma^2 - \frac{\varepsilon^2}{2}\right)_+\right)$$

May collapse
to a dirac

Entropy shrinking

Quantifying the entropy bias

Theorem 1

Let \mathcal{G} the set of sub-Gaussian measures in \mathbb{R} and $\alpha_k \sim \mathcal{N}(\mu_k, \sigma^2)$

“Entropic OT is maximum likelihood deconvolution”

$$Y = X + \sigma^2 Z, \quad Z \sim \mathcal{N}(0, \text{Id})$$

$$P_X = \arg \min_P \text{OT}_{\sigma^2}^{\otimes} \left(P, \sum_{i=1}^n \frac{1}{n} \delta_{y_i} \right)$$

$$\alpha^{\mathcal{L}} \stackrel{\text{def}}{=} \arg \min_{\beta \in \mathcal{G}} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}^{\mathcal{L}} (\alpha_k, \beta) \sim \mathcal{N} \left(\bar{\mu}, \sigma^2 + \frac{\varepsilon^2}{2} \right)$$

(Rigollet & Weed, 18')

χ^{ideal}

(II) General case

$$\alpha^{\otimes} \stackrel{\text{def}}{=} \arg \min_{\beta \in \mathcal{G}} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}^{\otimes} (\alpha_k, \beta) \sim \mathcal{N} \left(\bar{\mu}, \left(\sigma^2 - \frac{\varepsilon^2}{2} \right)_+ \right)$$

Yet, useful

Entropy shrinking

Fixing the entropy bias

(Feydy et al, 19): \mathcal{X} is compact

$$S_\varepsilon(\alpha, \beta) \stackrel{\text{def}}{=} \text{OT}_\varepsilon^\otimes(\alpha, \beta) - \frac{1}{2}(\text{OT}_\varepsilon^\otimes(\alpha, \alpha) + \text{OT}_\varepsilon^\otimes(\beta, \beta))$$

~~- Entropy bias~~

+ $S_\varepsilon(\alpha, \beta) \geq 0;$

+ $S_\varepsilon(\alpha, \beta) = 0 \Rightarrow \alpha = \beta$

Theorem

Why ?

Let \mathcal{G} the set of sub-Gaussian measures in \mathbb{R} and $\alpha_k \sim \mathcal{N}(\mu_k, \sigma^2)$

$$\bar{\mu} = \sum_{k=1}^K w_k \mu_k \quad C(x, y) = (x - y)^2 \quad \text{then:}$$

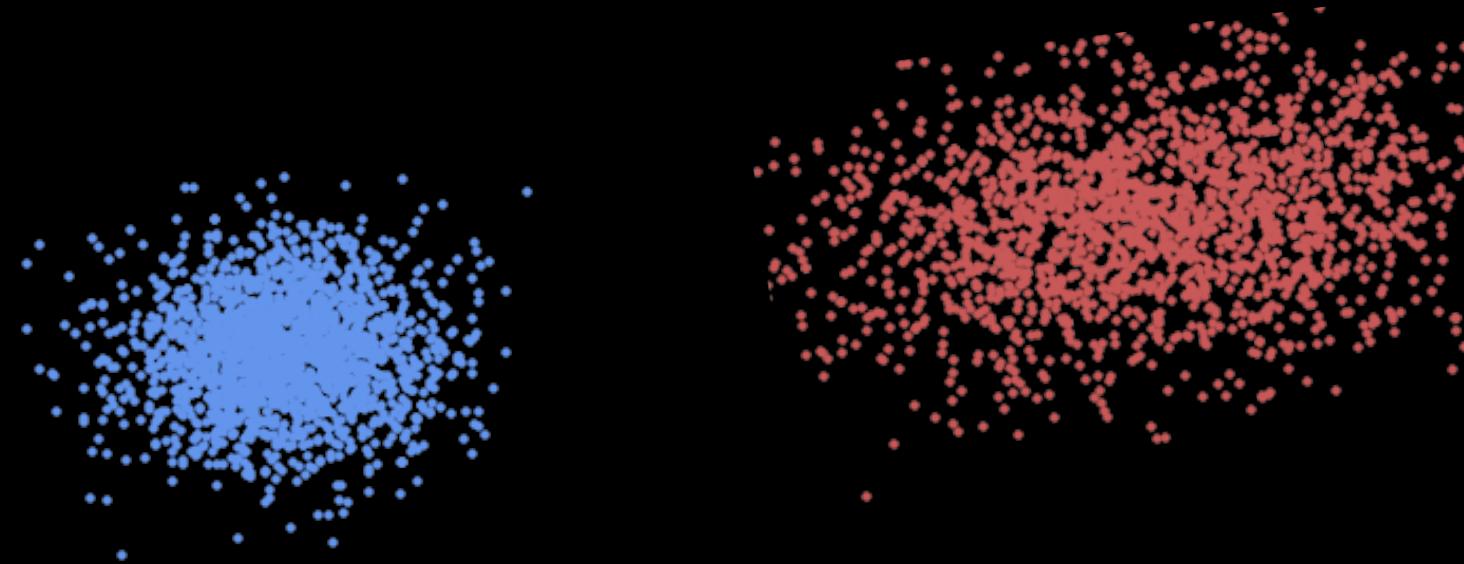
$$\alpha^S \stackrel{\text{def}}{=} \arg \min_{\beta \in \mathcal{G}} \sum_{k=1}^K w_k S_\varepsilon(\alpha_k, \beta) \sim \mathcal{N}(\bar{\mu}, \sigma^2)$$

To prove the convexity and differentiability of S_ε and OT_ε
and characterize the barycentric optimality

Barycentric Algorithms: two different views

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Lagrangian (Free supports)



*Distributions represented
by point clouds (positions, weights)*

- + scalable for sparse distributions in high dimensions
- Optimization over weights and **positions**: requires several Sinkhorn loops

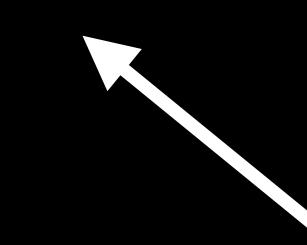
Eulerian (Fixed supports)



*Distributions represented
by histograms on a fixed grid*

- + Parallelizable on regular grids (e.g. images)
- Not scalable memory footprint

Done by (Luise, 19')



Sinkhorn algorithm and IBP

$$\alpha^{\mathcal{U}} \stackrel{\text{def}}{=} \arg \min_{\beta \in \Delta_n} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}^{\mathcal{U}}(\alpha_k, \beta) \quad \text{can be written as a KL projection:}$$

$$\begin{aligned} & \min_{\pi_1, \dots, \pi_K \in \mathbb{R}_+^{n \times n}} \sum_{k=1}^K w_k \text{KL}(\pi_k \mid e^{-\frac{(C_{ij})}{\varepsilon}}) \\ & \pi_k^\top \mathbf{1} = \alpha_k \\ & \pi_1^\top \mathbf{1} = \dots = \pi_K^\top \mathbf{1} \end{aligned} \quad \begin{aligned} & \text{Solved using} \\ & \text{“Iterative Bregman Projections” (IBP)} \\ & \text{a.k.a. generalized Sinkhorn} \end{aligned}$$

Not possible with the product measure as reference :(

$$\alpha^{\otimes} \stackrel{\text{def}}{=} \arg \min_{\beta \in \Delta_n} \sum_{k=1}^K w_k \text{OT}_{\varepsilon}^{\otimes}(\alpha_k, \beta)$$

What about

S_{ε} ?

Debiased Sinkhorn algorithm and IBP

$\pi \in \mathcal{P}(\mathcal{X} \times \mathcal{X})$, $\pi_1 = \alpha$ and $\pi_2 = \beta$ then:

$$\text{KL}(\pi|m_1 \otimes m_2) = \text{KL}(\pi|\alpha \otimes \beta) + \text{KL}(\alpha|m_1) + \text{KL}(\beta|m_2)$$

(Di marino, 19')

Then S_ε is independent of the reference measure:

If discrete: $S_\varepsilon^{\mathcal{U}}(\alpha, \beta) = S_\varepsilon^{\otimes}(\alpha, \beta)$

If Lebesgue-continuous: $S_\varepsilon^{\mathcal{L}}(\alpha, \beta) = S_\varepsilon^{\otimes}(\alpha, \beta)$

Debiased Sinkhorn algorithm and IBP

Using $S_{\varepsilon}^{\mathcal{U}}(\alpha, \beta) = S_{\varepsilon}^{\otimes}(\alpha, \beta)$

$\alpha^S \stackrel{\text{def}}{=} \arg \min_{\beta \in \Delta_n} \sum_{k=1}^K w_k S_{\varepsilon}^{\mathcal{U}}(\alpha_k, \beta)$ equivalent to:

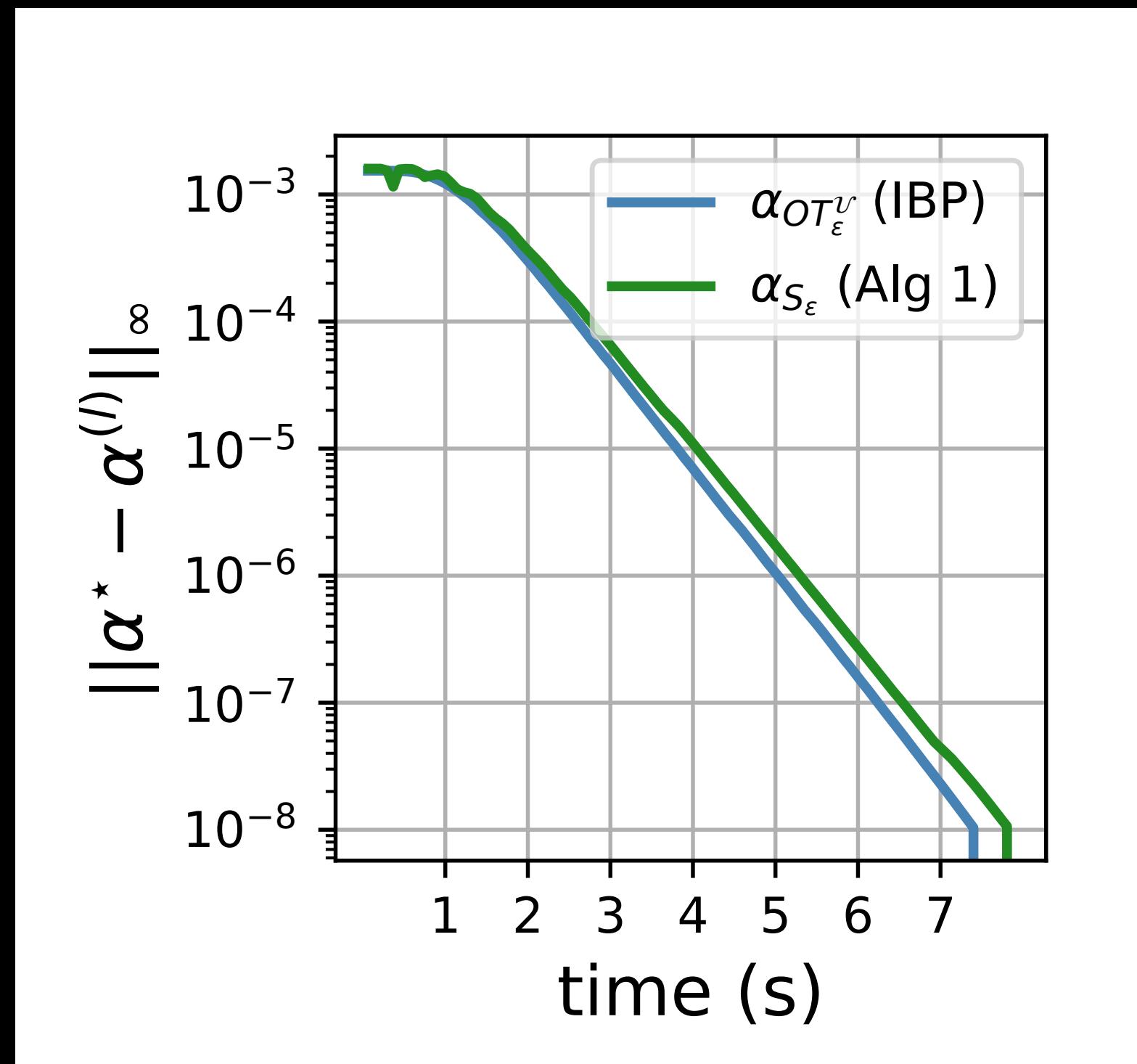
$$\min_{\pi_1, \dots, \pi_K \in \mathbb{R}_+^{n \times n}} \sum_{k=1}^K w_k \text{KL}(\pi_k | e^{-\frac{(C_{ij})}{\varepsilon}} d_j) + \frac{\varepsilon}{2} \langle d - \mathbf{1}, e^{-\frac{(C_{ij})}{\varepsilon}} (d - \mathbf{1}) \rangle$$

$\pi_k \mathbf{1} = \alpha_k$
 $\pi_1^\top \mathbf{1} = \dots = \pi_K^\top \mathbf{1}$
 $d \in \mathbb{R}_+^n$

Alternating block minimization:

- 1) IBP loop
- 2) Symmetric Sinkhorn

Debiased Sinkhorn algorithm and IBP



Algorithm 1 Debiased Sinkhorn Barycenter

Input: $\alpha_1, \dots, \alpha_K, \mathbf{K} = e^{-\frac{\mathbf{C}}{\varepsilon}}$

Output: α_{S_ε}

Initialize all scalings $(b_k), d$ to $\mathbb{1}$,

repeat

for $k = 1$ **to** K **do**

$$a_k \leftarrow \left(\frac{\alpha_k}{\mathbf{K} b_k} \right)$$

end for

$$\alpha \leftarrow d \odot \prod_{k=1}^K (\mathbf{K}^\top a_k)^{w_k}$$

for $k = 1$ **to** K **do**

$$b_k \leftarrow \left(\frac{\alpha}{\mathbf{K}^\top a_k} \right)$$

end for

$$d \leftarrow \sqrt{d \odot \left(\frac{\alpha}{\mathbf{K} d} \right)}$$

until convergence

Take home message

- The entropic barycenter of univariate Gaussians is Gaussian
- The entropic bias can be smoothing or shrinking
- The debiased barycenter can be computed on a GPU-friendly modified Sinkhorn algorithm