

Scalable Nonparametric Sampling from Multimodal Posteriors with the Posterior Bootstrap

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**The
Alan Turing
Institute**

Thirty-sixth International Conference on Machine Learning

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Challenges in Bayesian Inference

Suppose we observe $y_{1:n} \stackrel{\text{iid}}{\sim} F_0$. We are interested in a parameter $\theta \in \Theta \subseteq \mathbb{R}^p$, which indexes a family of probability densities $\mathcal{F}_\Theta = \{f_\theta(y); \theta \in \Theta\}$.

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- ▶ Unlikely in large and complex datasets

Computation

- ▶ Markov chain Monte Carlo is inherently serial, computationally expensive, and struggles with multimodal posteriors
- ▶ Difficult to quantify the approximation of Variational Bayes, and poor uncertainty estimates

Bayesian Nonparametric Learning

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- ▶ A Dirichlet process (DP) prior on the unknown data distribution accounts for **model misspecification**.
- ▶ We sample from the NPL posterior through **parallel optimizations** of randomized objective functions.
- ▶ Our method is adept at sampling from **multimodal** posterior distributions via a random restart mechanism.

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Suppose we observe $y_{1:n} \stackrel{\text{iid}}{\sim} F_0$.

Our parameter of interest is defined:

$$\theta_0(F_0) = \arg \min_{\theta} \int \ell(y, \theta) dF_0(y) \quad (1)$$

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- ▶ For example, $\ell(y, \theta) = |y - \theta|$ gives the median and $(y - \theta)^2$ gives the mean.
- ▶ For model fitting, let $\ell(y, \theta) = -\log f_{\theta}(y)$, where f_{θ} is the density of some parametric model.

Our NPL Posterior

We elicit a Dirichlet process prior on the unknown sampling distribution:

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Calculate the posterior over F from the conjugacy of the DP:

$$\begin{aligned} [F|y_{1:n}] &\sim \text{DP}(\alpha + n, G_n) \\ G_n &= \frac{\alpha}{\alpha + n} F_\pi + \frac{1}{\alpha + n} \sum_{i=1}^n \delta_{y_i} \end{aligned} \quad (3)$$

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Then the NPL posterior over θ is defined:

$$\tilde{\pi}(\theta|y_{1:n}) = \int \pi(\theta|F) d\pi(F|y_{1:n}) \quad (4)$$

where $\pi(\theta|F) = \delta_{\theta_0(F)}(\theta)$; the delta arises as θ is a deterministic functional of F as in (1).

Sampling from the NPL Posterior

Algorithm 1 NPL Posterior Sampling

for $i = 1$ **to** B **do**

 Draw $F^{(i)} \sim \pi(F|y_{1:n})$

$\theta^{(i)} = \arg \min_{\theta} \int \ell(y, \theta) dF^{(i)}(y)$

end for

Here $\theta^{(i)} \sim \tilde{\pi}(\theta|y_{1:n})$ and B is the number of posterior samples.

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- ▶ NPL posterior is usually intractable
- ▶ Embarrassingly parallel sampling scheme

Properties of NPL Posterior

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Consistency at θ_0 , from the properties of the DP. This is true irrespective of the choice of F_π .

Asymptotic dominance of $\tilde{\pi}(\cdot|y_{1:n})$ over $\pi(\cdot|y_{1:n})$ for $\alpha = 0$:

$$\begin{aligned}\mathbb{E}_{y_{1:n} \sim q} [\text{KL}(q(\cdot) || \pi(\cdot|y_{1:n})) - \text{KL}(q(\cdot) || \tilde{\pi}(\cdot|y_{1:n}))] \\ = K(q(\cdot)) + o(n^{-1})\end{aligned}$$

for all distributions q , where K is a non-negative and possibly positive real-valued functional.

The Posterior Bootstrap

Draws of F from the posterior DP are almost surely discrete:

$$\begin{aligned}\theta(F) &= \arg \min_{\theta} \int \ell(y, \theta) dF(y) \\ &= \arg \min_{\theta} \sum_{k=1}^{\infty} w_k \ell(\tilde{y}_k, \theta)\end{aligned}\tag{5}$$

where $w_{1:\infty} \sim \text{GEM}(\alpha + n)$ and $\tilde{y}_{1:\infty} \stackrel{\text{iid}}{\sim} G_n$ from the stick-breaking construction.

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As an approximation, we can truncate the sum to obtain the **posterior bootstrap**.

The Posterior Bootstrap

Algorithm 2 Posterior Bootstrap Sampling

Define T as truncation limit

Observed samples are $y_{1:n}$

for $i = 1$ **to** B **do**

Draw prior pseudo-samples $\tilde{y}_{1:T}^{(i)} \stackrel{\text{iid}}{\sim} F_{\pi}$

Draw $(w_{1:n}^{(i)}, \tilde{w}_{1:T}^{(i)}) \sim \text{Dir}(1, \dots, 1, \alpha/T, \dots, \alpha/T)$

$$\theta^{(i)} = \arg \min_{\theta} \left\{ \sum_{j=1}^n w_j^{(i)} \ell(y_j, \theta) + \sum_{k=1}^T \tilde{w}_k^{(i)} \ell(\tilde{y}_k^{(i)}, \theta) \right\}$$

end for

The Posterior Bootstrap for a Linear Model

For a simple linear model

$$f_{\beta}(y|x) = \mathcal{N}(y; \beta x + \gamma, 1)$$

sample $(\beta^{(i)}, \gamma^{(i)}) \sim \tilde{\pi}(\beta, \gamma|y)$
with $\alpha = 0$. Here $n = 11$ and
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Multimodality

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Algorithm 3 Random Restart NPL Posterior Sampling

for $i = 1$ **to** B **do**

Draw $F^{(i)} \sim \text{DP}(\alpha + n, G_n)$

for $r = 1$ **to** R **do**

Draw $\theta_r^{\text{init}} \sim \pi_0$

$\theta_r^{(i)} = \text{local arg min}_{\theta} (\int \ell(y, \theta) dF^{(i)}(y), \theta_r^{\text{init}})$

end for

$\theta^{(i)} = \text{arg min}_r \int \ell(y, \theta_r^{(i)}) dF^{(i)}(y)$

end for

In [Lyddon et al., 2018], they let $\pi(F)$ be a mixture of Dirichlet processes:

$$F|\theta \sim \text{DP}(\alpha, F_\theta); \quad \theta \sim \pi(\theta) \quad (6)$$

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where $(f_\theta, \pi(\theta))$ is the conventional Bayesian likelihood and prior.

- ▶ They recover conventional Bayesian inference for $\alpha \rightarrow \infty$
- ▶ Posterior $\pi(F|y_{1:n})$ requires sampling from Bayesian posterior $\pi(\theta|y_{1:n})$, which is the computationally difficult step

Related Approaches

- ▶ Bayesian bootstrap [Rubin, 1981] for $\alpha = 0$

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- ▶ Weighted likelihood bootstrap [Newton and Raftery, 1994] if we further set $\ell(y, \theta) = -\log f_{\theta}(y)$
- ▶ General Bayesian updating [Bissiri et al., 2016] also uses the expected loss to define a posterior

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Gaussian Mixture Model

Our Bayesian model for K-component diagonal GMM with non-conjugate prior is:

$$\begin{aligned} \mathbf{y}_i | \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\sigma} &\sim \sum_{k=1}^K \pi_k \mathcal{N}(\boldsymbol{\mu}_k, \text{diag}(\boldsymbol{\sigma}_k^2)) \\ \boldsymbol{\pi} | \mathbf{a}_0 &\sim \text{Dir}(\mathbf{a}_0, \dots, \mathbf{a}_0) \\ \mu_{kj} &\sim \mathcal{N}(0, 1) \\ \sigma_{kj} &\sim \text{logNormal}(0, 1) \end{aligned} \tag{7}$$

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For NPL, we are interested in model fitting, so our loss function is simply the negative log-likelihood:

$$\ell(\mathbf{y}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\sigma}) = -\log \sum_{k=1}^K \pi_k \mathcal{N}(\mathbf{y}; \boldsymbol{\mu}_k, \text{diag}(\boldsymbol{\sigma}_k^2)) \tag{8}$$

Gaussian Mixture Model: Toy Data

Toy data from a GMM with $K = 3$, $d = 1$ and the parameters:

$$\boldsymbol{\pi}_0 = \{0.1, 0.3, 0.6\}, \quad \boldsymbol{\mu}_0 = \{0, 2, 4\}, \quad \boldsymbol{\sigma}_0^2 = \{1, 1, 1\} \quad (9)$$

$$n_{train} = 1000, n_{test} = 250$$

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As $n \gg d$, we elicit a noninformative NPL prior with $\alpha = 0$

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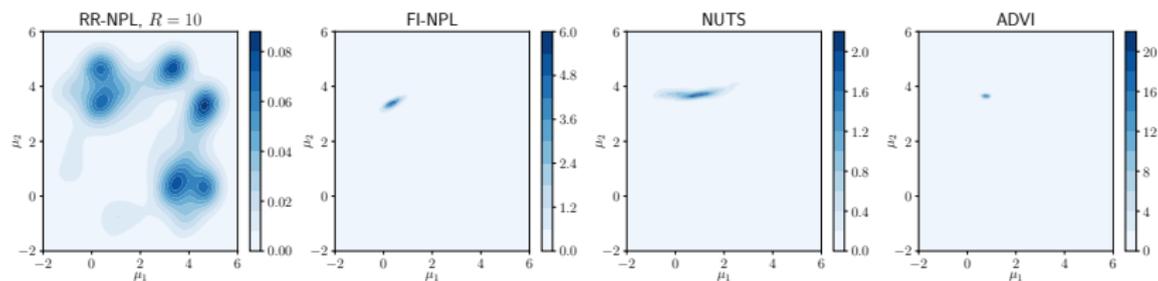


Figure 1: Posterior KDE of (μ_1, μ_2) in $K=3$ toy GMM problem

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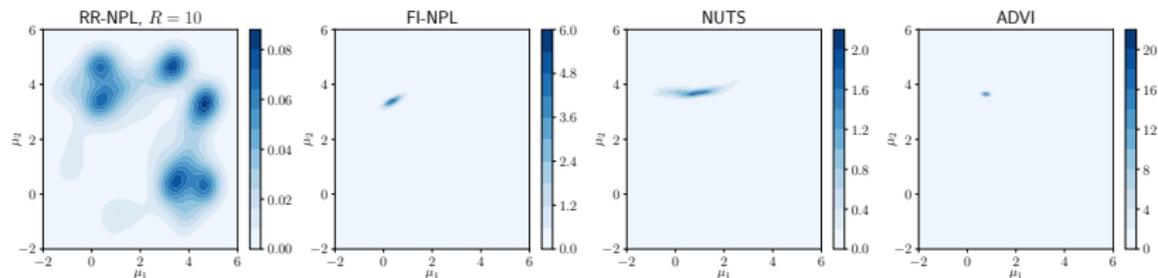


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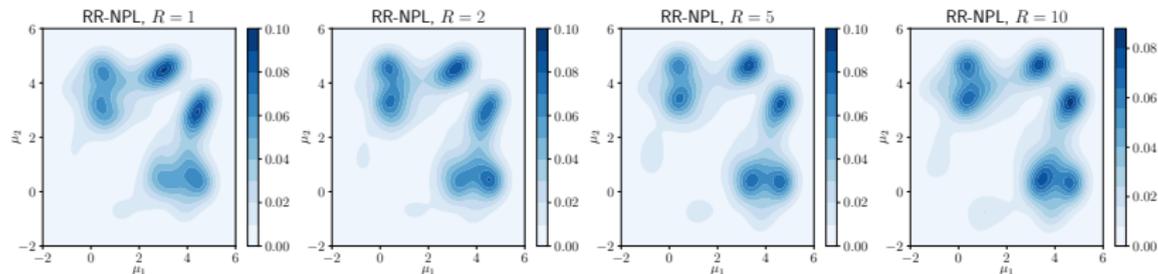


Figure 2: Posterior KDE of (μ_1, μ_2) in $K=3$ toy GMM problem for RR-NPL with increasing R

Sparse Logistic Regression

Our Bayesian model for sparse logistic is:

$$\begin{aligned}y_i | \mathbf{x}_i, \boldsymbol{\beta}, \beta_0 &\sim \text{Bernoulli}(\eta_i) \\ \eta_i &= \sigma(\boldsymbol{\beta}^T \mathbf{x}_i + \beta_0) \\ \beta_j &\sim \text{Student-t} \left(2a, 0, \frac{b}{a} \right)\end{aligned}\tag{10}$$

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For NPL, we use the loss:

$$\begin{aligned}\ell(y, \mathbf{x}, \boldsymbol{\beta}, \beta_0) &= -(y \log \eta + (1 - y) \log(1 - \eta)) \\ &\quad + \gamma \left(\frac{2a + 1}{2} \right) \sum_{j=1}^d \log \left(1 + \frac{\beta_j^2}{2b} \right)\end{aligned}\tag{11}$$

Sparse Logistic Regression: UCI Datasets

We use 3 binary classification datasets from UCI ML repo: 'Adult' ($n = 36177, d = 96$), 'Polish companies bankruptcy' ($n = 8402, d = 64$), and 'Arcene' ($n = 100, d = 10000$)

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Table 1: Mean log pointwise predictive density on held-out test data for LogReg

DATA SET	LOSS-NPL	NUTS	ADVI
ADULT	-0.326	-0.326	-0.327
POLISH	-0.229	-3.336	-0.247
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Table 2: Run-time for 2000 samples for LogReg on 4 72-core Azure VMs

DATA SET	LOSS-NPL	NUTS	ADVI
ADULT	2M24s	2H36M	26.9s
POLISH	19.0s	1H20M	3.3s
ARCENE	2M20s	4H31M	54.2s

Bayesian Sparsity-path-analysis: Genetics Dataset

Single-nucleotide polymorphisms from a genome-wide data set [Lee et al., 2012] with $n = 500$, $d = 50$

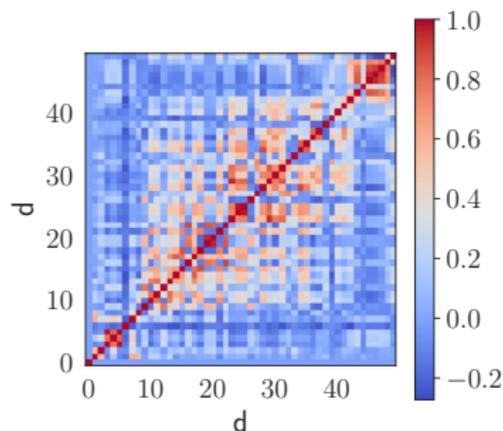


Figure 3: Block-like correlations of covariates \mathbf{x}

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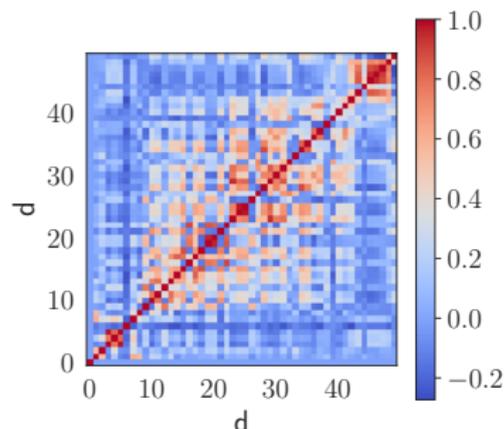


Figure 3: Block-like correlations of covariates \mathbf{x}

We simulated phenotype data from $y \sim \text{Bernoulli}(\sigma(\beta_0^T \mathbf{x}))$; β_0 has 5 non-zero components with the rest set to 0.

Bayesian Sparsity-path-analysis: Genetics Dataset

We vary the scale of the Student-t prior $c = b/a$ (same ℓ as before) to visualize how the responsibility of each covariate changes with sparsity

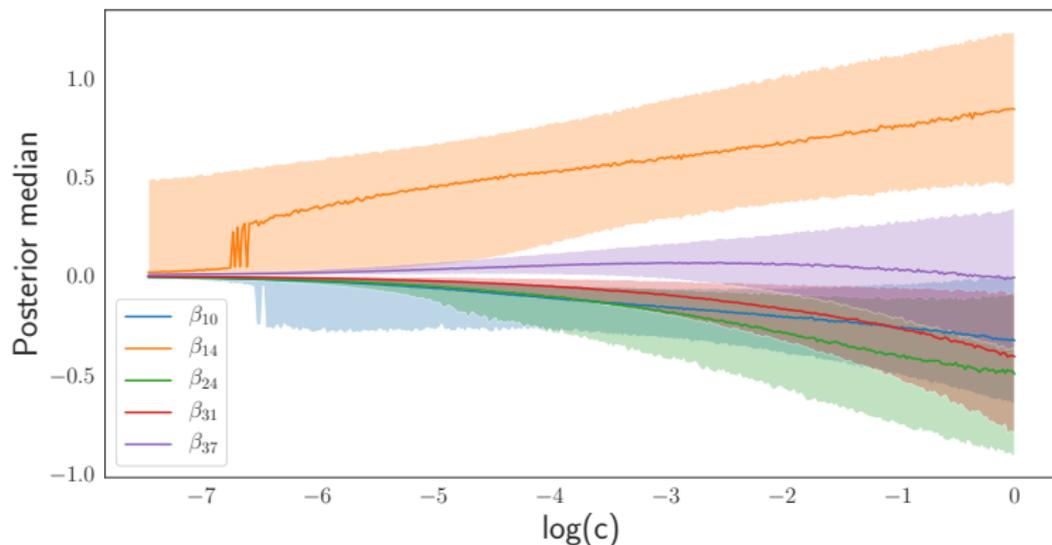


Figure 4: Lasso-type plot for posterior medians of non-zero β with 80% credible intervals against $\log(c)$ from genetic dataset. NPL required 5m 24s to generate 450×4000 posterior samples.

Bayesian Sparsity-path-analysis: Genetics Dataset

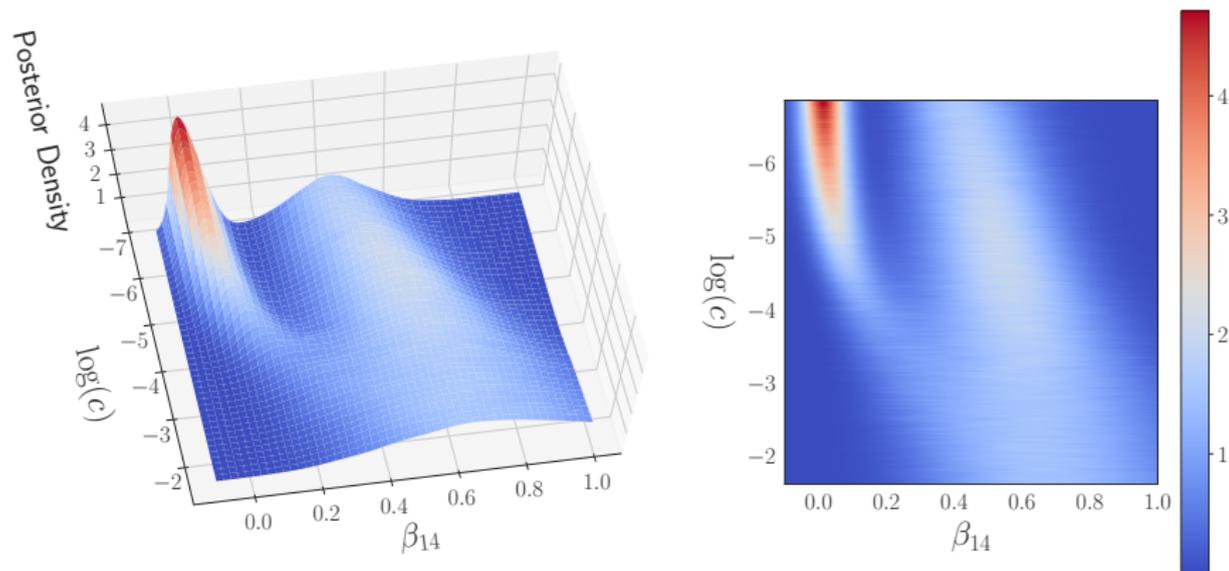


Figure 5: Posterior marginal KDE of β_{14} against $\log(c)$ from genetic dataset

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Thank you! Any questions?

Come check out poster #235.

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