

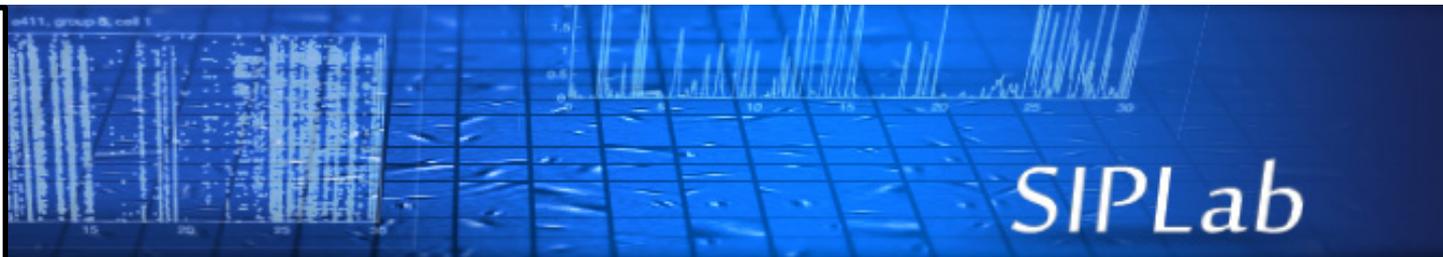
Active Embedding Search via Noisy Paired Comparisons

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Sensory Information Processing Lab

Estimating preferences in similarity embedding



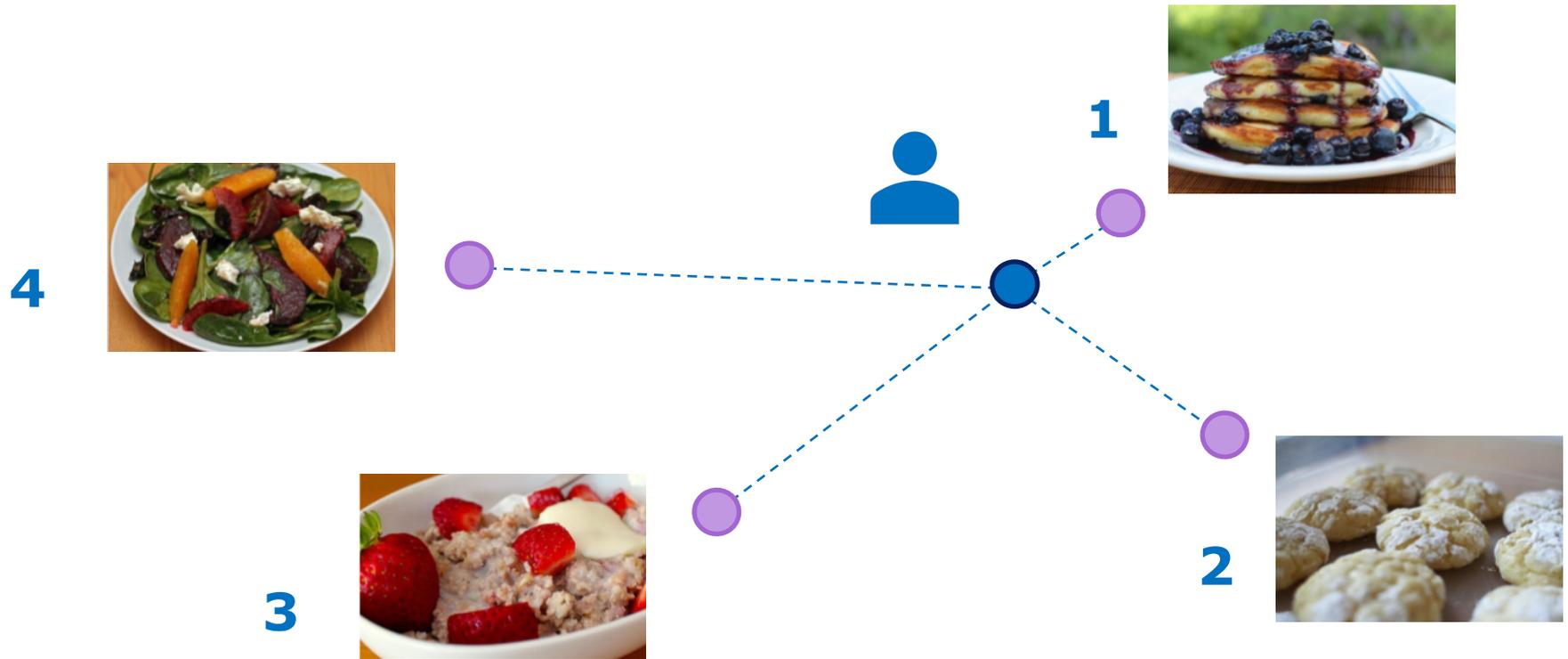
Estimating preferences in similarity embedding



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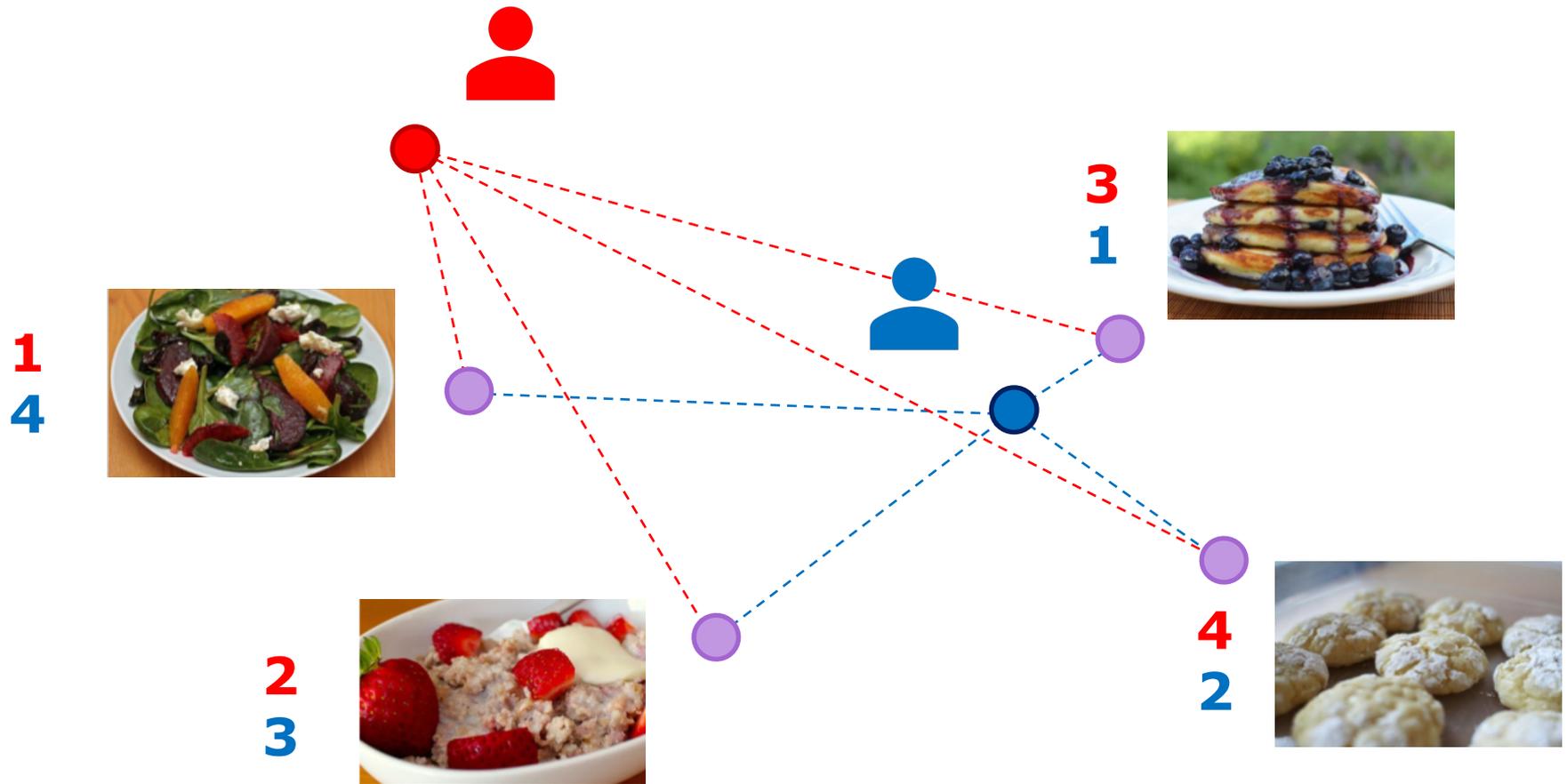


Estimating preferences in similarity embedding



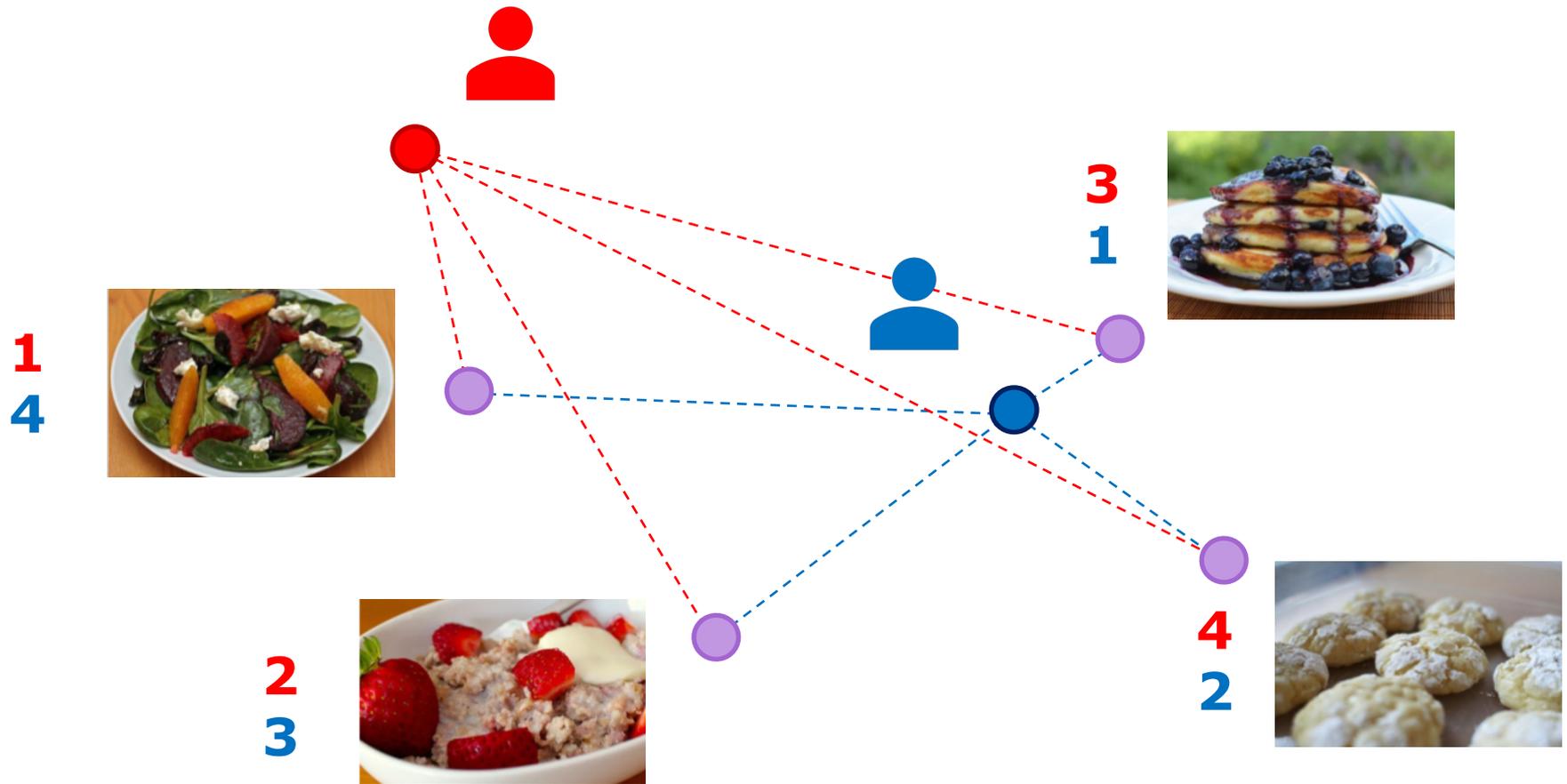
- Item preferences ranked by distance to user

Estimating preferences in similarity embedding



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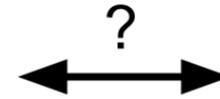


- Item preferences ranked by distance to user
- Continuous user point: hypothetical *ideal* item (not necessarily in dataset)

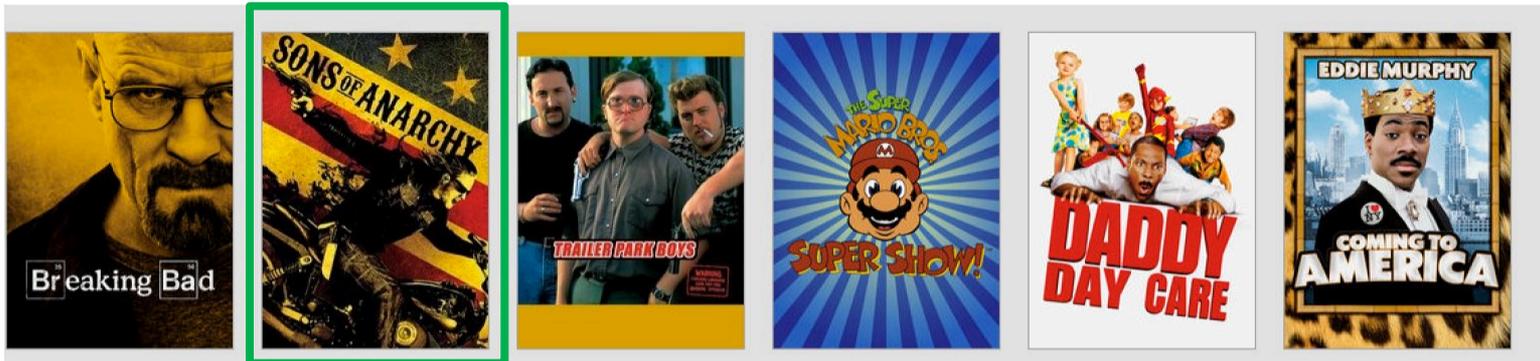
Method of paired comparisons

Learn preferences via *method of paired comparisons* (David, 1963)

"Which of these two foods do you prefer to eat?"



- Direct comparisons may be explicitly solicited
- Comparisons are *implicitly* solicited everywhere

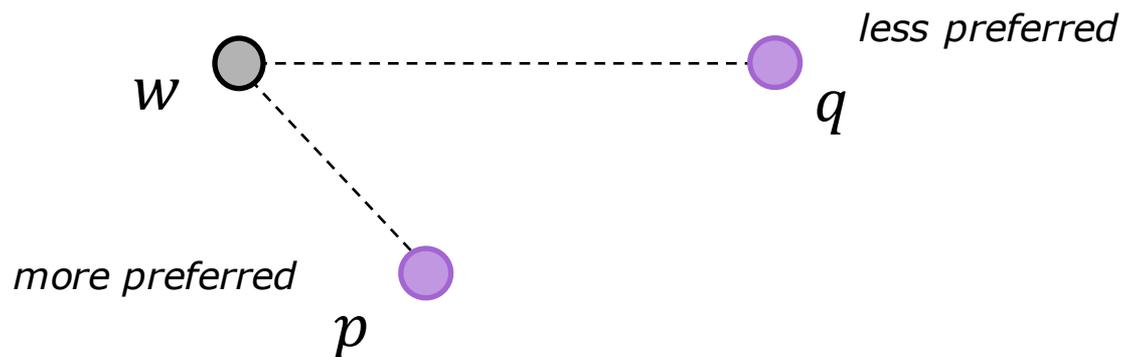


- In practice, responses are noisy, inconsistent

Ideal point model

- *Pairwise search*: estimate user vector $w \in \mathbb{R}^d$ based on paired comparisons between items
- *Ideal point model*: continuous point w encodes ideal item that is preferred over all other items (Coombs, 1950)

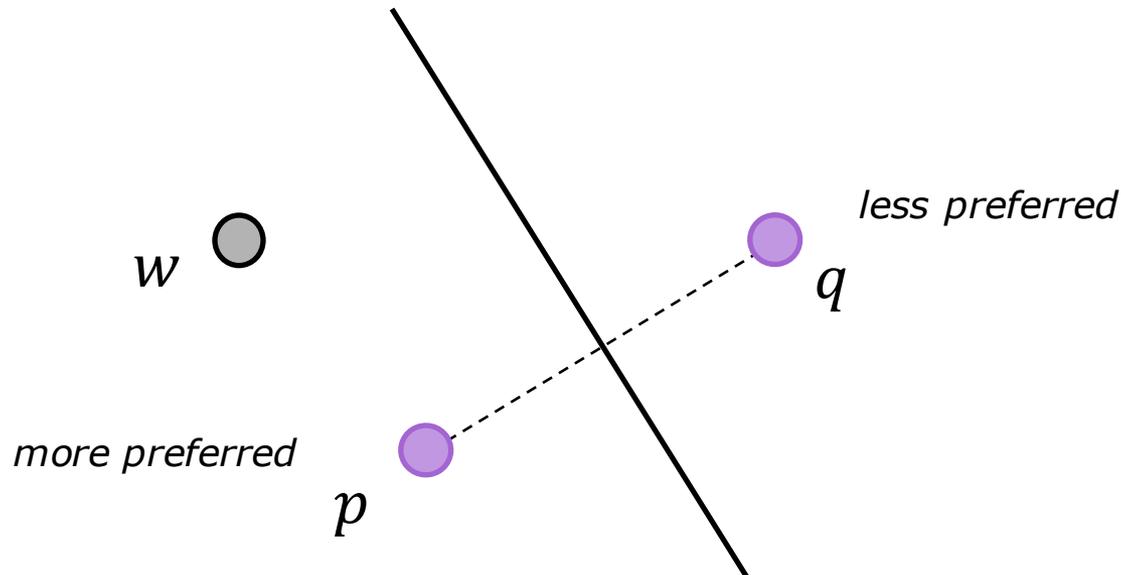
Paired comparison (p, q) : user at w prefers item p over item q if and only if $\|w - p\| < \|w - q\|$



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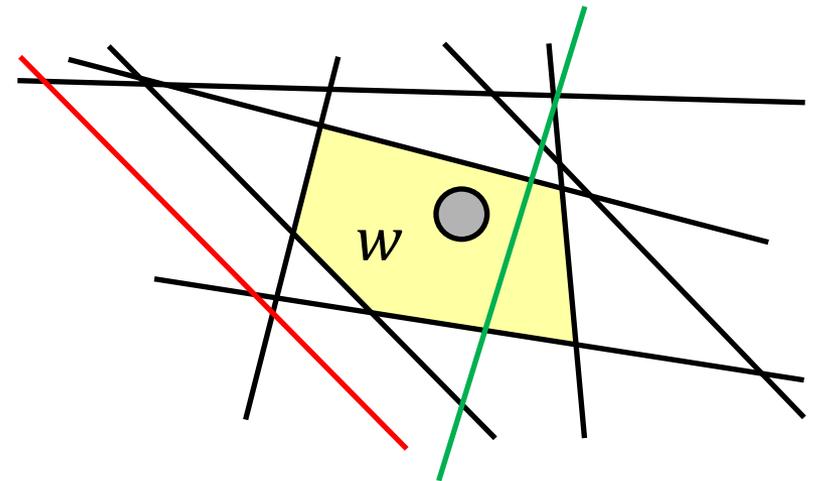
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Prior work

How can paired comparisons (hyperplanes) be selected?

- Query as few pairs as possible
- Linear models (e.g., learning to rank, latent factors) unsuitable for nonlinear ideal point model (Wu et al., 2017; Qian et al., 2015)
- Feasible region tracking
 - Query pairs adaptively
 - Add slack variables to feasible region (Massimino & Davenport, 2018)
 - Repeat comparisons, take majority vote (Jamieson & Nowak, 2011)
 - Previous methods **do not** incorporate noise into pair selection

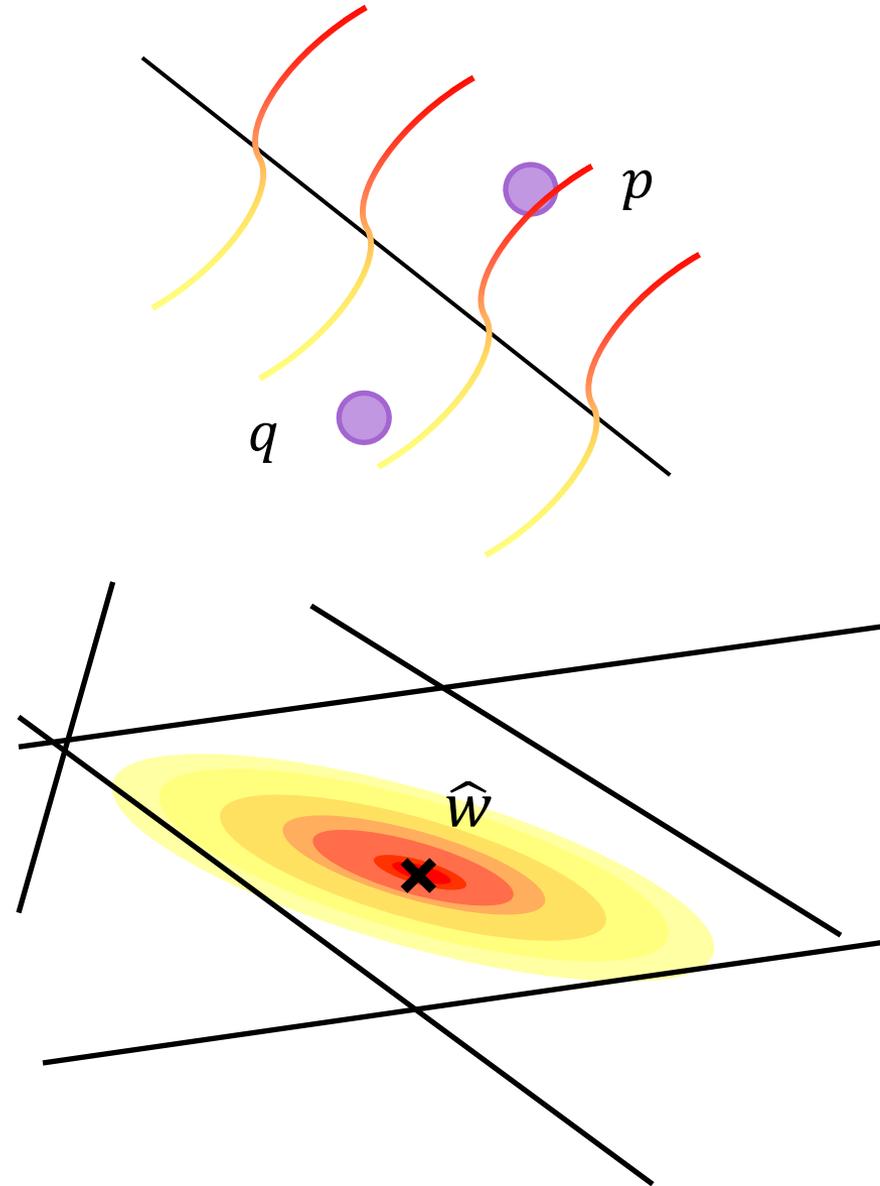


Modeling response noise

- $a_{pq} \in \mathbb{R}^d, b_{pq} \in \mathbb{R}$: weights, threshold of hyperplane bisecting p, q
- Model noise with logistic response probability

$$P(p < q) = \frac{1}{1 + e^{-k_{pq}(a_{pq}^T w - b_{pq})}}$$

- k_{pq} : noise constant, represents signal-to-noise ratio
- User estimated as posterior mean (MMSE estimator)



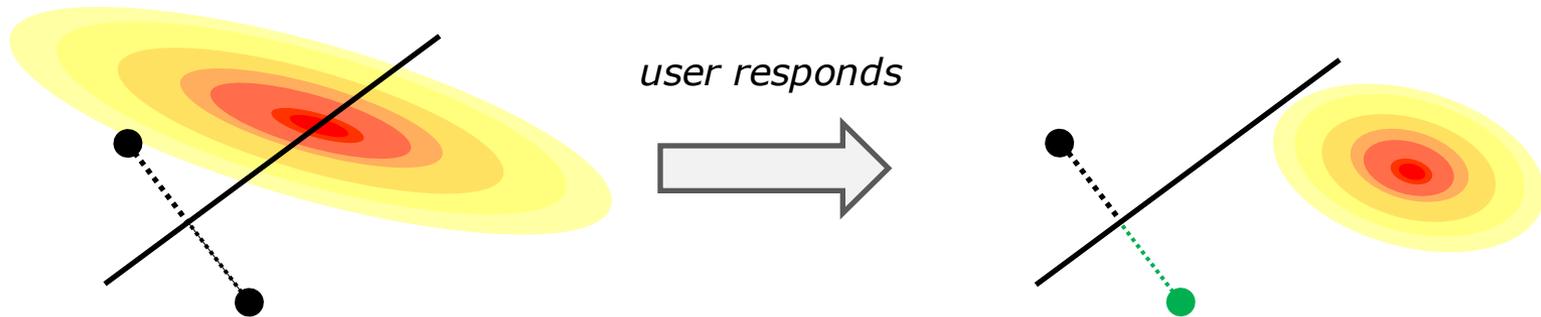
Our contribution

- ***Directly*** incorporate noise model into adaptive selection of pairs
- Strategy 1: InfoGain
- Strategy 2: EPMV
 - analytically tractable
- Strategy 3: MCMV
 - computationally tractable

Strategy 1: Maximize information gain (InfoGain)

- Y_i : binary response to i^{th} paired comparison
- $h_i(W)$: differential entropy of posterior
- *InfoGain*: choose queries that maximize expected decrease in posterior entropy i.e. *information gain*:

$$I(W; Y_i | y^{i-1}) = h_{i-1}(W) - E_{Y_i}[h_i(W) | y^{i-1}]$$



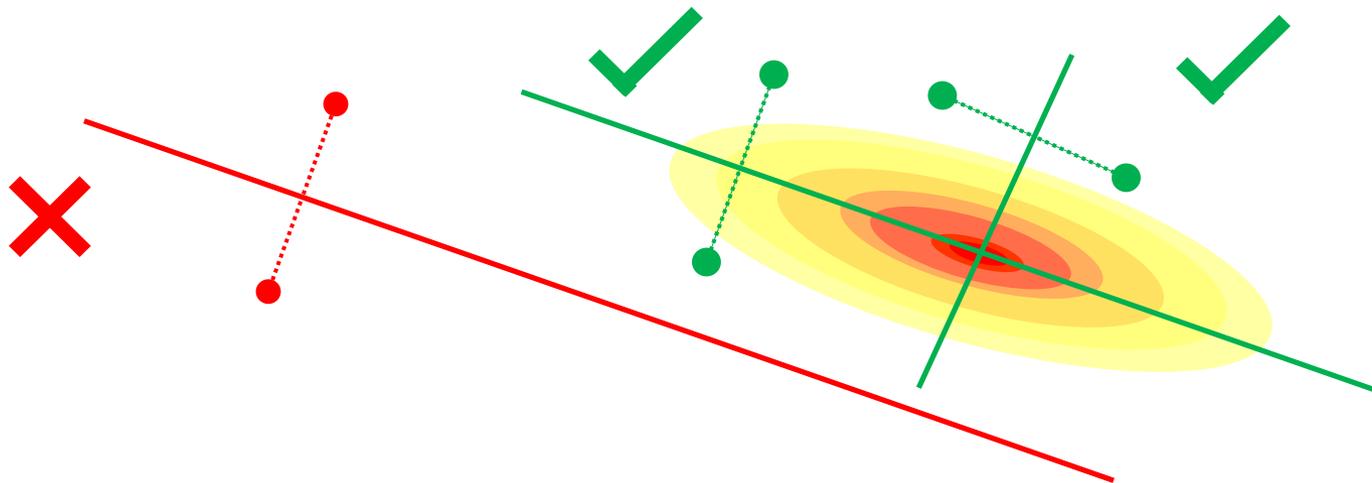
- No closed-form expression, estimate with samples from posterior
 - Computationally **expensive**: scales in product of # of samples and # candidate pairs
- Difficult to analyze convergence

Information gain intuition

- Symmetry of mutual information:

$$I(W; Y_i | y^{i-1}) = \boxed{H(Y_i | y^{i-1})} - H(Y_i | W, y^{i-1})$$

- **First term** promotes selection of comparisons where outcome is **non-obvious**, given previous responses
 - Maximized when comparison response is **equiprobable**, i.e. probability of picking each pair item is 1/2



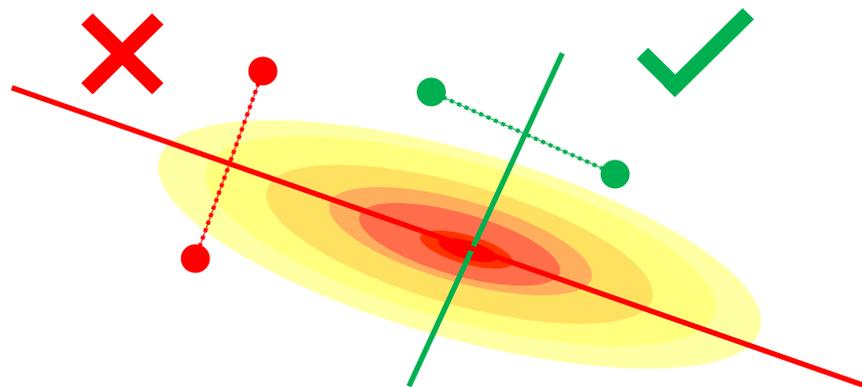
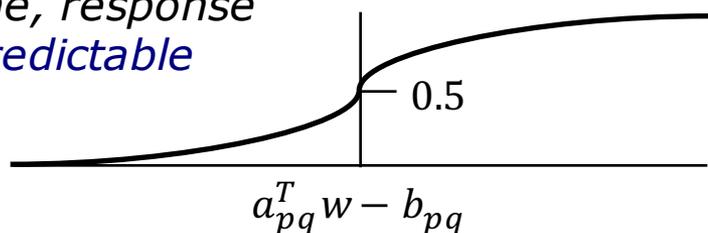
Information gain intuition

- Symmetry of mutual information:

$$I(W; Y_i | y^{i-1}) = H(Y_i | y^{i-1}) - \boxed{H(Y_i | W, y^{i-1})}$$

- **Second term** promotes selection of comparisons that would have **predictable** outcomes if w were known

When w close to hyperplane, response is *unpredictable*



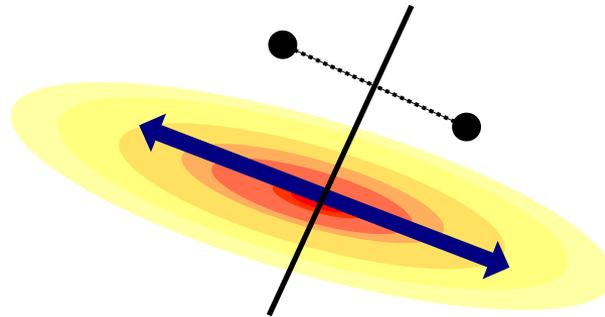
- Choose query where w is **far** from hyperplane in expectation
 - i.e. posterior variance orthogonal to hyperplane (*projected variance*) is **large**

Strategy 2: Equiprobable, max-variance (EPMV)

$$I(W; Y_i | y^{i-1}) = \boxed{H(Y_i | y^{i-1})} - \boxed{H(Y_i | W, y^{i-1})}$$

- *Equiprobable*: response is equally likely to be either item
 - Determines hyperplane threshold
- *Max-variance*: comparison cuts in direction of maximum projected variance
 - Determines hyperplane weights

$$P(p < q) = 1/2$$



Proposition

For equiprobable comparison with hyperplane weights a_{pq} ,

$$I(W; Y_i | y^{i-1}) \geq L_1 \left(a_{pq}^T \Sigma_{W|Y^{i-1}} a_{pq} \right)$$

where L_1 is a monotonically increasing function.

- EPMV approximates InfoGain

Theorem

For the EPMV query scheme with each selected query satisfying $k_{pq} \|a_{pq}\| \geq k_{min} > 0$ and stopping threshold $\varepsilon > 0$, consider the stopping time $T_\varepsilon = \min \left\{ i: \left| \Sigma_{W|y^i} \right|^{\frac{1}{d}} < \varepsilon \right\}$. We have

$$E[T_\varepsilon] = O\left(d \log \frac{1}{\varepsilon} + \frac{1}{\varepsilon k_{min}^2} d^2 \log \frac{1}{\varepsilon}\right).$$

Furthermore, for any query scheme $E[T_\varepsilon] = \Omega\left(d \log \frac{1}{\varepsilon}\right)$.

- For large noise constants ($k_{min} \gg 0$), EPMV reduces the posterior volume at a nearly-optimal rate.

EPMV in practice

- Often, one selects pair from pool, rather than querying arbitrary hyperplanes
- Select pair that maximizes approximate EPMV utility function, for $\lambda > 0$

$$\arg \max_{p,q} \underbrace{k_{pq} \sqrt{a_{pq}^T \Sigma_{W|Y^{i-1}} a_{pq}}}_{\text{Prefers max-variance queries}} - \underbrace{\lambda \left| \hat{p}_1 - \frac{1}{2} \right|}_{\text{Prefers equiprobable queries}}$$
$$\hat{p}_1 = P(Y_i = 1 | Y^{i-1}) = \mathbb{E}_{W|Y^{i-1}} \left[\frac{1}{1 + e^{-k_{pq}(a_{pq}^T W - b_{pq})}} \right]$$

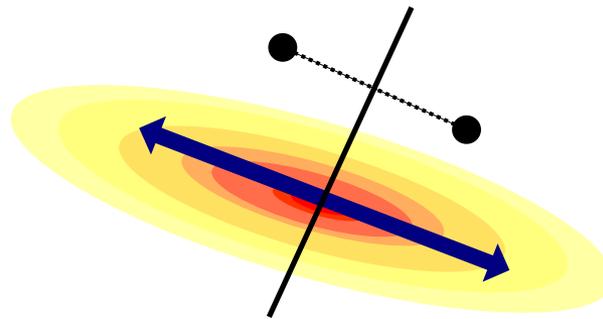
- Computationally **expensive** – same utility evaluation cost as InfoGain

Strategy 3: Mean-cut, max-variance (MCMV)

$$I(W; Y_i | y^{i-1}) = \boxed{H(Y_i | y^{i-1})} - \boxed{H(Y_i | W, y^{i-1})}$$

- Computational bottleneck in EPMV is evaluating equiprobable property
 - Approximate equiprobable property with *mean-cut* property i.e. hyperplane passes through posterior mean

$$a_{pq}^T E[W | Y^{i-1}] - b_{pq} = 0$$



Proposition

For mean-cut comparisons with $a_{pq}^T \Sigma_{W|Y^{i-1}} a_{pq} \gg 0$,

$$|p(Y_i|y^{i-1}) - 1/2| \lesssim 0.14$$

- MCMV approximates EPMV

Proposition

For mean-cut comparison with hyperplane weights a_{pq} ,

$$I(W; Y_i | y^{i-1}) \geq L_2 \left(a_{pq}^T \Sigma_{W|Y^{i-1}} a_{pq} \right)$$

where L_2 is a monotonically increasing function.

- MCMV approximates InfoGain

MCMV in practice

- Select pair that maximizes utility function, for $\lambda > 0$

$$\arg \max_{p,q} \underbrace{k_{pq} \sqrt{a_{pq}^T \Sigma_{W|Y^{i-1}} a_{pq}}}_{\text{Prefers max-variance queries}} - \lambda \underbrace{\frac{|a_{pq}^T \mathbb{E}[W|Y^{i-1}] - b_{pq}|}{\|a_{pq}\|_2}}_{\text{Prefers mean-cut queries}}$$

- Computational cost is ***much*** cheaper than InfoGain and EPMV
 - Scales with ***sum*** of # number of posterior samples and # candidate pairs, rather than ***product***

Methods overview

Method	Advantages	Limitations
InfoGain	Directly minimizes posterior volume	Computationally expensive Difficult to analyze
EPMV	Convergence guarantee	Computationally expensive
MCMV	Computationally cheap	No convergence guarantee (future work)

Simulated results

- Item embedding constructed from Yummly Food-10k dataset (Wilber et al., 2015; 2014)
 - 10,000 food items
 - ~ 1 million human comparisons between items



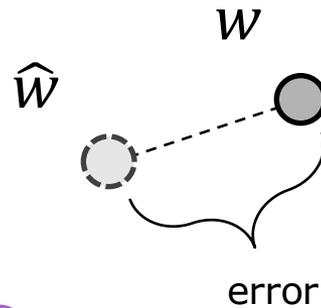
- Simulated pairwise search
 - Noise constant k_{pq} estimated from training comparisons
 - User preference point drawn uniformly from hypercube, $d = 4$

Simulated results – baseline methods

- *Random*
 - pairs selected uniformly at random
 - user estimated as posterior mean
- *GaussCloud* (Massimino & Davenport, 2018)
 - pairs chosen to approximate Gaussian point cloud around estimate, shrinks over multiple stages
 - user estimated by approximately solving non-convex program
- *ActRank* (Jamieson & Nowak, 2011)
 - pairs selected that intersect feasible region of preference points
 - query repeated multiple times, majority vote taken
 - user estimated as Chebyshev center*

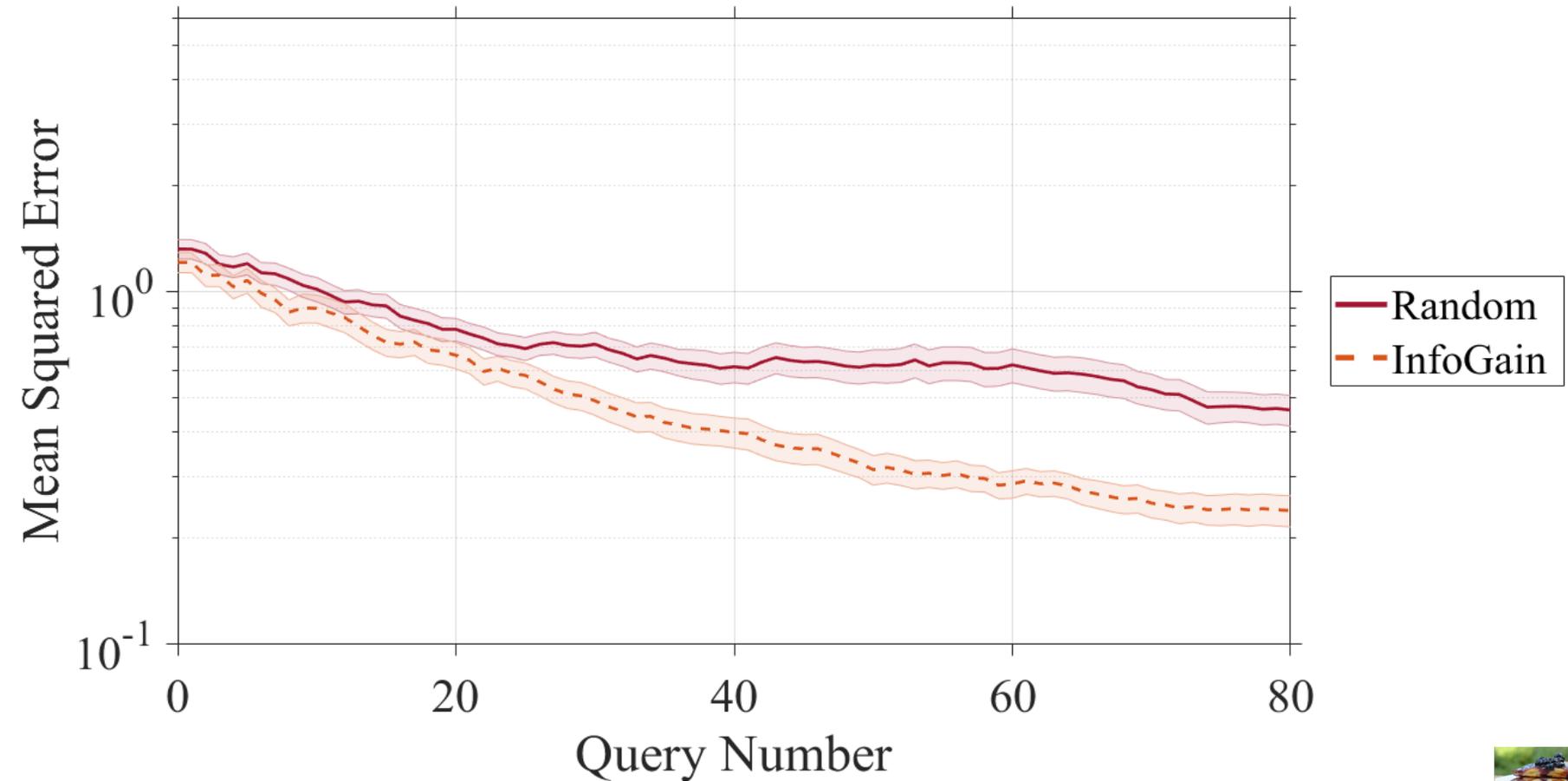
* our addition

Simulated results - MSE

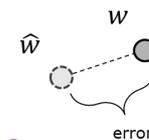


- Mean-squared error (MSE) measures accuracy in estimating user preference point

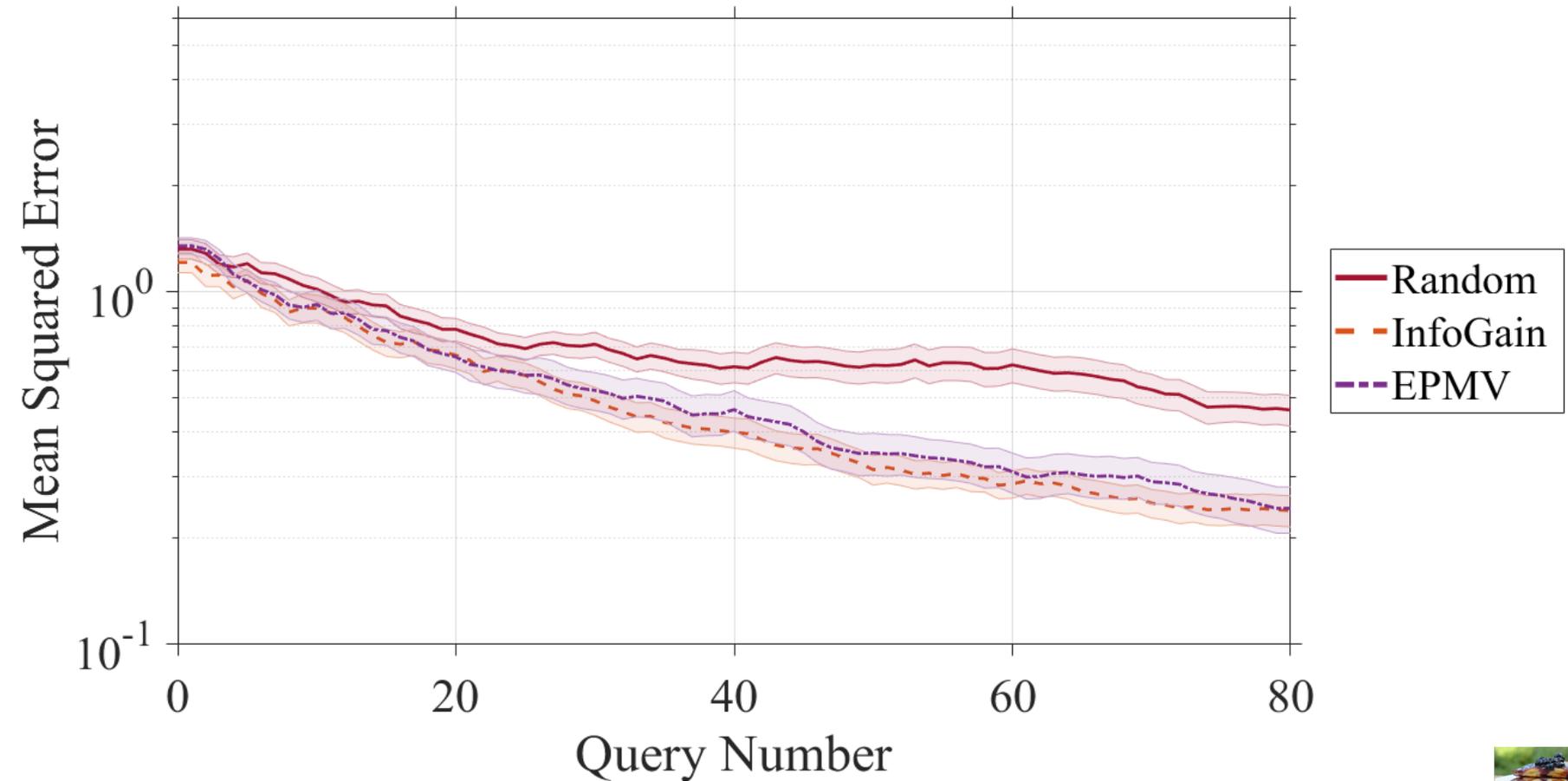
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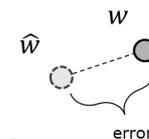
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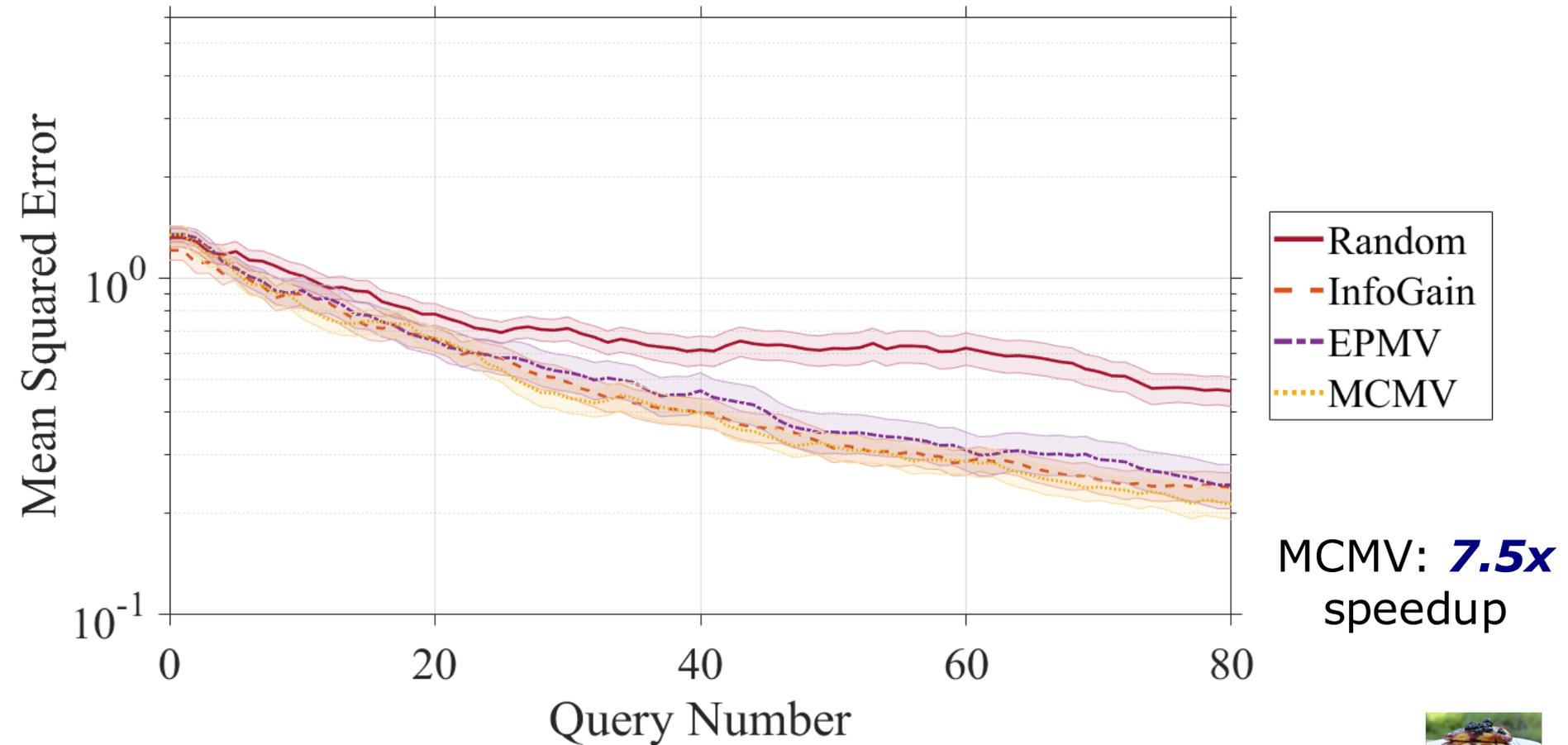
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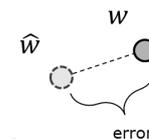
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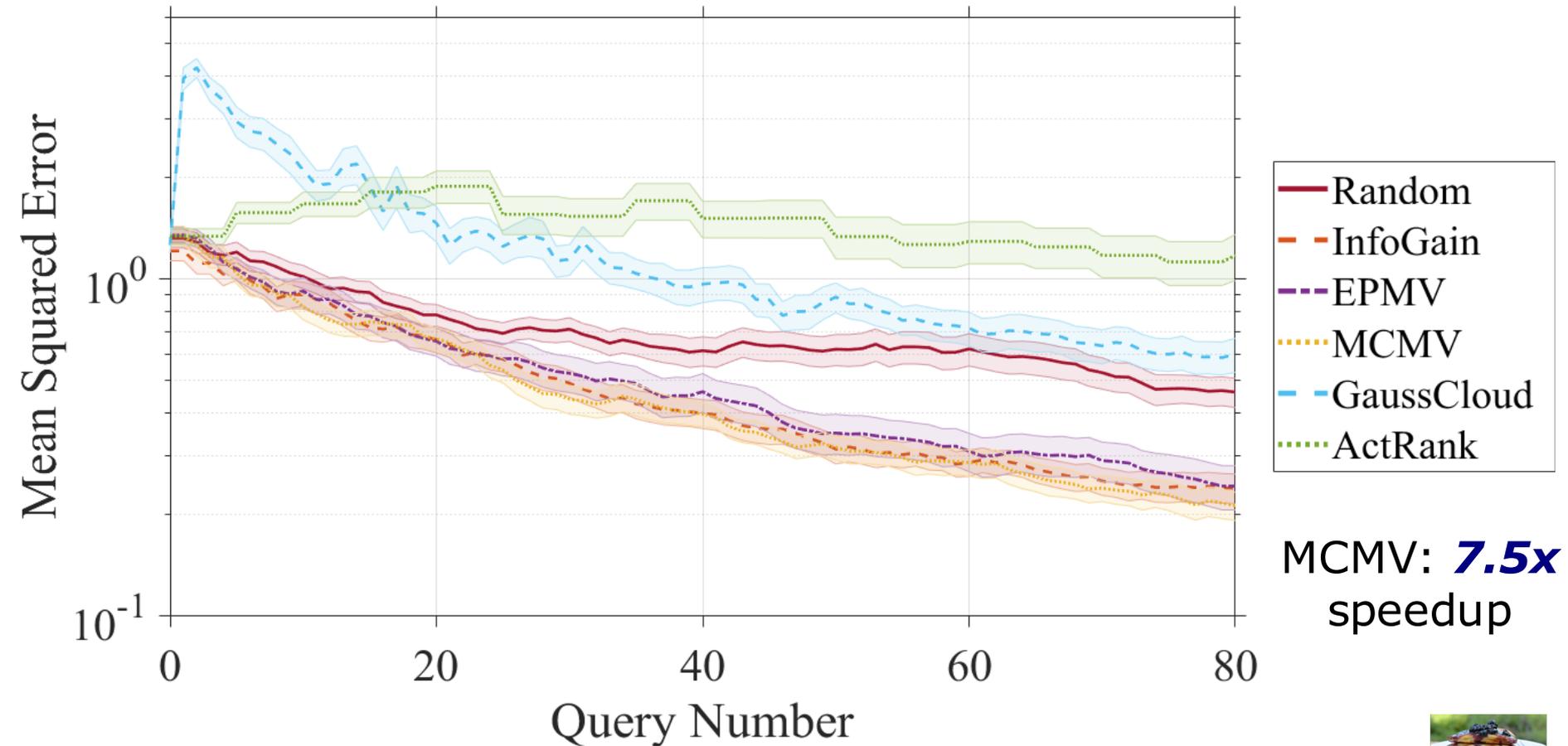
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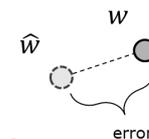
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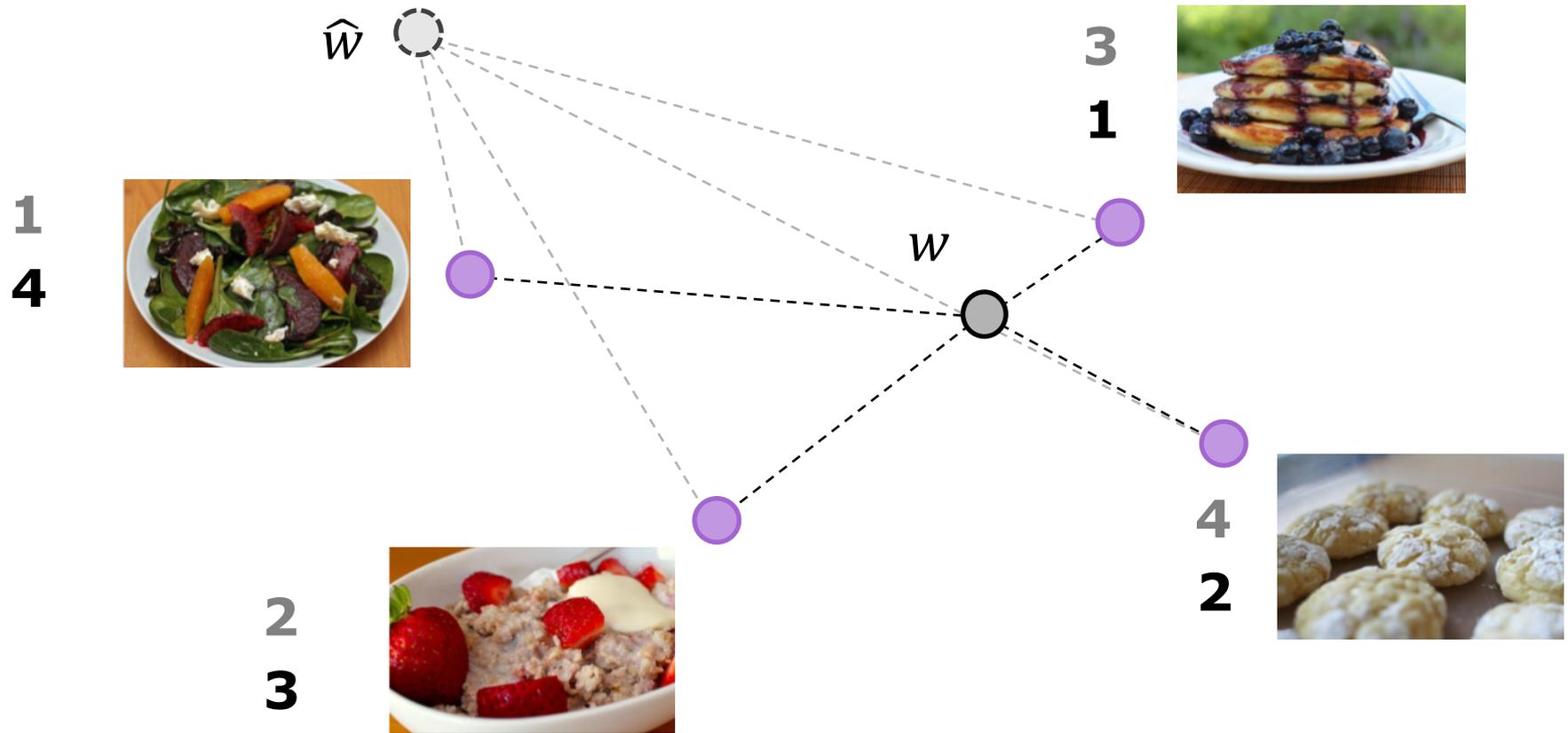
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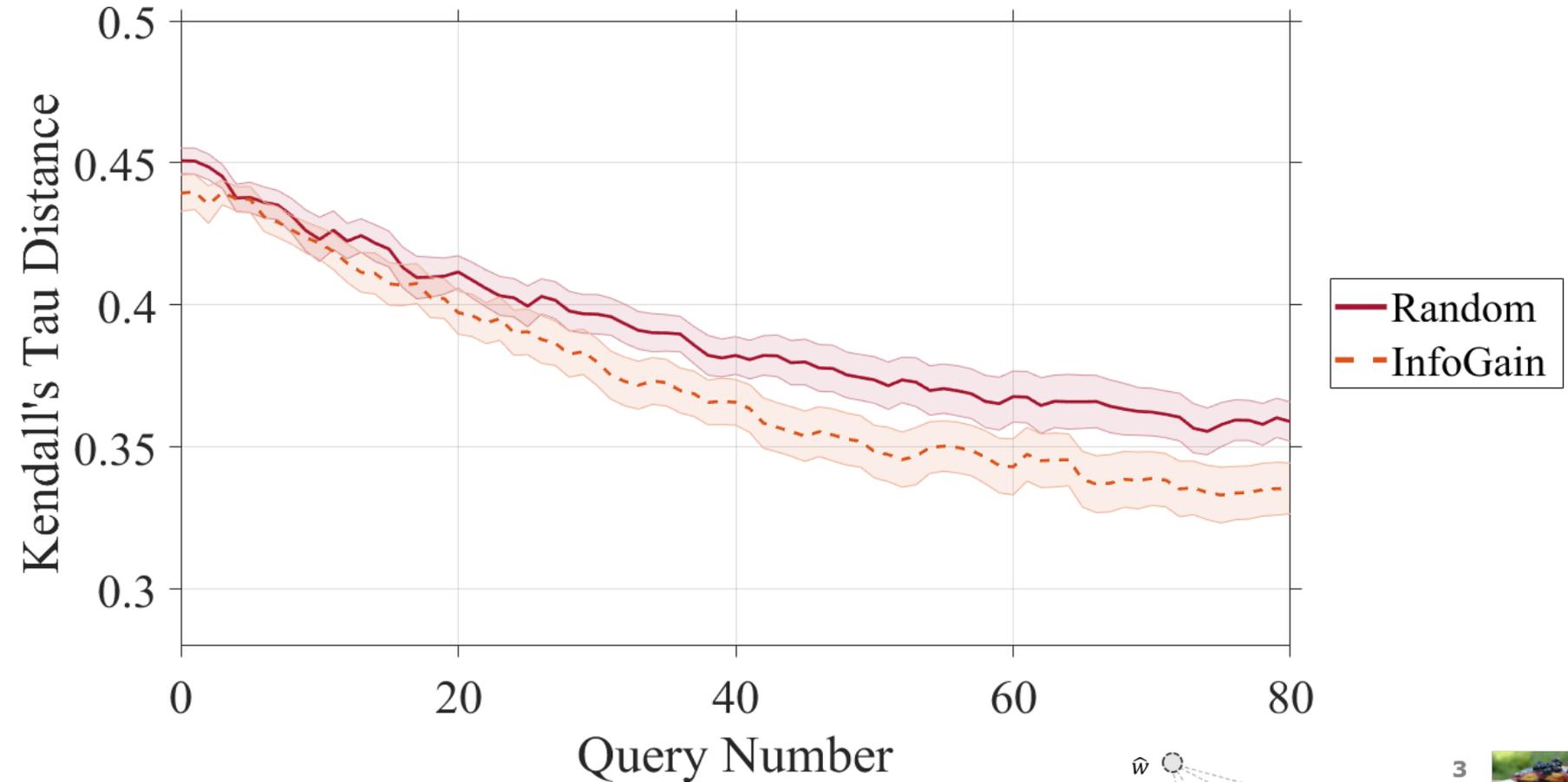


Simulated results – Kendall's Tau distance

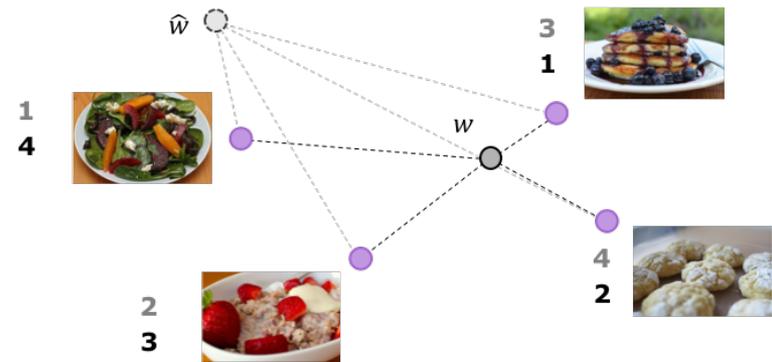


- Normalized Kendall's Tau distance for preference ranking of 15 randomly selected items

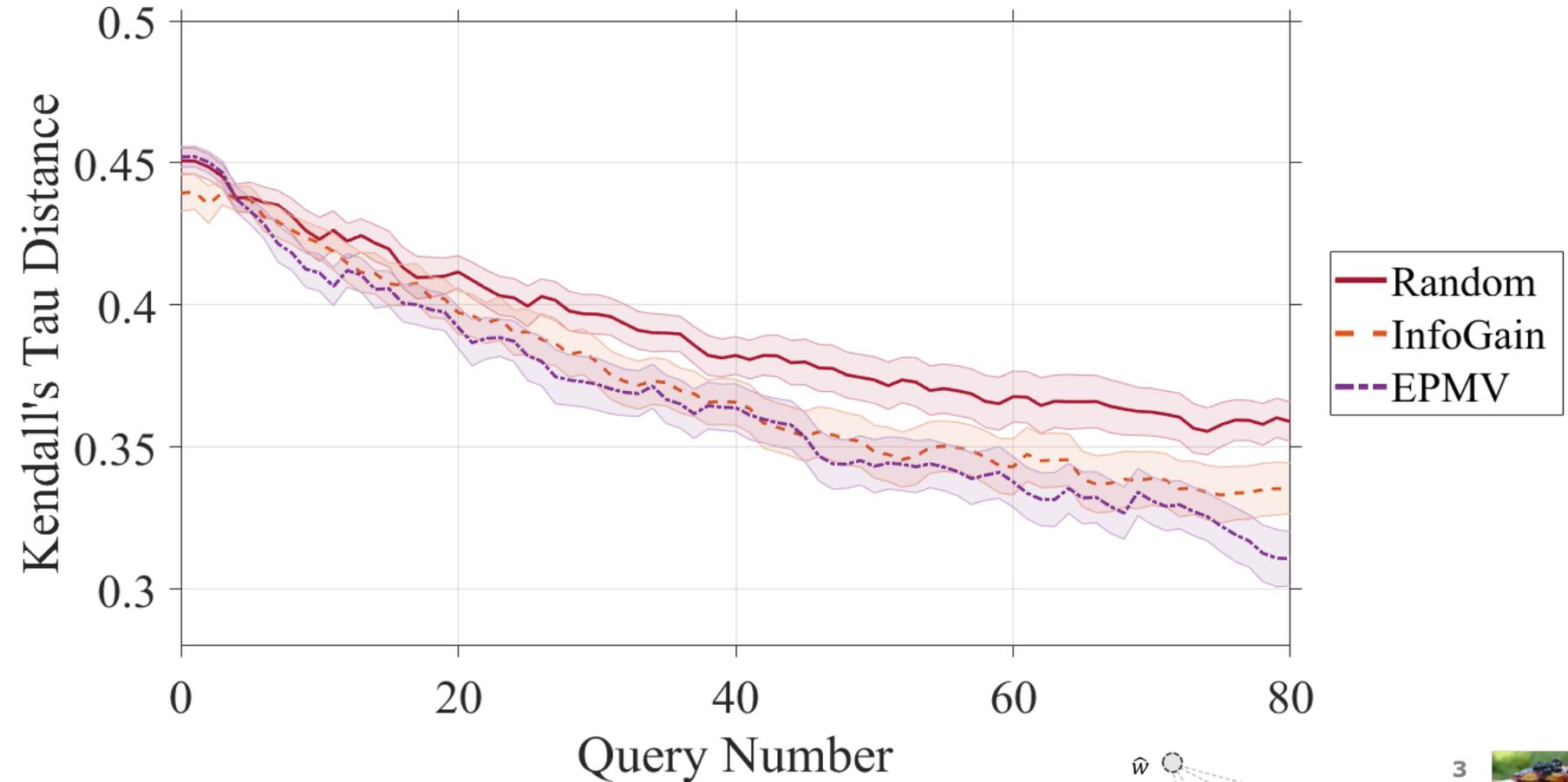
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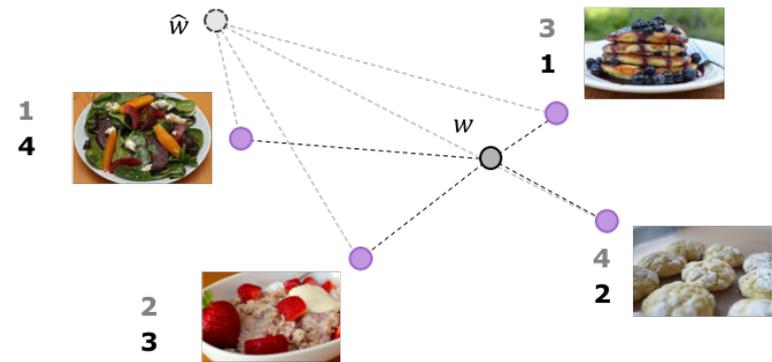
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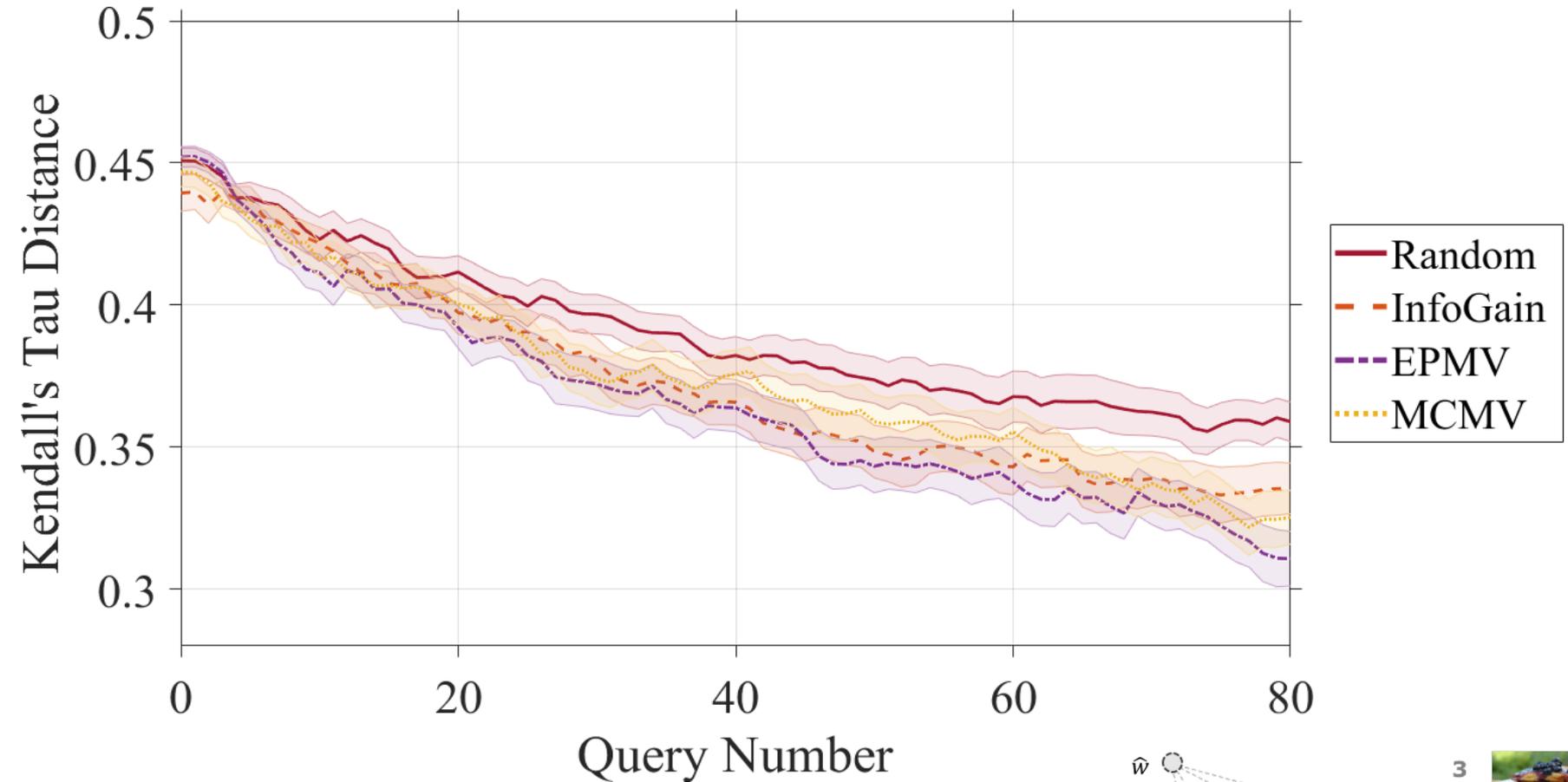
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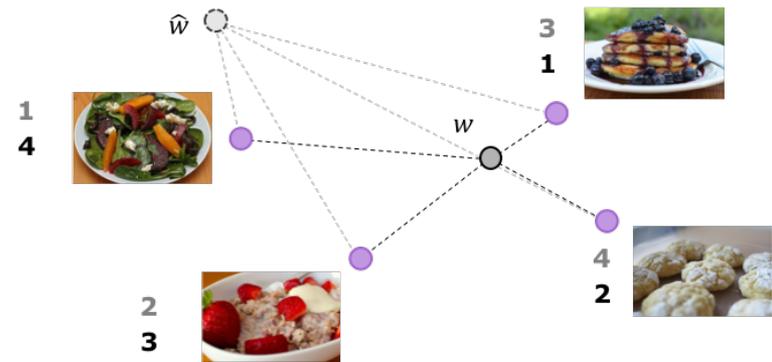
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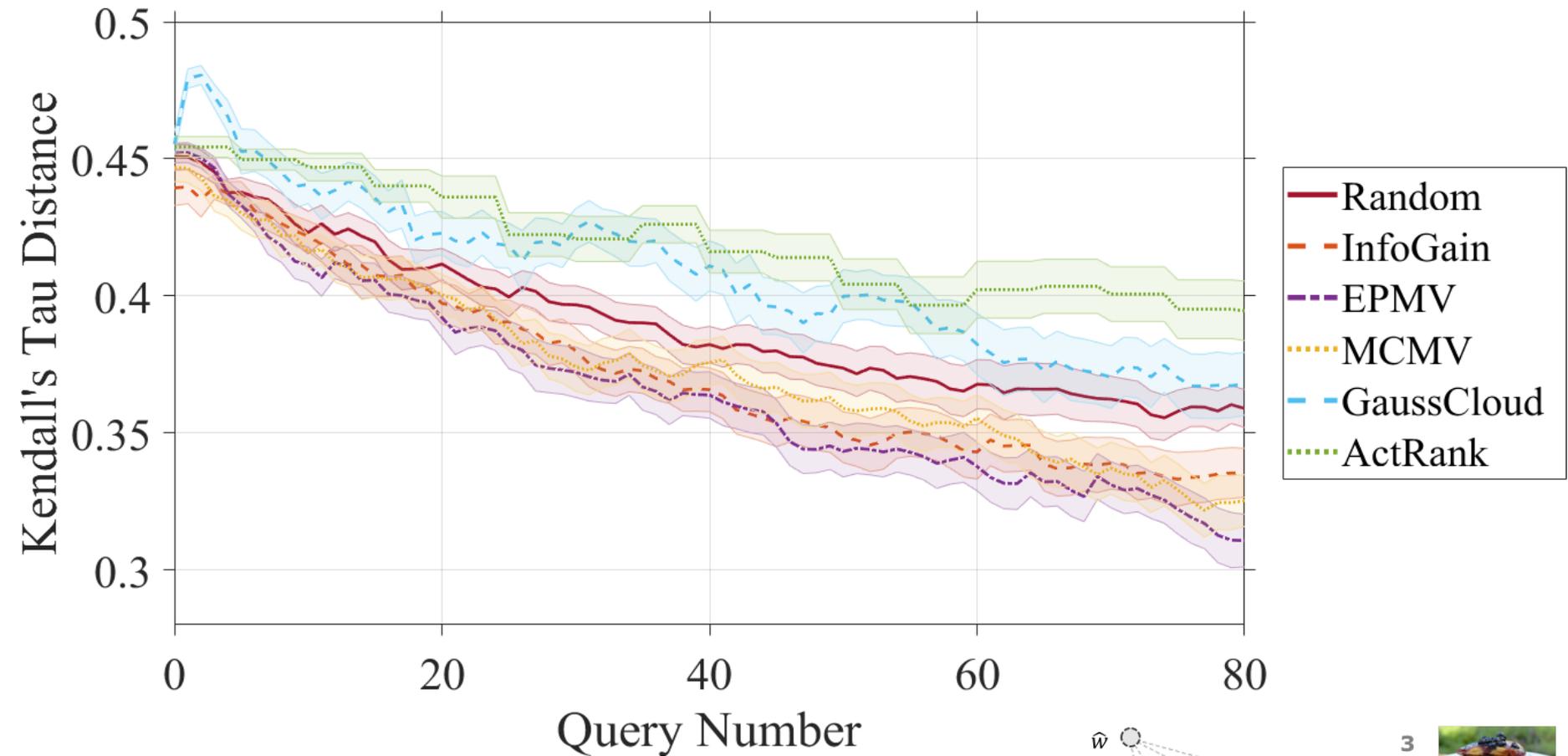
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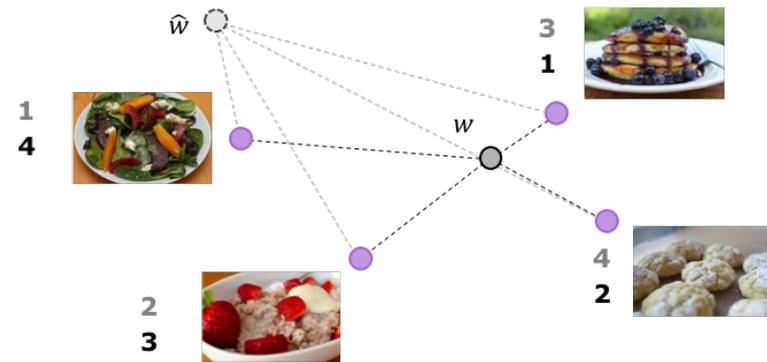
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Simulated results – Kendall's Tau distance



- Normalized Kendall's Tau distance for preference ranking of 15 randomly selected items



Takeaways

- First effort to directly model noise in active pairwise preference learning for ideal point model
 - InfoGain
 - Equiprobable max-variance (EPMV)
 - Mean-cut max-variance (MCMV)
- Preliminary support for robustness to noise mismatch
- Potential applications
 - Advertising, online shopping
 - Parameter settings
 - Product customization, recipe generation
 - Database search (medical records, faces)

Code available at: <https://github.com/siplab-gt/pairsearch>

<http://siplab.gatech.edu>

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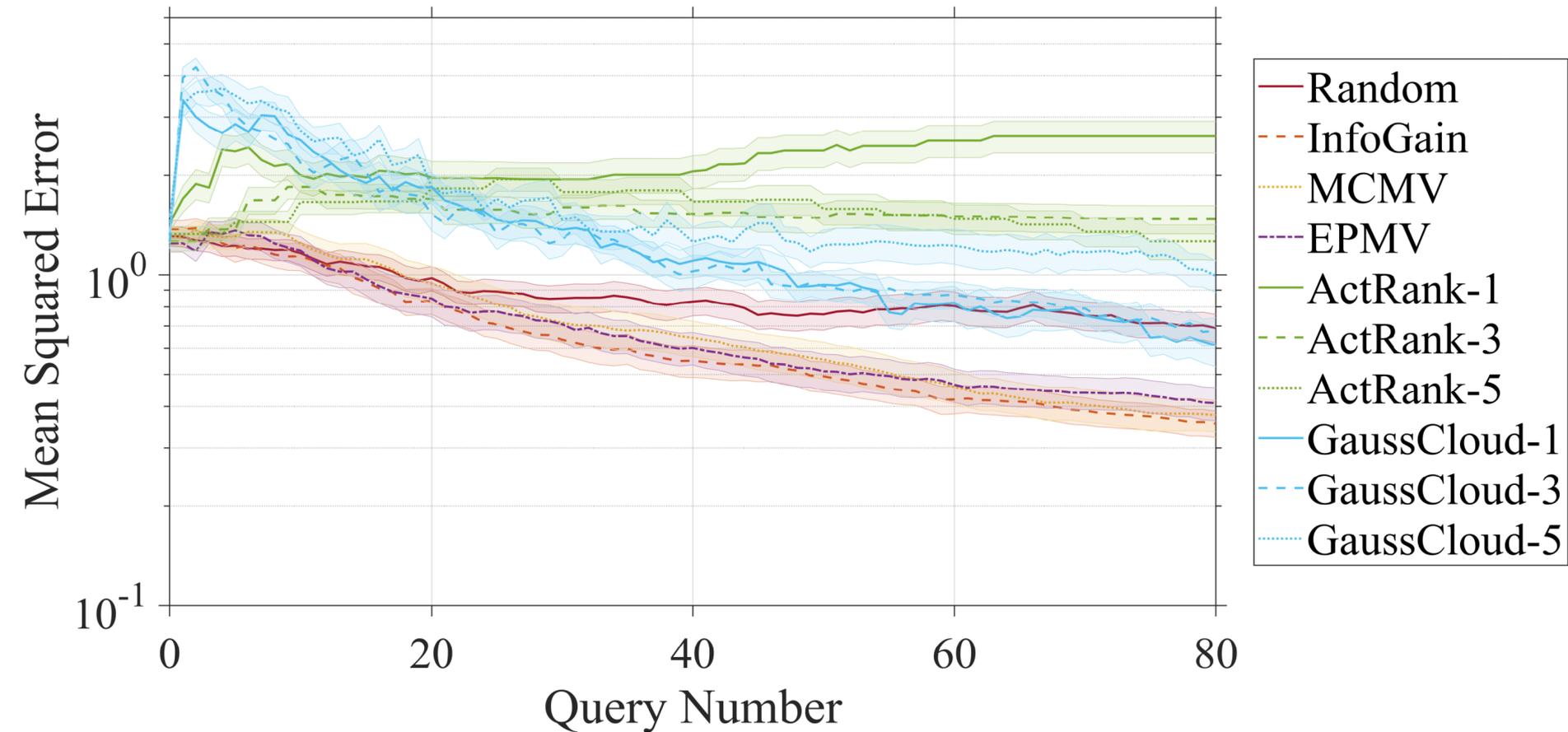


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POSTER #260

TODAY, 6:30 – 9:00 PM, Pacific Ballroom

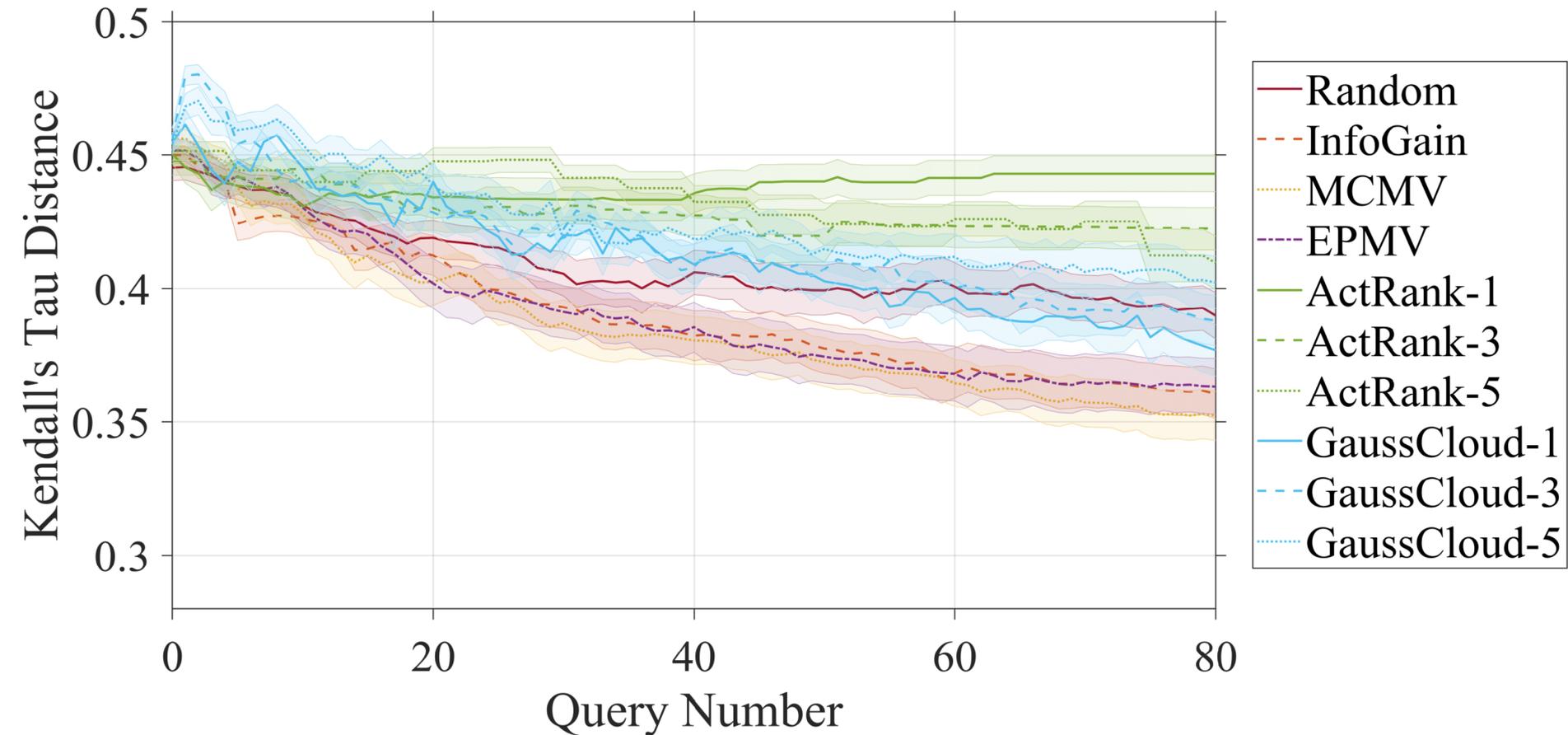
Simulated mismatched noise - MSE



$$y_i = \text{sign}(k_{pq}(a_i^T w - b_i) + Z)$$

$$Z \sim \mathcal{N}(0, 1)$$

Simulated mismatched noise – Kendall's Tau



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