

Composable Core-sets for Determinant Maximization: A Simple Near-Optimal Algorithm

Piotr Indyk

MIT

Sepideh Mahabadi

TTIC

Shayan Oveis Gharan

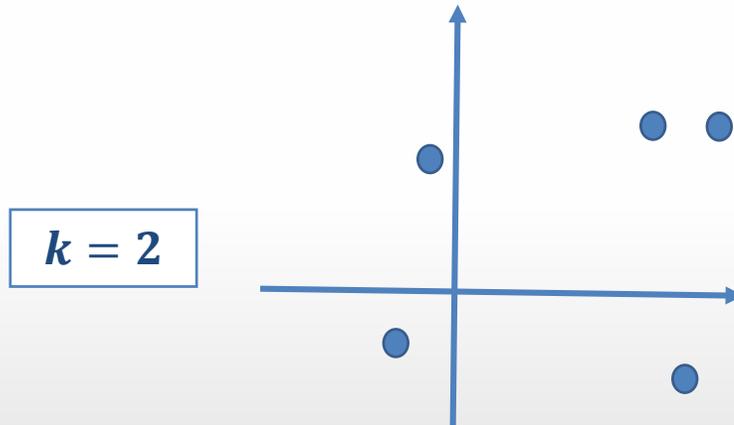
U. of Washington

Alireza Rezaei

U. of Washington

Volume (Determinant) Maximization Problem

Input: a set of n vectors $V \in \mathbb{R}^d$ and a parameter $k \leq d$,



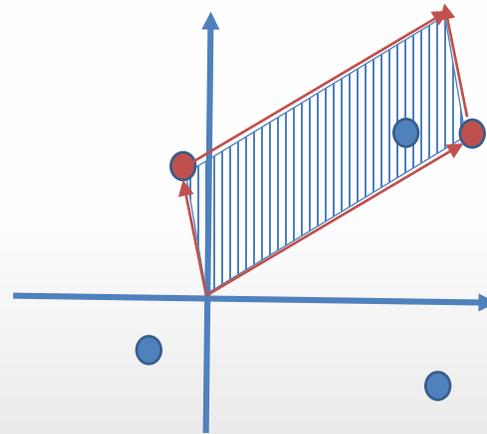
Volume (Determinant) Maximization Problem

Input: a set of n vectors $V \in \mathbb{R}^d$ and a parameter $k \leq d$,

Output: a subset $S \subset V$ of size k with the maximum volume

- Parallelepiped spanned by the points in S

$k = 2$

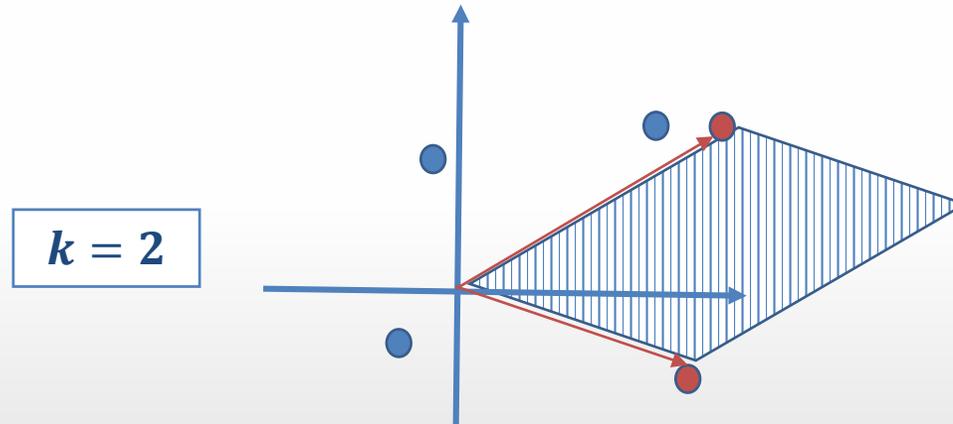


Volume (Determinant) Maximization Problem

Input: a set of n vectors $V \in \mathbb{R}^d$ and a parameter $k \leq d$,

Output: a subset $S \subset V$ of size k with the maximum volume

- Parallelepiped spanned by the points in S



Determinant (Volume) Maximization Problem

Input: a set of n vectors $V \in \mathbb{R}^d$ and a parameter $k \leq d$,

Output: a subset $S \subset V$ of size k with the maximum volume

- Parallelepiped spanned by the points in S

$$\begin{pmatrix} v_1 & v_2 & \dots & v_n \end{pmatrix}$$

V

Equivalent Formulation:

Reuse V to denote the matrix where its columns are the vectors in V

Determinant (Volume) Maximization Problem

Input: a set of n vectors $V \in \mathbb{R}^d$ and a parameter $k \leq d$,

Output: a subset $S \subset V$ of size k with the maximum volume

- Parallelepiped spanned by the points in S

$$\begin{matrix} \begin{pmatrix} v_1 \\ v_2 \\ \dots \\ v_n \end{pmatrix} \\ \mathbf{V}^T \end{matrix} \times \begin{matrix} \begin{pmatrix} v_1 & v_2 & \dots & v_n \end{pmatrix} \\ \mathbf{V} \end{matrix} = \begin{matrix} i & j \\ \begin{pmatrix} v_i \cdot v_j \end{pmatrix} \\ \mathbf{M} \end{matrix}$$

Equivalent Formulation:

Reuse V to denote the matrix where its columns are the vectors in V

- Let M be the gram matrix $V^T V$

$$M_{i,j} = v_i \cdot v_j$$

Determinant (Volume) Maximization Problem

Input: a set of n vectors $V \in \mathbb{R}^d$ and a parameter $k \leq d$,

Output: a subset $S \subset V$ of size k with the maximum volume

- Parallelepiped spanned by the points in S

$$\begin{pmatrix} v_1 \\ v_2 \\ \dots \\ v_n \end{pmatrix} \times \begin{pmatrix} v_1 & v_2 & \dots & v_n \end{pmatrix} = \begin{pmatrix} \square & & & \\ & \square & & \\ & & \dots & \\ & & & \square \end{pmatrix}$$

$V_S^T \quad V_S \quad M_{S,S}$

Equivalent Formulation:

Reuse V to denote the matrix where its columns are the vectors in V

- Let M be the gram matrix $V^T V$
- Choose S such that $\det(M_{S,S})$ is maximized

$$M_{i,j} = v_i \cdot v_j$$

$$\det(M_{S,S}) = \text{Vol}(S)^2$$

What is known?

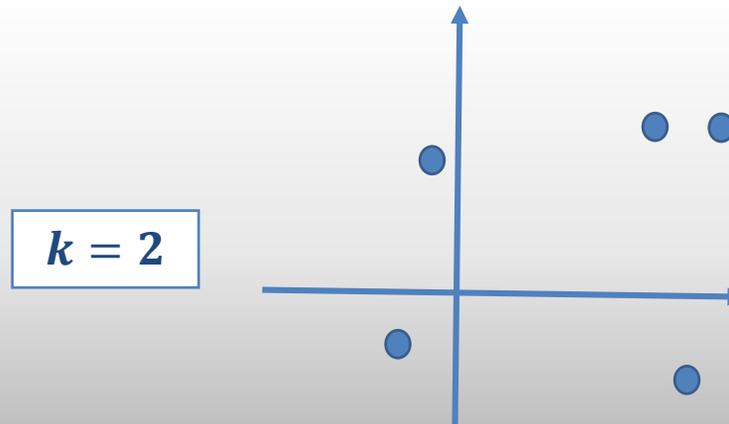
- Hard to approximate within a factor of 2^{ck} [CMI'13]

What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]

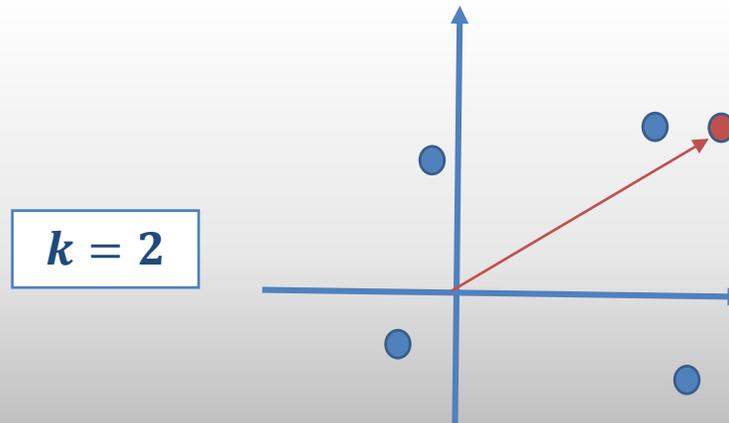
What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]
- **Greedy** is a popular algorithm: achieves approximation factor $k!$
 - $U \leftarrow \emptyset$
 - For k iterations,
 - Add to U the farthest point from the subspace spanned by U



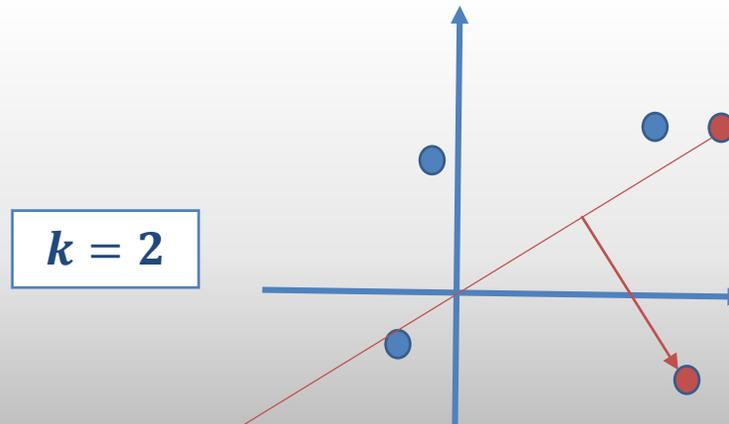
What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]
- **Greedy** is a popular algorithm: achieves approximation factor $k!$
 - $U \leftarrow \emptyset$
 - For k iterations,
 - Add to U the farthest point from the subspace spanned by U



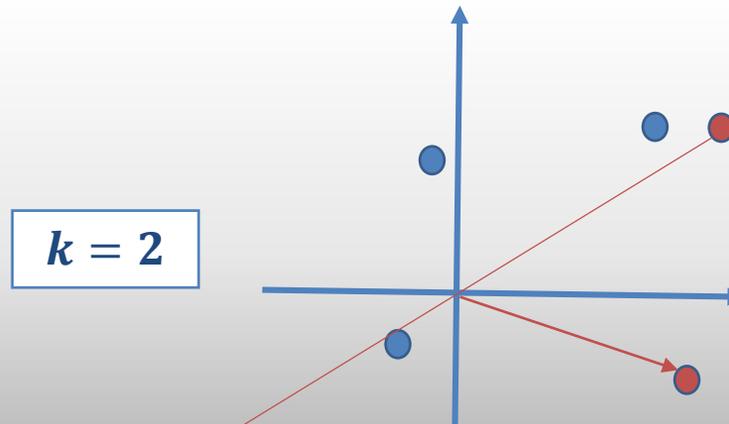
What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]
- **Greedy** is a popular algorithm: achieves approximation factor $k!$
 - $U \leftarrow \emptyset$
 - For k iterations,
 - Add to U the farthest point from the subspace spanned by U



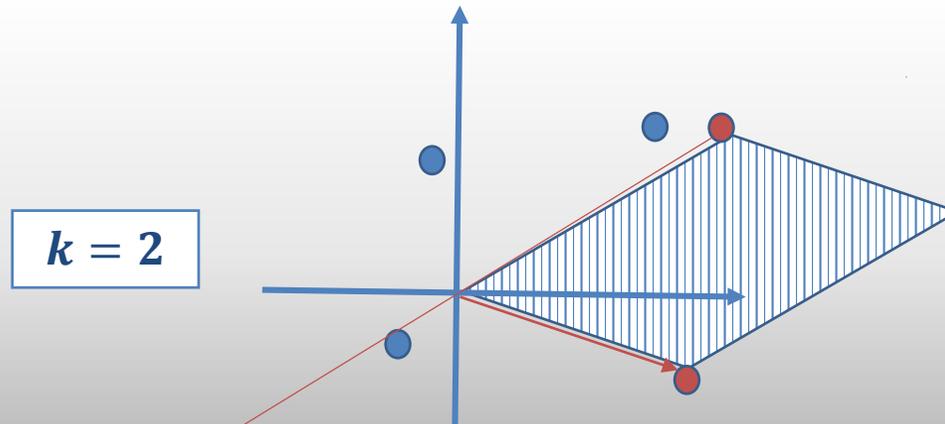
What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]
- **Greedy** is a popular algorithm: achieves approximation factor $k!$
 - $U \leftarrow \emptyset$
 - For k iterations,
 - Add to U the farthest point from the subspace spanned by U



What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]
- **Greedy** is a popular algorithm: achieves approximation factor $k!$
 - $U \leftarrow \emptyset$
 - For k iterations,
 - Add to U the farthest point from the subspace spanned by U

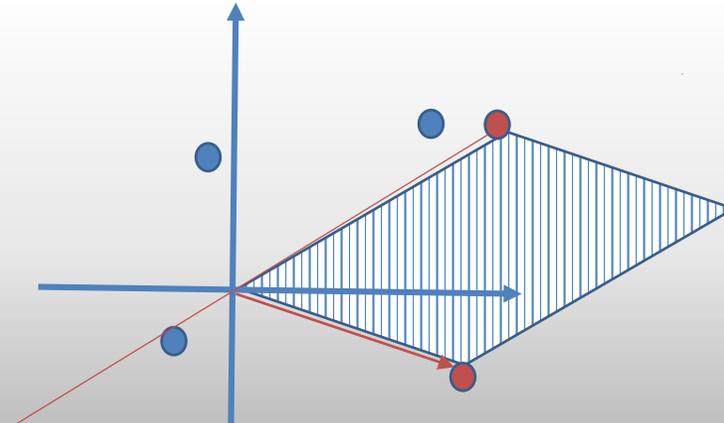


What is known?

- Hard to approximate within a factor of 2^{ck} [CMI'13]
- Best algorithm: e^k -approximation [Nik'15]
- **Greedy** is a popular algorithm: achieves approximation factor $k!$
 - $U \leftarrow \emptyset$
 - For k iterations,
 - Add to U the farthest point from the subspace spanned by U

- Greedy performs very well in practice

$k = 2$



Determinantal Point Processes (DPP)

DPP: Very popular probabilistic model, where given a set of vectors V , **samples** any k -subset S with probability proportional to this determinant.

- Maximum a posteriori (MAP) decoding is determinant maximization
- Volume/determinant is a notion of **diversity**

- **NeurIPS'18 Tutorial**, *Negative Dependence, Stable Polynomials, and All That*, Jegelka, Sra
- **ICML'19 Workshop**, *Negative Dependence: Theory and Applications in Machine Learning*, Gartrell, Gillenwater, Kulesza, Mariet

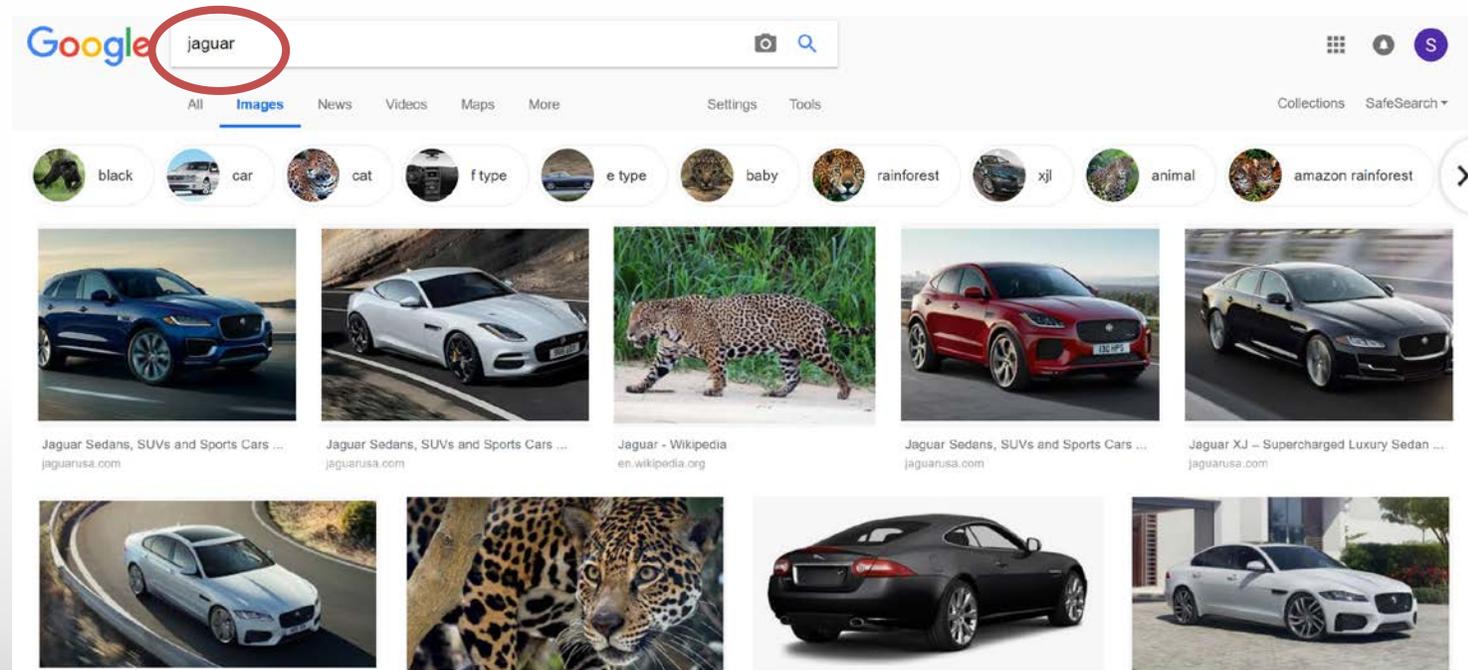
Application: Diversity Maximization

Given a set of objects, how to pick **a few** of them while maximizing **diversity**?

Application: Diversity Maximization

Given a set of objects, how to pick **a few** of them while maximizing **diversity**?

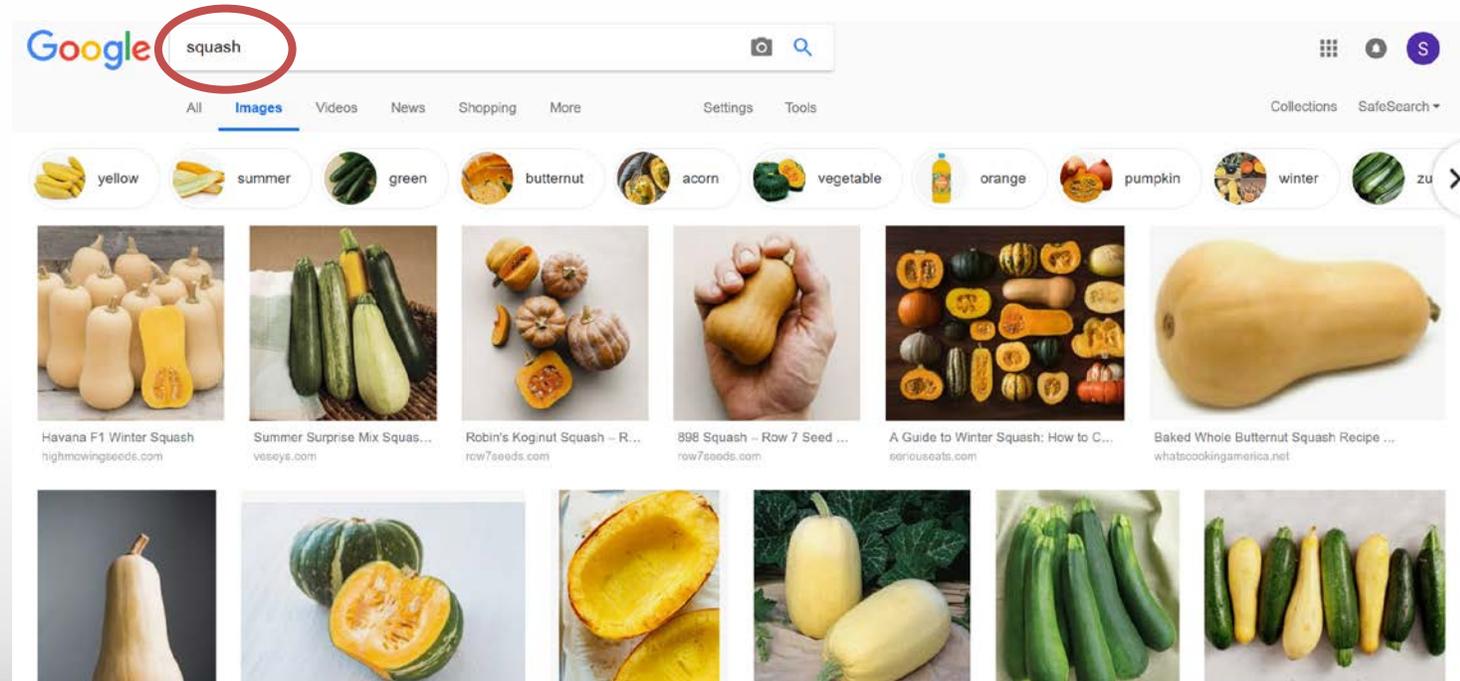
- Searching



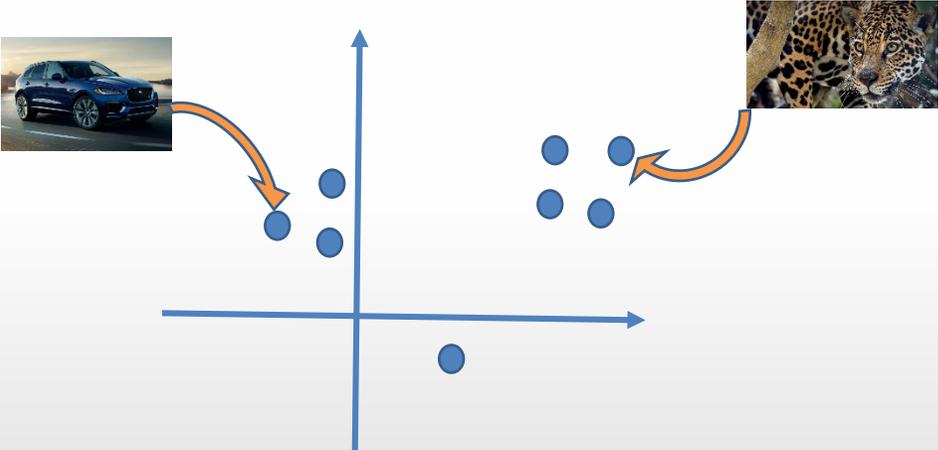
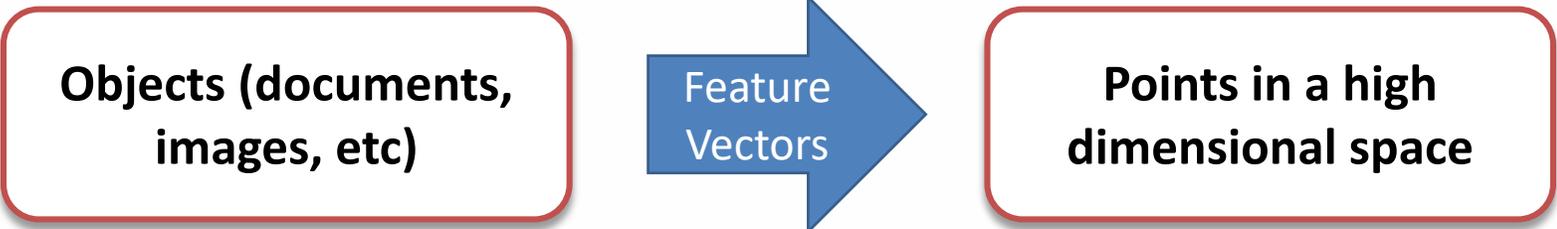
Application: Diversity Maximization

Given a set of objects, how to pick **a few** of them while maximizing **diversity**?

- Searching



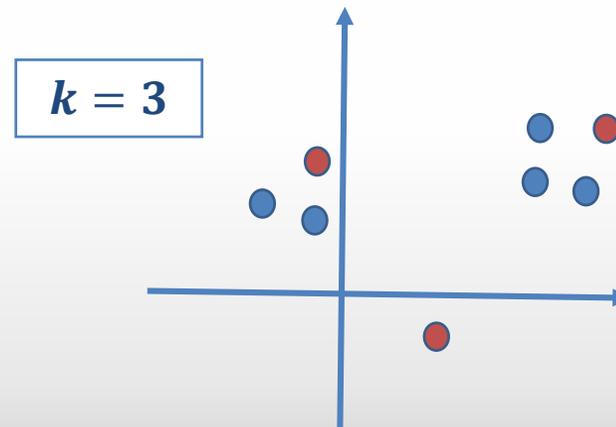
Application: Diversity Maximization



Application: Diversity Maximization

Input: a set of n vectors $V \subset \mathbb{R}^d$ and a parameter k ,

Goal: pick k points while maximizing “diversity”.



Determinantal Point Processes (DPP)

DPP: Very popular probabilistic model, where given a set of vectors V , **samples** any k -subset S with probability proportional to this determinant.

- Maximum a posteriori (MAP) decoding is determinant maximization
- Volume/determinant is a notion of **diversity**

Applications

[MJK'17,GCGS'14] Video summarization
[KT+'12, CGGS'15,KT'11] Document summarization
[YFZ+'16] Tweet generation
[LCYO'16] Object detection

....

Determinantal Point Processes (DPP)

DPP: Very popular probabilistic model, where given a set of vectors V , **samples** any k -subset S with probability proportional to this determinant.

- Maximum a posteriori (MAP) decoding is determinant maximization
- Volume/determinant is a notion of **diversity**



Applications

[MJK'17,GCGS'14] Video summarization
[KT+'12, CGGS'15,KT'11] Document summarization
[YFZ+'16] Tweet generation
[LCYO'16] Object detection
....

- 
- Most applications deal with **massive data**
 - Lots of effort for solving the problem in massive data models of computation [MJK'17, WIB'14, PJG+'14, MKSK'13, MKBK'15, MZ'15, MZ'15, BENW'15]
 - e.g. **streaming, distributed, parallel**

Determinantal Point Processes (DPP)

DPP: Very popular probabilistic model, where given a set of vectors V , **samples** any k -subset S with probability proportional to this determinant.

- Maximum a posteriori (MAP) decoding is determinant maximization
- Volume/determinant is a notion of **diversity**

Applications

[MJK'17,GCGS'14] Video summarization
[KT+'12, CGGS'15,KT'11] Document summarization
[YFZ+'16] Tweet generation
[LCYO'16] Object detection
....

- Most applications deal with **massive data**
- Lots of effort for solving the problem in massive data models of computation [MJK'17, WIB'14, PJG+'14, MKSK'13, MKBK'15, MZ'15, MZ'15, BENW'15]
- e.g. **streaming, distributed, parallel**

Composable Core-sets

Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Solving the problem over U gives a good approximation of solving the problem over V

Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The union of coresets is a coreset for the union

Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The **union of coresets** is a **coreset for the union**

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization

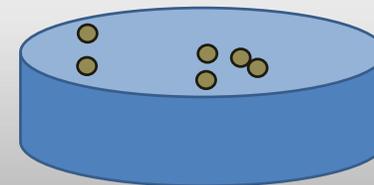
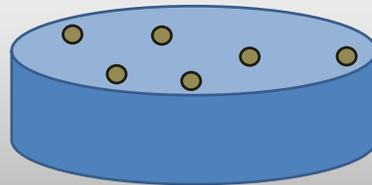
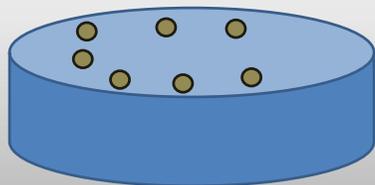
Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The **union of coresets** is a **coreset for the union**

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization
- Multiple data sets V_1, \dots, V_m and their coresets $U_1 \subset V_1, \dots, U_m \subset V_m$,
 - $f(U_1 \cup \dots \cup U_m)$ approximates $f(V_1 \cup \dots \cup V_m)$ by a factor α



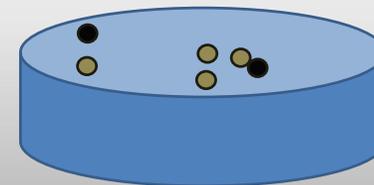
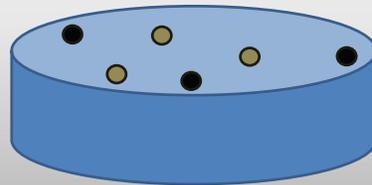
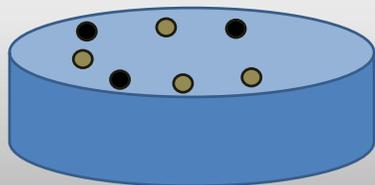
Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The **union of coresets** is a **coreset for the union**

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization
- Multiple data sets V_1, \dots, V_m and their coresets $U_1 \subset V_1, \dots, U_m \subset V_m$,
 - $f(U_1 \cup \dots \cup U_m)$ approximates $f(V_1 \cup \dots \cup V_m)$ by a factor α



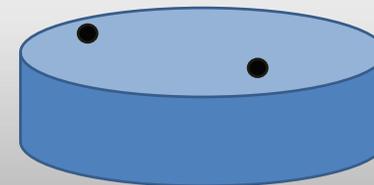
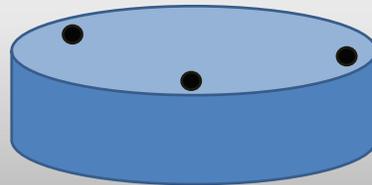
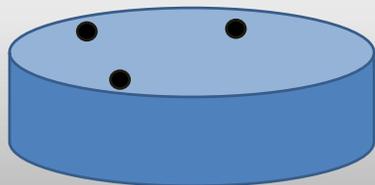
Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The **union of coresets** is a **coreset for the union**

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization
- Multiple data sets V_1, \dots, V_m and their coresets $U_1 \subset V_1, \dots, U_m \subset V_m$,
 - $f(U_1 \cup \dots \cup U_m)$ approximates $f(V_1 \cup \dots \cup V_m)$ by a factor α



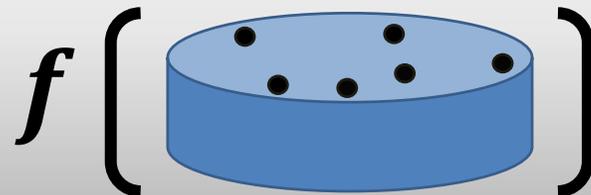
Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The **union of coresets** is a **coreset for the union**

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization
- Multiple data sets V_1, \dots, V_m and their coresets $U_1 \subset V_1, \dots, U_m \subset V_m$,
 - $f(U_1 \cup \dots \cup U_m)$ approximates $f(V_1 \cup \dots \cup V_m)$ by a factor α



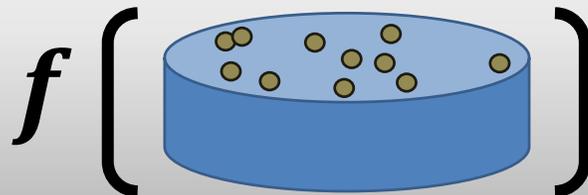
Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The union of coresets is a coreset for the union

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization
- Multiple data sets V_1, \dots, V_m and their coresets $U_1 \subset V_1, \dots, U_m \subset V_m$,
 - $f(U_1 \cup \dots \cup U_m)$ approximates $f(V_1 \cup \dots \cup V_m)$ by a factor α



Composable Core-sets

Core-sets [AHV'05]: a subset U of the data V that represents it well

Composable Core-sets [AAIMV'13 and IMMM'14]:

The **union of coresets** is a **coreset for the union**

- Let f be an optimization function
 - E.g. $f(V)$: solution to k determinant maximization
- Multiple data sets V_1, \dots, V_m and their coresets $U_1 \subset V_1, \dots, U_m \subset V_m$,
 - $f(U_1 \cup \dots \cup U_m)$ approximates $f(V_1 \cup \dots \cup V_m)$ by a factor α

- ✓ Composable Core-sets have been studied for the **diversity Maximization** problems, for other notions of diversity: **minimum pairwise distance**, **sum of pairwise distances**, etc.
- ✓ Determinant maximization is a “higher order” notion of diversity

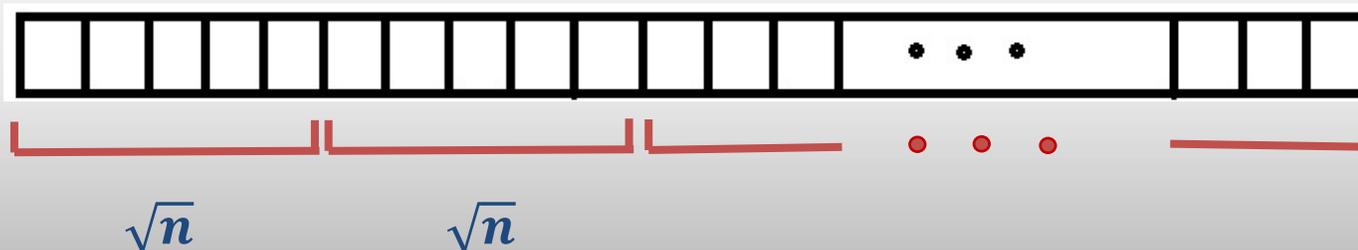
Applications: Streaming Computation

- **Streaming Computation:**
 - Processing sequence of n data elements “on the fly”
 - limited Storage



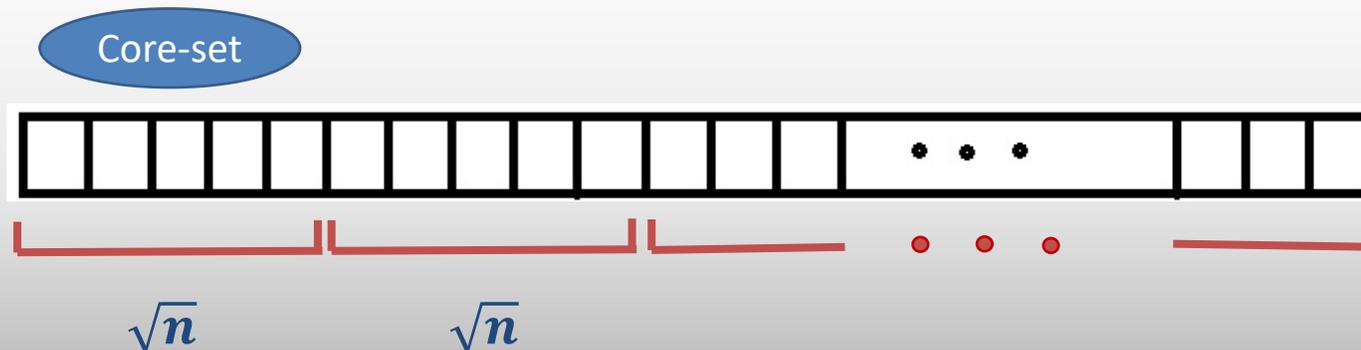
Applications: Streaming Computation

- **Streaming Computation:**
 - Processing sequence of n data elements “on the fly”
 - limited Storage
- **Composable Core-set**
 - Divide into chunks



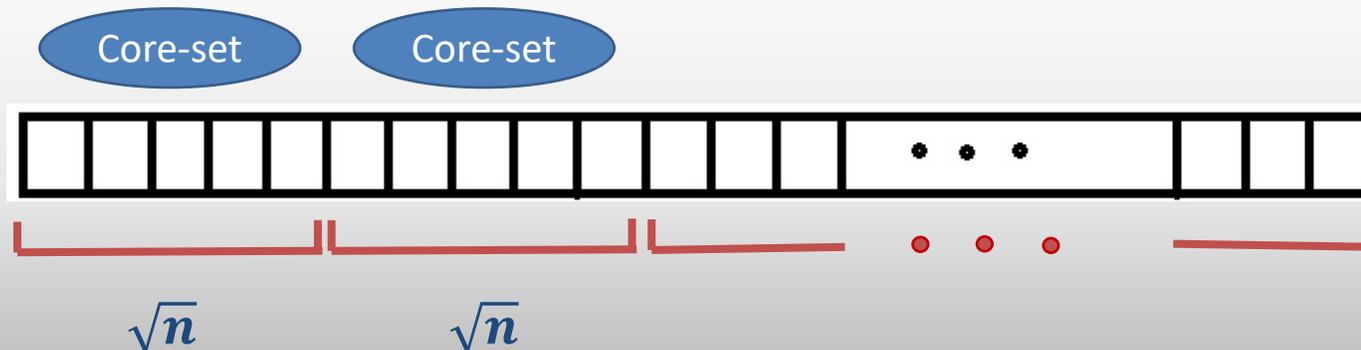
Applications: Streaming Computation

- **Streaming Computation:**
 - Processing sequence of n data elements “on the fly”
 - limited Storage
- **Composable Core-set**
 - Divide into chunks
 - Compute Core-set for each chunk as it arrives



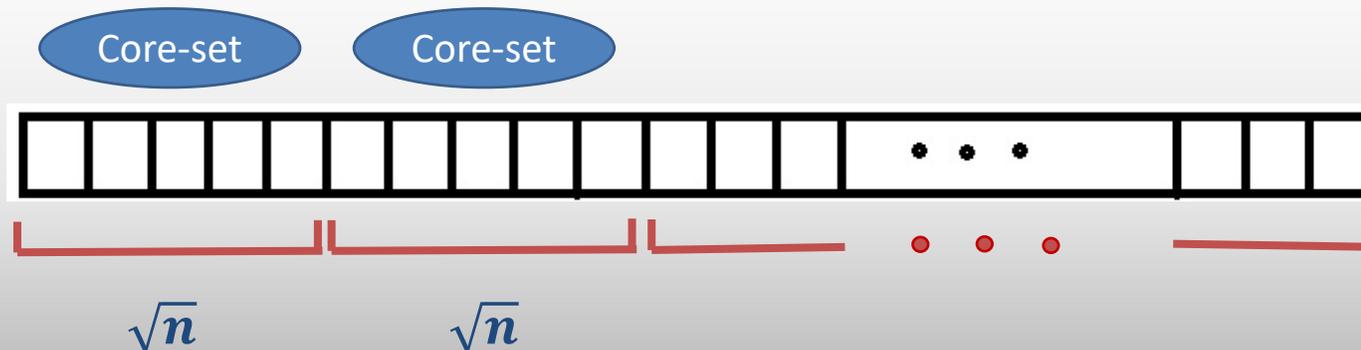
Applications: Streaming Computation

- **Streaming Computation:**
 - Processing sequence of n data elements “on the fly”
 - limited Storage
- **Composable Core-set**
 - Divide into chunks
 - Compute Core-set for each chunk as it arrives



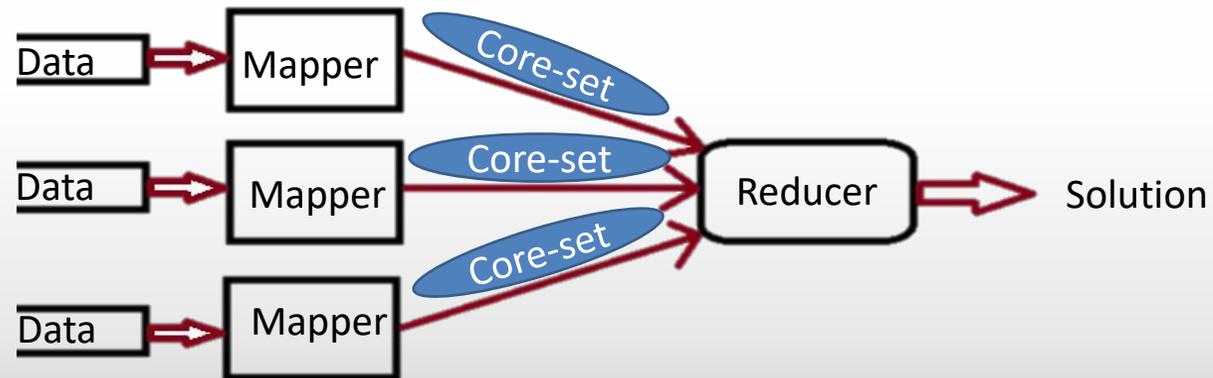
Applications: Streaming Computation

- **Streaming Computation:**
 - Processing sequence of n data elements “on the fly”
 - limited Storage
- **Composable Core-set**
 - Divide into chunks
 - Compute Core-set for each chunk as it arrives
 - Space goes down from n to \sqrt{n}



Applications: Distributed Computation

- Streaming Computation
- **Distributed System:**
 - Each machine holds a block of data.
 - A composable core-set is computed and sent to the server



Applications: Improving Runtime

- Streaming Computation
- Distributed System
- **Similar framework for improving the runtime**

Can we get a composable core-set of small size
for the determinant maximization problem?

Composable Core-sets for Volume Maximization

		[IMOR'18]
Approximation		$\tilde{O}(k)^{k/2}$
Core-set Size		$\tilde{O}(k)$
Simple?		×

LP-based Optimal Approximation Algorithm of [IMOR'18]:

There exists a polynomial time algorithm for computing an $\tilde{O}(k)^{k/2}$ -composable core-set of size $\tilde{O}(k)$ for the volume maximization problem.

Composable Core-sets for Volume Maximization

	Lower Bound	[IMOR'18]
Approximation	$\Omega(k)^{\frac{k}{2}-o(k)}$	$\tilde{O}(k)^{\frac{k}{2}}$
Core-set Size	$k^{O(1)}$	$\tilde{O}(k)$
Simple?		×

Lower bound [IMOR'18]:

Any composable core-set of size $k^{O(1)}$ for the volume maximization problem must have an approximation factor of $\Omega(k)^{\frac{k}{2}(1-o(1))}$.

Our Results

	Lower Bound	[IMOR'18]	Greedy
Approximation	$\Omega(k)^{\frac{k}{2}-o(k)}$	$\tilde{O}(k)^{\frac{k}{2}}$	$O(C^{k^2})$
Core-set Size	$k^{O(1)}$	$\tilde{O}(k)$	k
Simple?		×	✓

The widely used Greedy algorithm produces a composable core-set of size k with approximation factor $O(C^{k^2})$.

Our Results

	Lower Bound	[IMOR'18]	Greedy	Local Search
Approximation	$\Omega(k)^{\frac{k}{2}-o(k)}$	$\tilde{O}(k)^{\frac{k}{2}}$	$O(C^{k^2})$	$O(k^k)$
Core-set Size	$k^{O(1)}$	$\tilde{O}(k)$	k	k
Simple?		×	✓	✓

The Local Search Algorithm produces a composable core-set of size k with approximation factor $O(k)^{2k}$.

This Talk

The Local Search Algorithm produces a composable core-set of size k with approximation factor $O(k)^k$ for the volume maximization problem.

This Talk

The Local Search Algorithm produces a composable core-set of size k with approximation factor $O(k)^k$ for the volume maximization problem.

In comparison to the optimal core-set algorithm

- Approximation $O(k)^k$ as opposed to $O(k \log k)^{k/2}$
- **Smaller Size** k as opposed to $O(k \log k)$
- **Simpler** to implement (similar to Greedy)
- **Better** performance **in practice**

The Local Search Algorithm

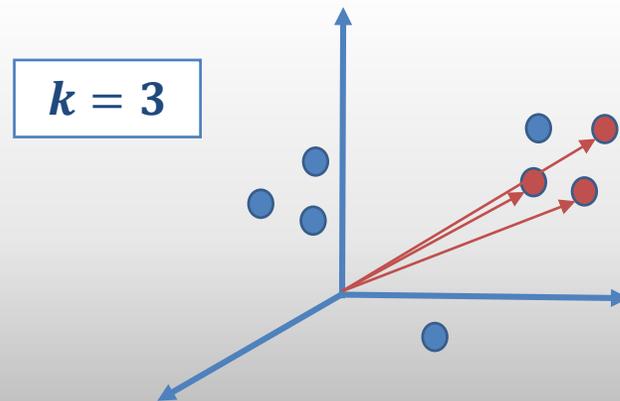
Input: a set V of n points and a parameter k

1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p increases the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$

The Local Search Algorithm

Input: a set V of n points and a parameter k

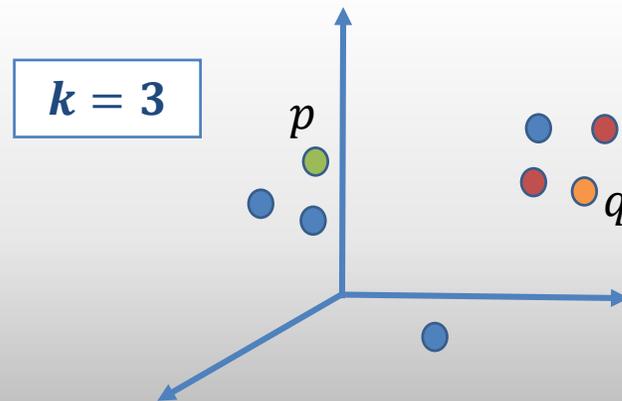
1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p increases the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$



The Local Search Algorithm

Input: a set V of n points and a parameter k

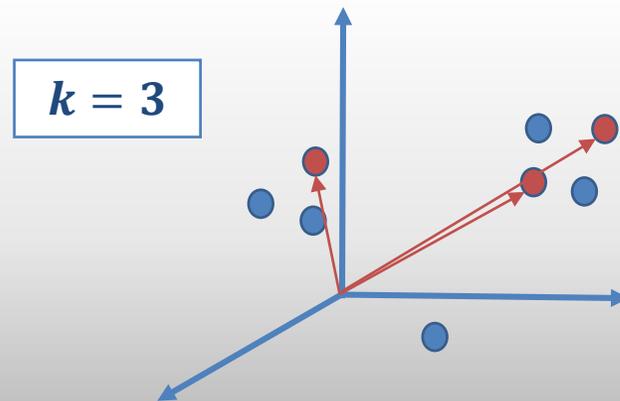
1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p increases the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$



The Local Search Algorithm

Input: a set V of n points and a parameter k

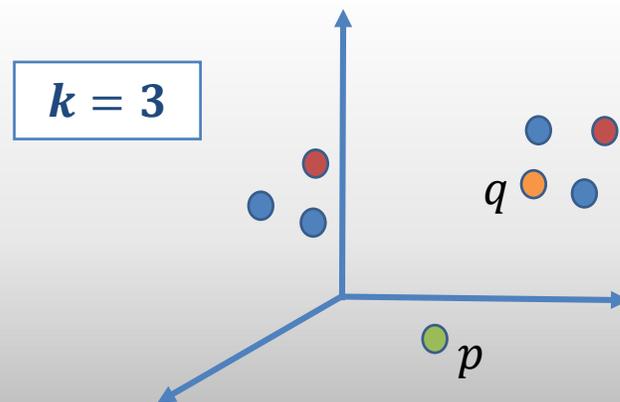
1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p increases the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$



The Local Search Algorithm

Input: a set V of n points and a parameter k

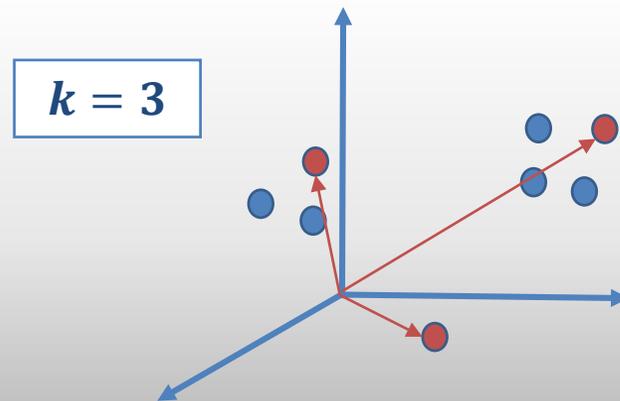
1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p increases the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$



The Local Search Algorithm

Input: a set V of n points and a parameter k

1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p increases the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$



To bound the run time

Input: a set V of n points and

Start with a crude approximation
(Greedy algorithm)

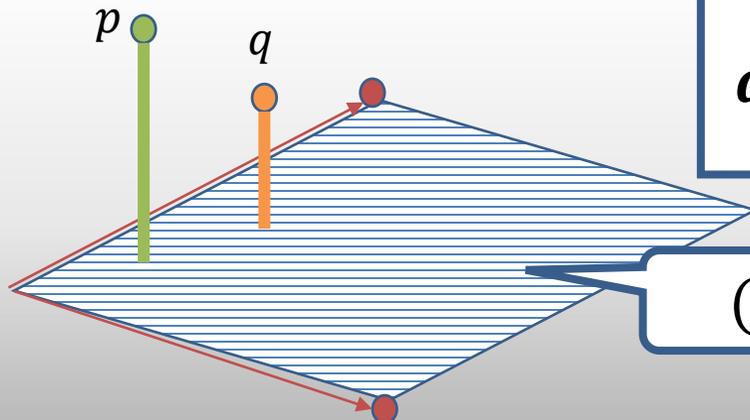
1. Start with an **arbitrary** subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p **increases** the volume, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$

If it increases by at least a factor of
 $(1 + \epsilon)$

Checking the condition

Input: a set V of n points and a parameter k

1. Start with an arbitrary subset of k points $S \subseteq V$
2. While there exists a point $p \in V \setminus S$ and $q \in S$ s.t. replacing q with p **increases the volume**, then swap them, i.e., $S = S \cup \{p\} \setminus \{q\}$



$$\text{dist}(p, H_{S \setminus \{q\}}) > \text{dist}(q, H_{S \setminus \{q\}})$$

$(k - 1)$ -dimensional Subspace

Main Lemma [informal]:

Local Search preserves **maximum distance** to “all” subspaces of dimension **$k - 1$**

Main Lemma [informal]:

Local Search preserves **maximum distance** to “all” subspaces of dimension $k - 1$

- V is the point set
- $S = LS(V)$ is the core-set produced by local search

Main Lemma [informal]:

Local Search preserves **maximum distance** to “all” subspaces of dimension $k - 1$

- V is the point set
- $S = LS(V)$ is the core-set produced by local search

Main Lemma [formal]:

For any $(k - 1)$ -dimensional subspace G , the **maximum distance** of the point set to G is approximately preserved

$$\max_{q \in S} \text{dist}(q, G) \geq \frac{1}{2k} \cdot \max_{p \in V} \text{dist}(p, G)$$

Main Lemma [formal]:

For any $(k - 1)$ -dimensional subspace G , the maximum distance of the point set to G is approximately preserved

$$\max_{s \in S} \text{dist}(s, G) \geq \frac{1}{2k} \cdot \max_{p \in V} \text{dist}(p, G)$$

- Let $p \in V$ be a point

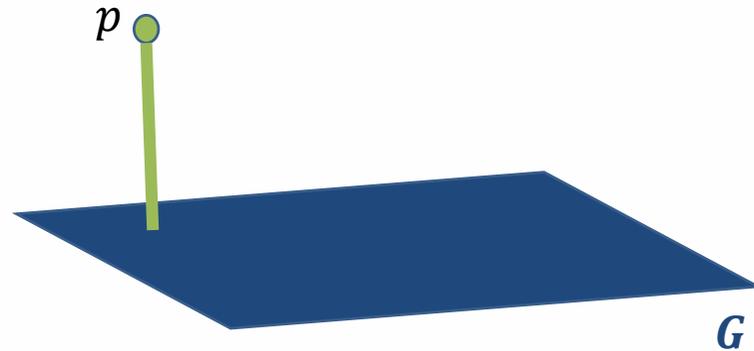
p ●

Main Lemma [formal]:

For any $(k - 1)$ -dimensional subspace G , the maximum distance of the point set to G is approximately preserved

$$\max_{s \in S} \text{dist}(s, G) \geq \frac{1}{2k} \cdot \max_{p \in V} \text{dist}(p, G)$$

- Let $p \in V$ be a point
- Let G be a $(k - 1)$ -dimensional subspace.

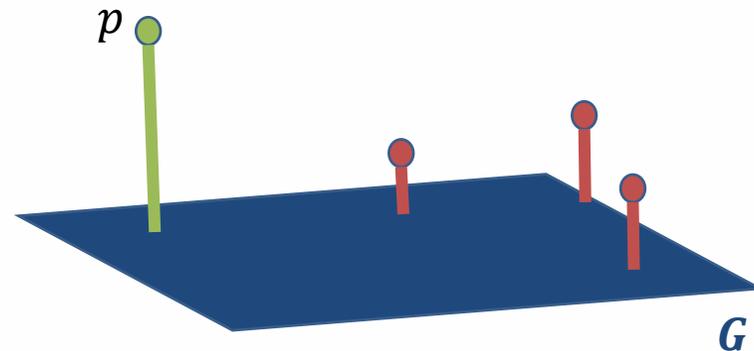


Main Lemma [formal]:

For any $(k - 1)$ -dimensional subspace G , the maximum distance of the point set to G is approximately preserved

$$\max_{s \in S} \text{dist}(q, G) \geq \frac{1}{2k} \cdot \max_{p \in V} \text{dist}(p, G)$$

- Let $p \in V$ be a point
- Let G be a $(k - 1)$ -dimensional subspace.
- Assume for any $q \in S$, $d(q, G) \leq x$

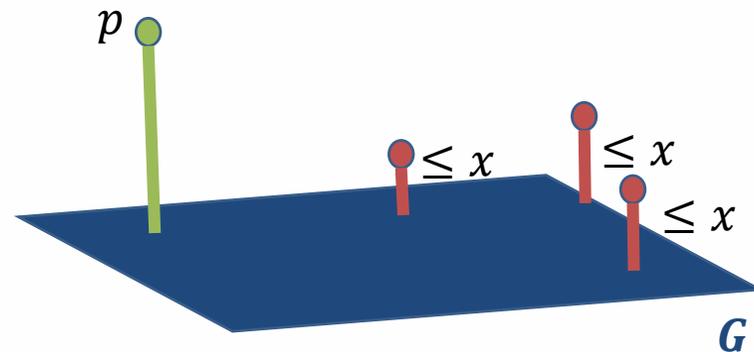


Main Lemma [formal]:

For any $(k - 1)$ -dimensional subspace G , the maximum distance of the point set to G is approximately preserved

$$\max_{s \in S} \text{dist}(q, G) \geq \frac{1}{2k} \cdot \max_{p \in V} \text{dist}(p, G)$$

- Let $p \in V$ be a point
- Let G be a $(k - 1)$ -dimensional subspace.
- Assume for any $q \in S$, $d(q, G) \leq x$



Main Lemma [formal]:

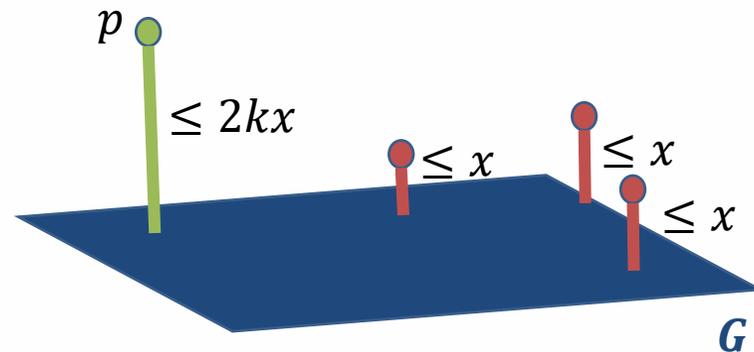
For any $(k - 1)$ -dimensional subspace G , the maximum distance of the point set to G is approximately preserved

$$\max_{s \in S} \text{dist}(q, G) \geq \frac{1}{2k} \cdot \max_{p \in V} \text{dist}(p, G)$$

- Let $p \in V$ be a point
- Let G be a $(k - 1)$ -dimensional subspace.
- Assume for any $q \in S$, $d(q, G) \leq x$

• **Lemma:**

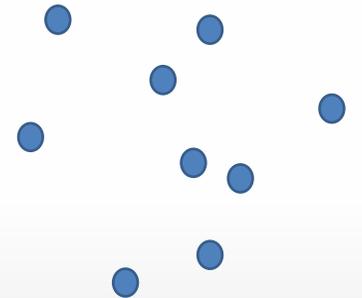
$$d(p, G) \leq 2kx$$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

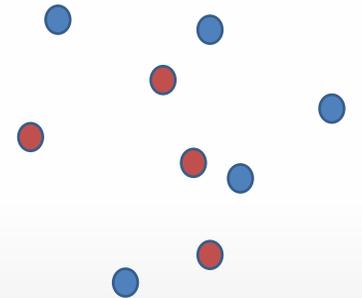


Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

Let $S = \cup_i S_i$ be the union of core-sets



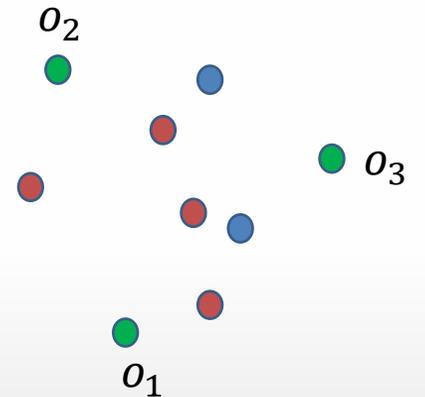
Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

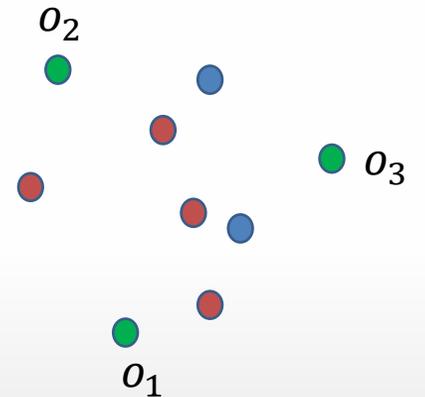
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

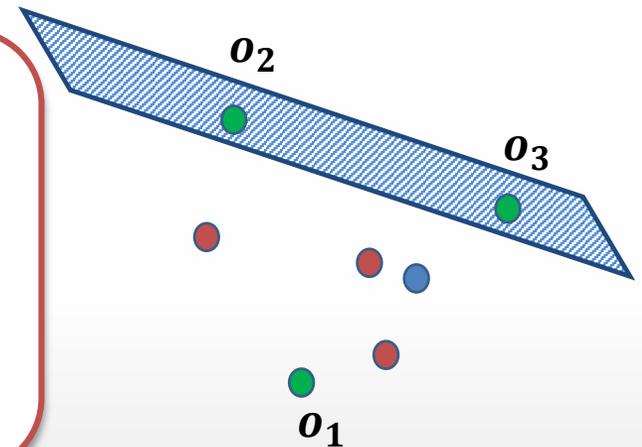
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

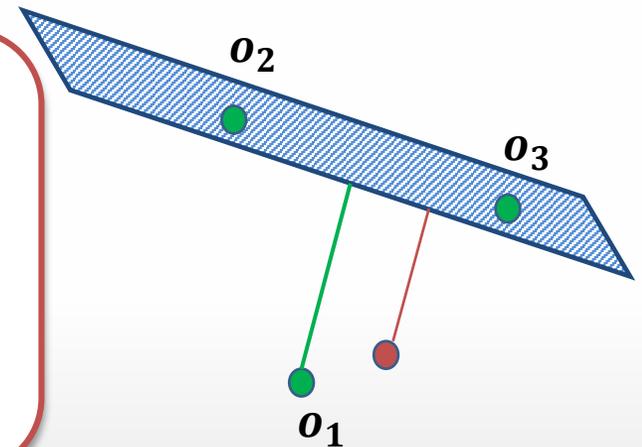
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

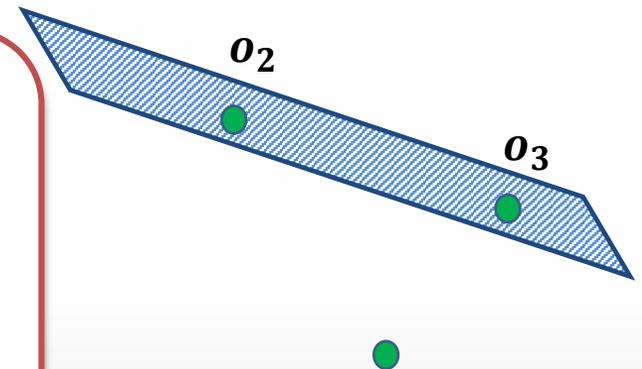
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

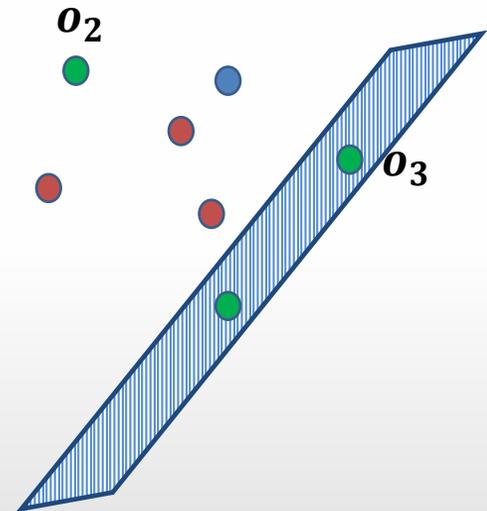
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

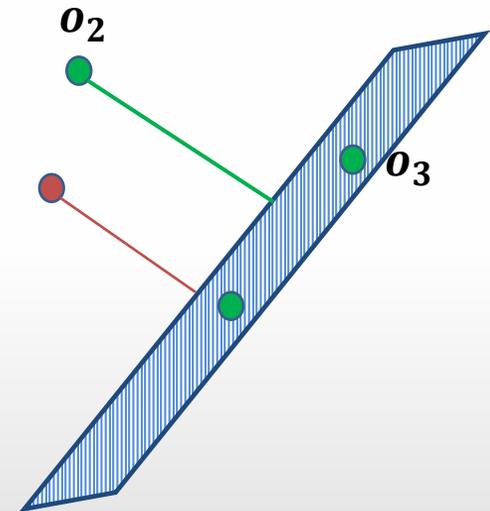
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

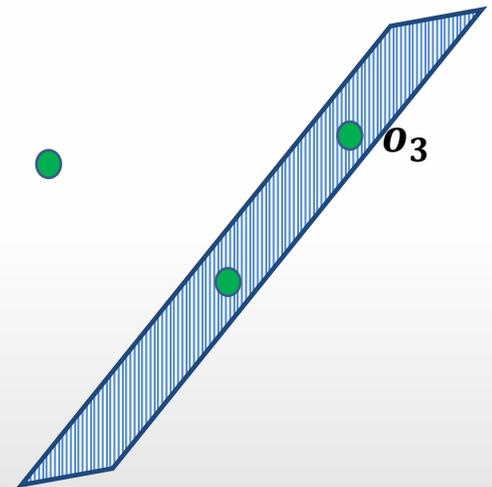
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

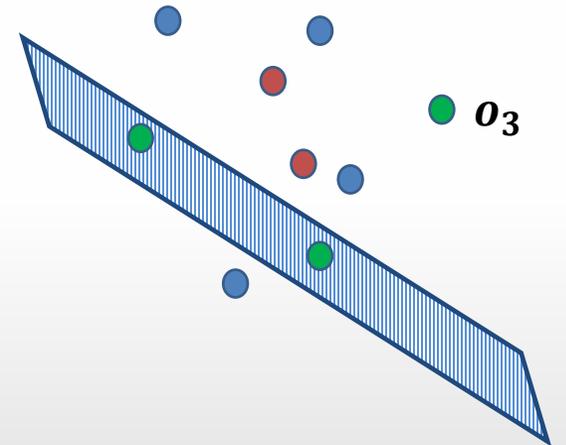
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

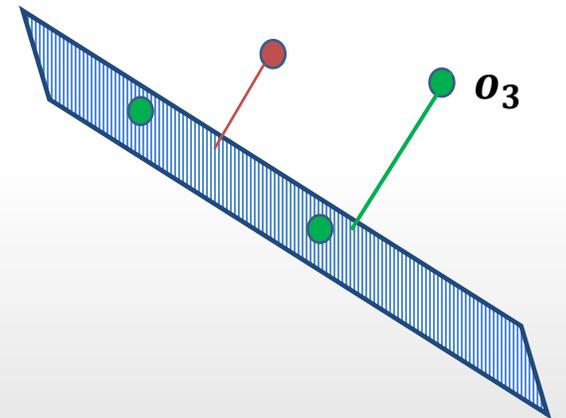
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

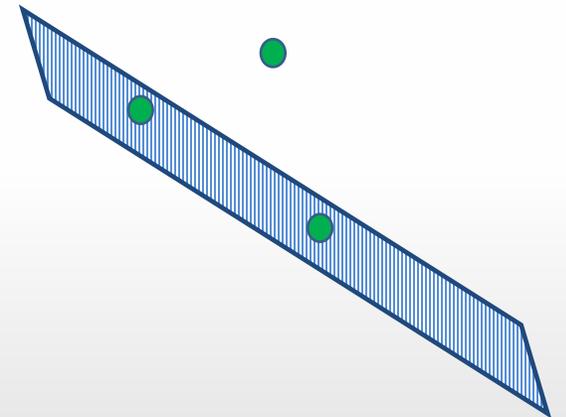
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

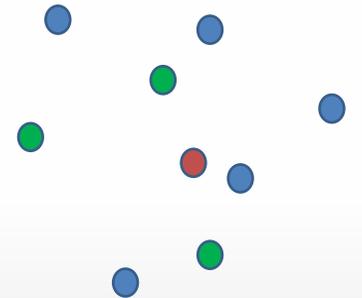
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

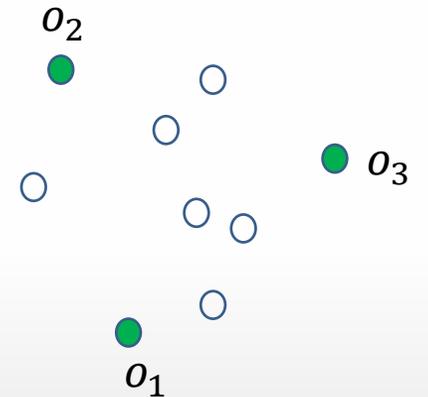
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

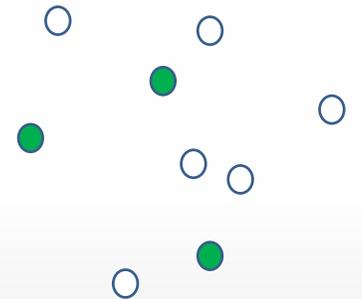
Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \bigcup_i V_i$ be the union of the point sets

Let $S = \bigcup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest from Sol
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$

Since local search preserve maximum distances to subspaces

➤ Lose a factor of at most $2k$ at each iteration



Main Theorem

Local Search produces a core-set for volume maximization

Let $V = \cup_i V_i$ be the union of the point sets

Let $S = \cup_i S_i$ be the union of core-sets

Let $Opt = \{o_1, \dots, o_k\} \subset V$ be the optimal subset of points maximizing the volume

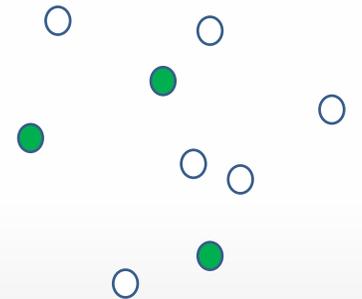
$Sol \leftarrow Opt$

For $i = 1$ to k

- Let $q_i \in S$ be the point that is farthest away from $H_{Sol \setminus \{o_i\}}$
- $Sol \leftarrow Sol \cup \{q_i\} \setminus \{o_i\}$

➤ Lose a factor of at most $2k$ at each iteration

➤ Total approximation factor $(2k)^k$



Empirical Results

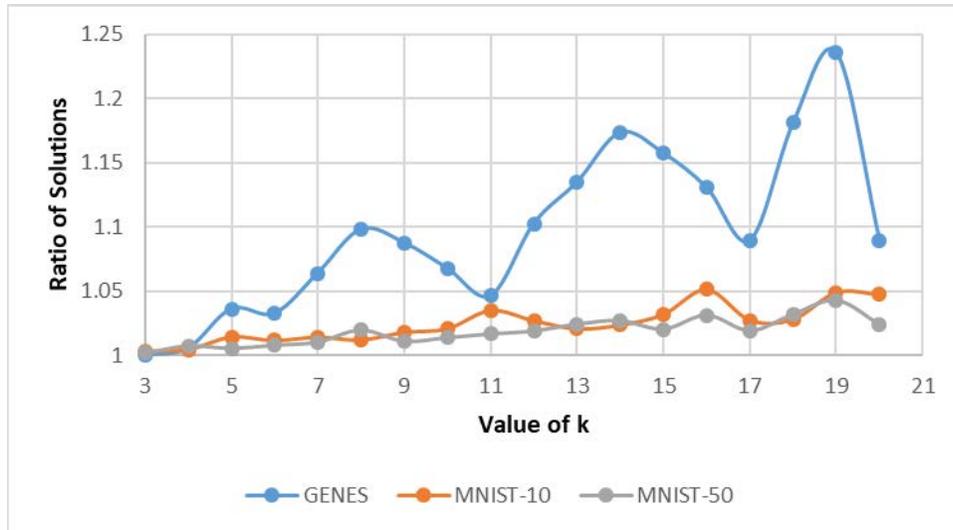
Data Set

- MNIST, with number of parts = 10
- MNIST, with number of parts = 50
- GENES, with number of parts = 10

Process

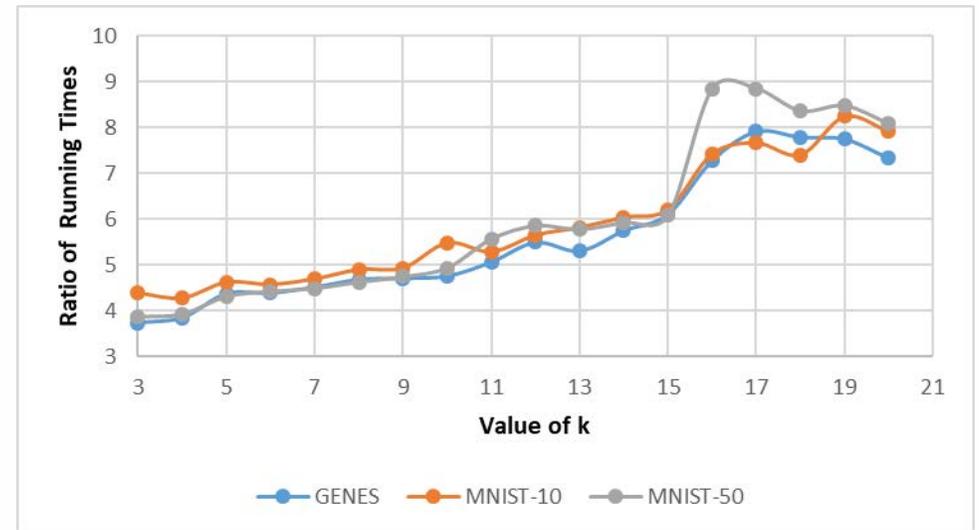
- Partition the data set randomly into parts
- Compute a core-set using one of the algorithms: **Greedy, Local Search, LP-Based algorithm of [IMOR'18]**
- Use greedy on the union of the coresets

Local Search vs Greedy



Improvement of the solution of Local Search over Greedy

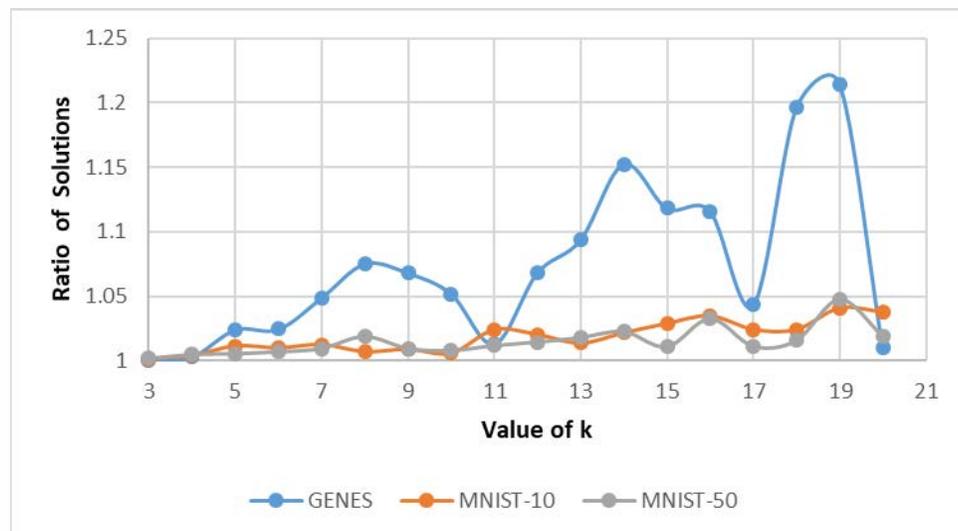
- On average, 1.2%, 2.5%, and 9.6% improvement
- Some cases up to 58% improvement



Ratio of runtime of Local Search over Greedy

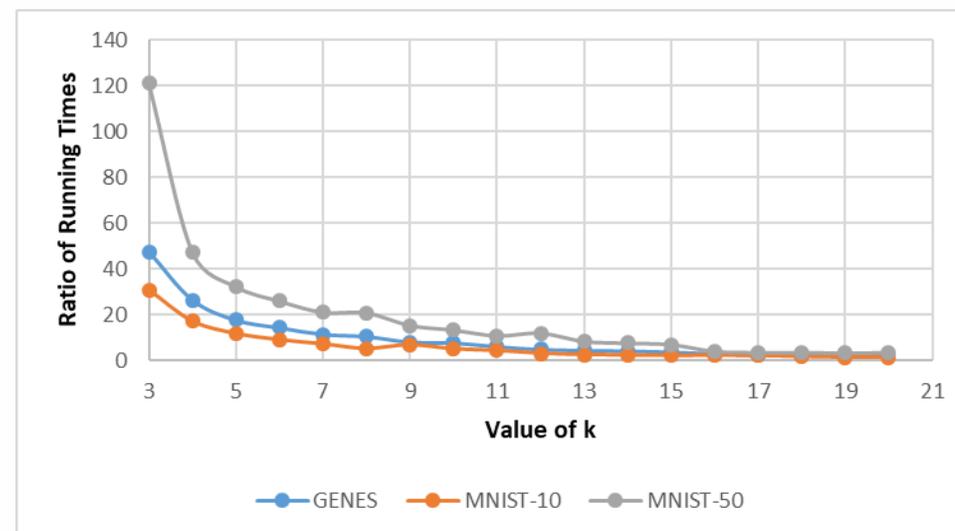
- On average, 6 times slower

Local Search vs. LP-based Algorithm of [IMOR'18]



Improvement of the solution of Local Search over [IMOR'18]

- On average, 1.4%, 1.8%, and 7.3% improvement
- Some cases up to 63% improvement



Ratio of runtime of Local Search over [IMOR'18]

- For lower values of k, Local Search is up to 50 times faster.

Summary

- Volume/Determinant Maximization Problem
- Notion of composable core-sets
- Algorithms that find composable core-sets for volume/determinant maximization

	[IMOR'18]	Greedy	Local Search
Approximation	$O(k \log k)^{k/2}$	$O(C^{k^2})$	$O(k^k)$
Core-set Size	$O(k \log k)$	k	k
Simple?	×	✓	✓
Empirical Approximation			Performs Best
Empirical Runtime	Slowest	Fastest	4 times slower than Greedy.

Summary

- Volume/Determinant Maximization Problem
- Notion of composable core-sets
- Algorithms that find composable core-sets for volume/determinant maximization

	[IMOR'18]	Greedy	Local Search
Approximation	$O(k \log k)^{k/2}$	$O(C^{k^2})$	$O(k^k)$
Core-set Size	$O(k \log k)$	k	k
Simple?	×	✓	✓
Empirical Approximation			Performs Best
Empirical Runtime	Slowest	Fastest	4 times slower than Greedy.

Conclusion

- Local Search might be the right algorithm to use in massive data models of computation.

Summary

- Volume/Determinant Maximization Problem
- Notion of composable core-sets
- Algorithms that find composable core-sets for volume/determinant maximization

	[IMOR'18]	Greedy	Local Search
Approximation	$O(k \log k)^{k/2}$	$O(C^{k^2})$	$O(k^k)$
Core-set Size	$O(k \log k)$	k	k
Simple?	×	✓	✓
Empirical Approximation			Performs Best
Empirical Runtime	Slowest	Fastest	4 times slower than Greedy.

Conclusion

- Local Search might be the right algorithm to use in massive data models of computation.

Open Problem

- Tight analysis of Greedy: does it also provide approximation $k^{O(k)}$?

THANK YOU!

Poster #81

Summary

- Volume/Determinant Maximization Problem
- Notion of composable core-sets
- Algorithms that find composable core-sets for volume/determinant maximization

	[IMOR'18]	Greedy	Local Search
Approximation	$O(k \log k)^{k/2}$	$O(C^{k^2})$	$O(k^k)$
Core-set Size	$O(k \log k)$	k	k
Simple?	×	✓	✓
Empirical Approximation			Performs Best
Empirical Runtime	Slowest	Fastest	4 times slower than Greedy.

Conclusion

- Local Search might be the right algorithm to use in massive data models of computation.

Open Problem

- Tight analysis of Greedy: does it also provide approximation $k^{O(k)}$?