

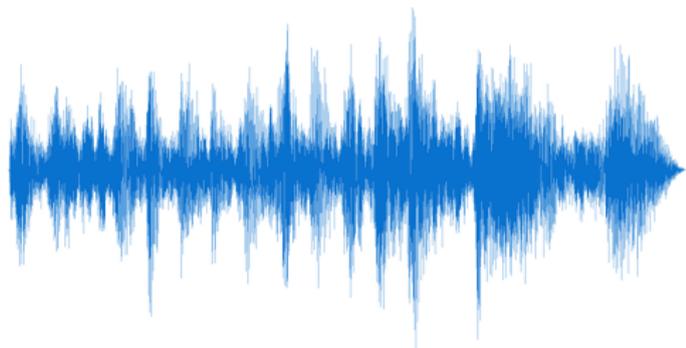
# Latent Normalizing Flows for Discrete Sequences

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**Poster #3** @ Pacific Ballroom

# Motivation: Normalizing flows



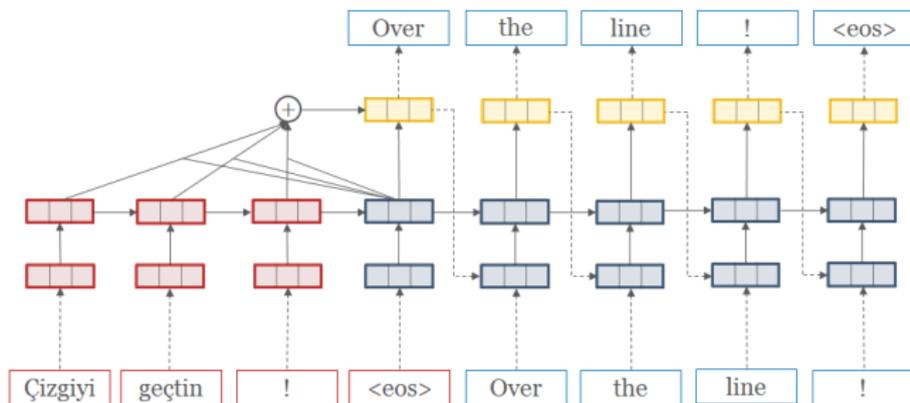
For invertible  $f_\theta : \epsilon \rightarrow \mathcal{Z}$  and base density  $p_\epsilon(\epsilon)$ ,

$$p_{\mathcal{Z}}(z) = p_\epsilon(f_\theta^{-1}(z)) \left| \det \frac{\partial f_\theta^{-1}(z)}{\partial z} \right|$$

- Flows generalize autoregressive models for continuous data, allowing **increased model flexibility** and **non-autoregressive generation**.

Kingma and Dhariwal 2018, van den Oord et al. 2017, Rezende and Mohamed 2015

# Goal: Flows for discrete data

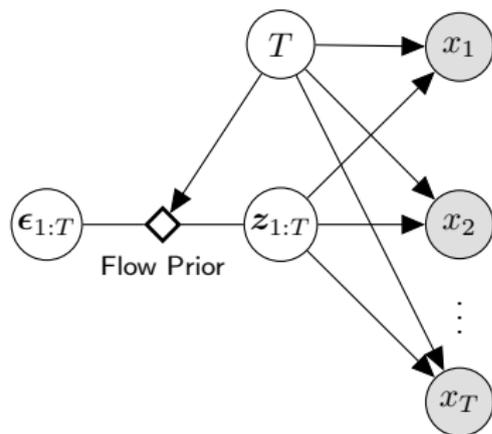


- For discrete sequences MLE autoregressive models are ubiquitous. Can flows go beyond AR models for discrete sequences?

Figure: OpenNMT

# Challenges and approach

- 1 Discrete change of variables poses theoretical and practical challenges compared to continuous change of variables.

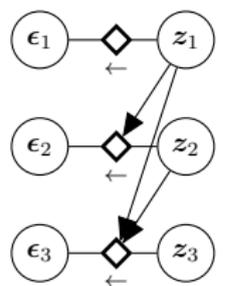


$$\mathbf{x} \in \mathcal{V}^T \quad \mathbf{z} \in \mathcal{R}^{T \times H}$$

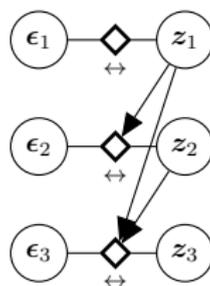
- Latent variable model where prior  $p(\mathbf{z}_{1:T})$  captures dynamics of discrete data over time.
- Key: weak conditionally independent emission model.
- VAE for inference, optimize ELBO.

# Challenges and approach

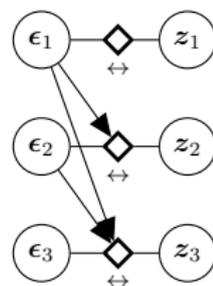
- 1 Discrete change of variables poses theoretical and practical challenges compared to continuous.
- 2 Discrete data is inherently highly multimodal.
- 3 Specialized flows for multimodal sequences:
  - Model dependencies across dimension and across time.



Autoregressive ( $\leftarrow$ )



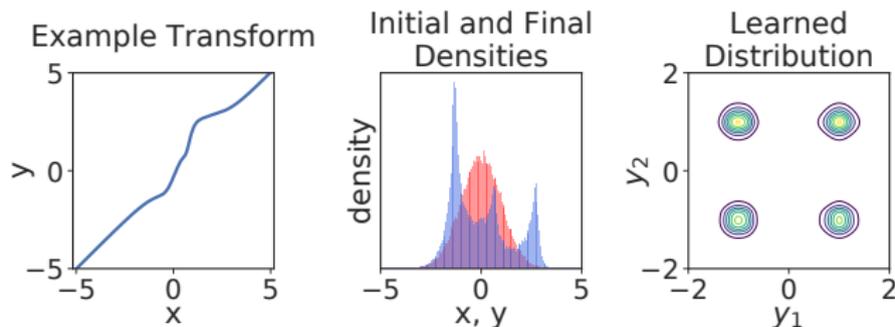
Autoregressive  
in time ( $\leftrightarrow$ )



Non-autoregressive ( $\rightarrow$ )

# Challenges and approach

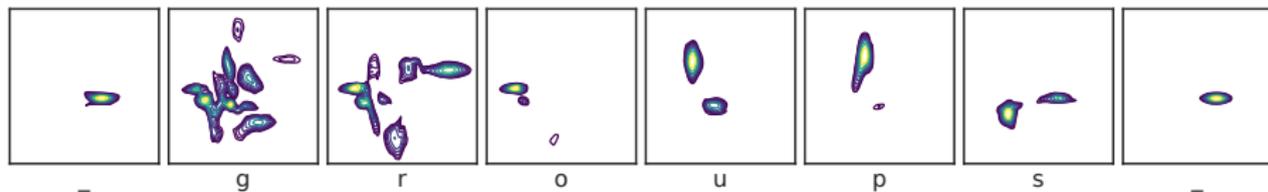
- 1 Discrete change of variables poses theoretical and practical challenges compared to continuous.
- 2 Discrete data is inherently highly multimodal.
- Specialized flows for multimodal sequences:
  - Model dependencies across dimension and across time.
  - Replace underlying affine transformation with non-linear transformation.



# Experiments: Character-level LM, PTB

Model	Test NLL	Reconst.	KL
LSTM	<b>1.41</b>	-	-
Independent-across-time flow	2.90	0.15	2.77
Autoregressive ( $\leftarrow$ )	<b>1.42</b>	0.10	<b>1.37</b>
Autoregressive in time ( $\leftarrow$ )	1.46	0.10	1.43
Non-autoregressive ( $\rightarrow$ )	1.63	0.21	1.55

- KL always makes up  $> 90\%$  of loss, indicating continuous flow models vast majority of uncertainty.
- Additional experiments on polyphonic music generation.



# Conclusions

- Latent variable model for discrete sequences modeling discrete dynamics in continuous latent space with continuous flows.
- See poster for details of approach, more experimental results, and generation speed comparison.

**Poster #3** @ Pacific Ballroom, for details and more experiments