

Amortized Monte Carlo Integration

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$$\mathbb{E}_{p(x|y)} [f(x; \theta)]$$



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AMCI = novel estimator +

$$\mathbb{E}_{p(x|y)} [f(x; \theta)]$$

AMCI = novel estimator + amortization objectives

Importance Sampling (IS)

$$\mathbb{E}_{\pi(x)}[f(x)] \approx \hat{\mu} := \frac{1}{N} \sum_{n=1}^N f(x_n) w_n$$

$$\text{where } x_n \sim q(x), w_n = \frac{\pi(x_n)}{q(x_n)}$$

$$\mathbb{E}[\hat{\mu}] = \mathbb{E}_{\pi(x)}[f(x)]$$

$$\text{Var}[\hat{\mu}] = \frac{\text{Var}[f(x_1)w_1]}{N}$$

Importance Sampling (IS)

When $f(x) \geq 0$ and $q(x) \propto \pi(x)f(x)$

yields an exact estimate using a single sample

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$$q^*(x) \propto f(x)\pi(x)$$

$$\implies q^*(x) = \frac{f(x)\pi(x)}{\int f(x)\pi(x)dx} = \frac{f(x)\pi(x)}{\mathbb{E}_{\pi(x)}[f(x)]}$$

$$f(x_1)w_1 = f(x_1)\frac{\pi(x_1)}{q^*(x_1)} = f(x_1)\frac{\pi(x_1)}{\frac{f(x_1)\pi(x_1)}{\mathbb{E}_{\pi(x)}[f(x)]}} = \mathbb{E}_{\pi(x)}[f(x)]$$

Self-Normalized Importance Sampling (SNIS)

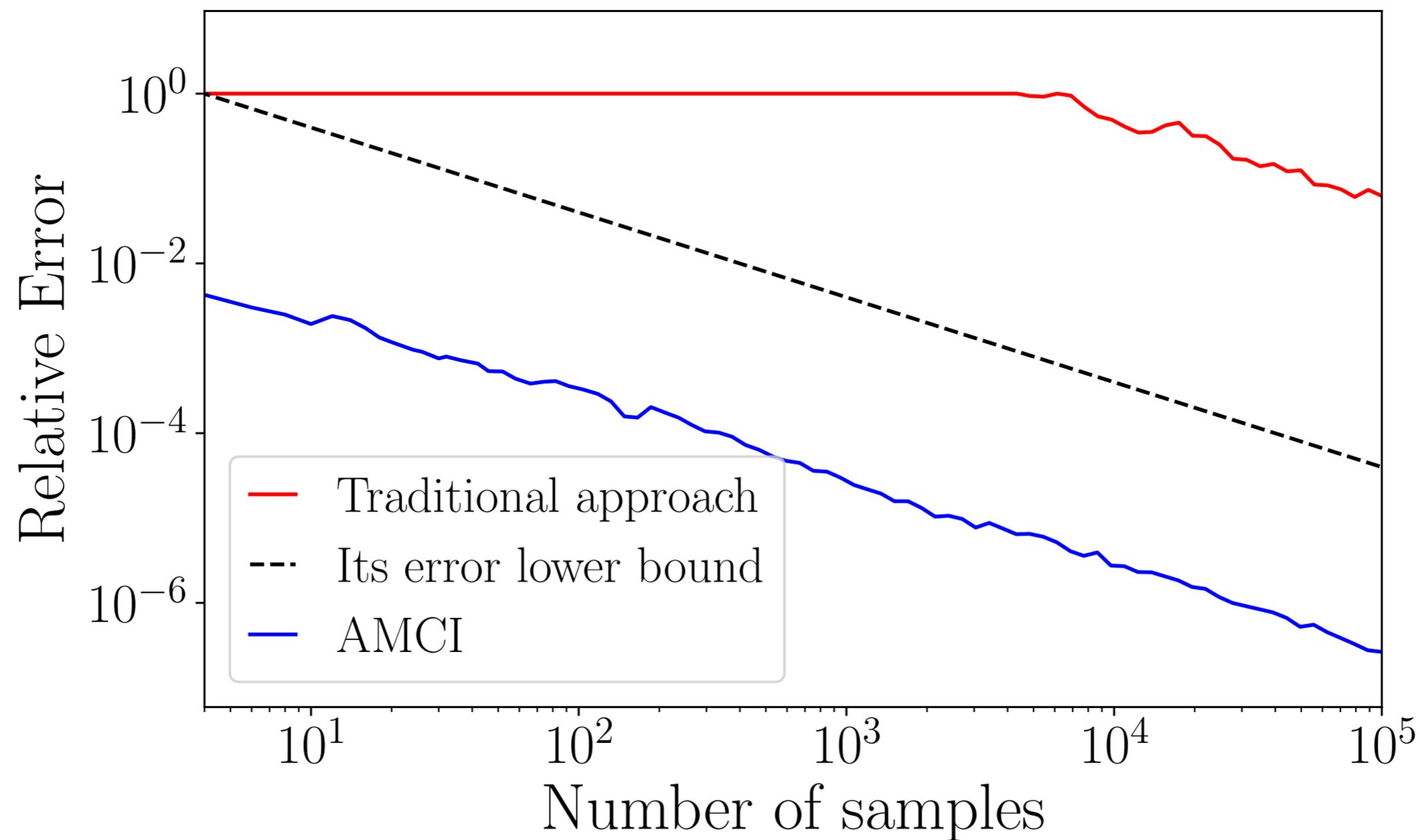
$$\mathbb{E}_{p(x|y)} [f(x)]$$

Self-Normalized Importance Sampling (SNIS)

$$\begin{aligned}\mathbb{E}_{p(x|y)}[f(x)] &= \frac{\mathbb{E}_{p(x)}[f(x)p(y|x)]}{\mathbb{E}_{p(x)}[p(y|x)]} \\ &\approx \frac{\frac{1}{N} \sum_{n=1}^N f(x_n) w_n}{\frac{1}{N} \sum_{n=1}^N w_n}\end{aligned}$$

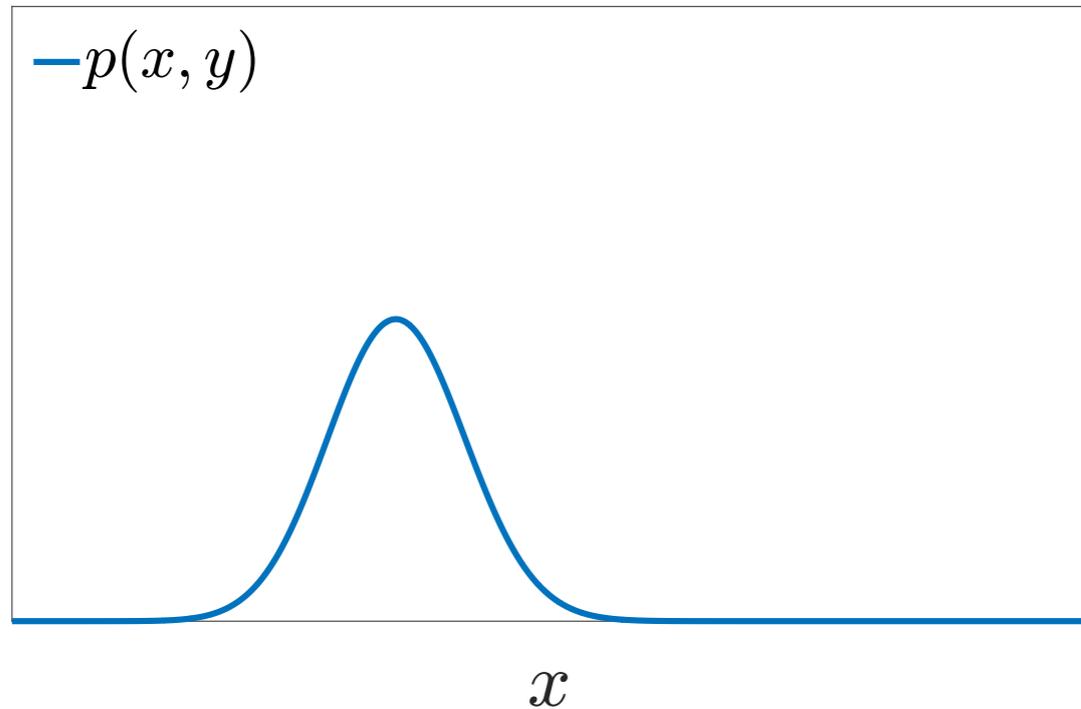
$$x_n \sim q(x)$$

$$w_n = \frac{p(x_n, y)}{q(x_n)}$$

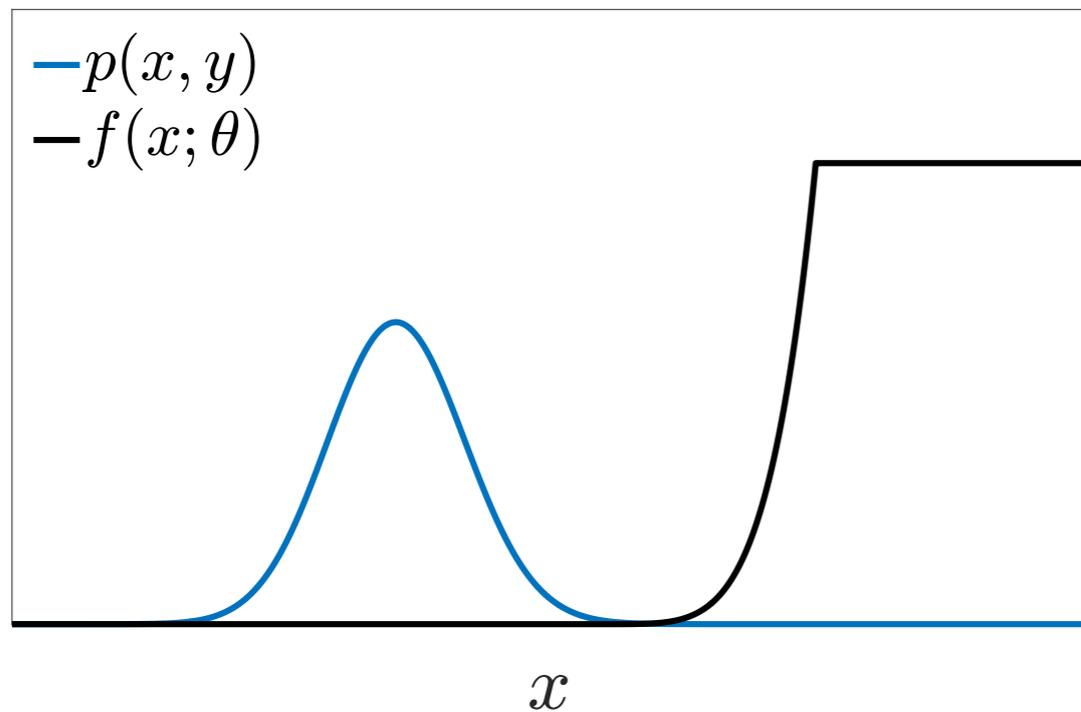




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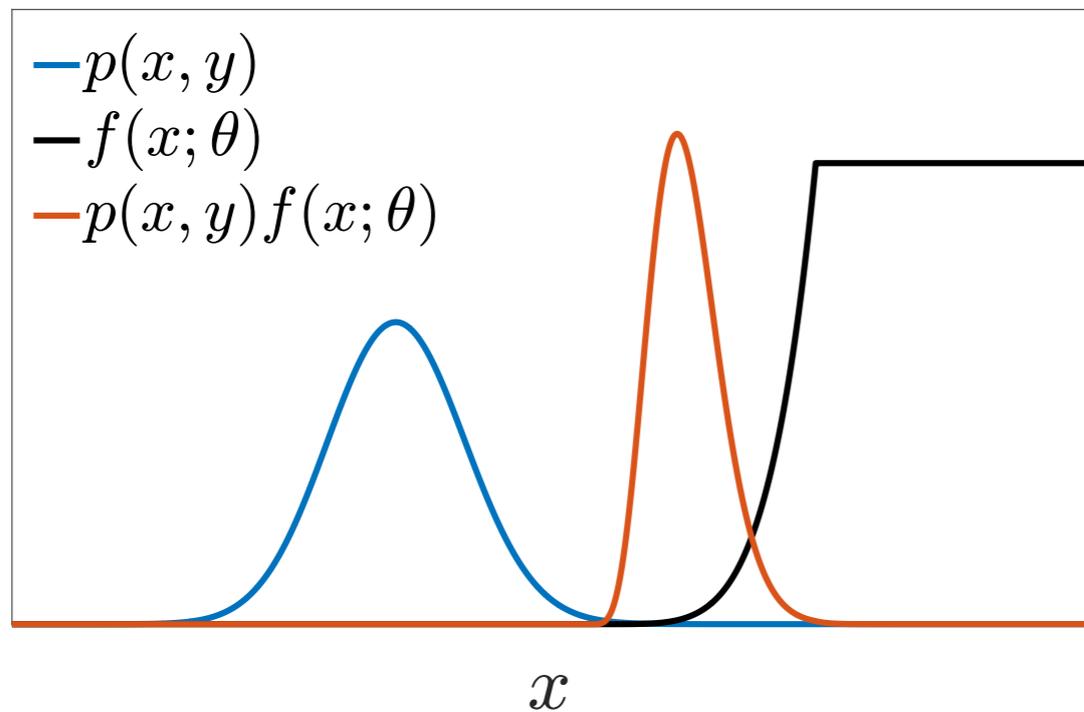


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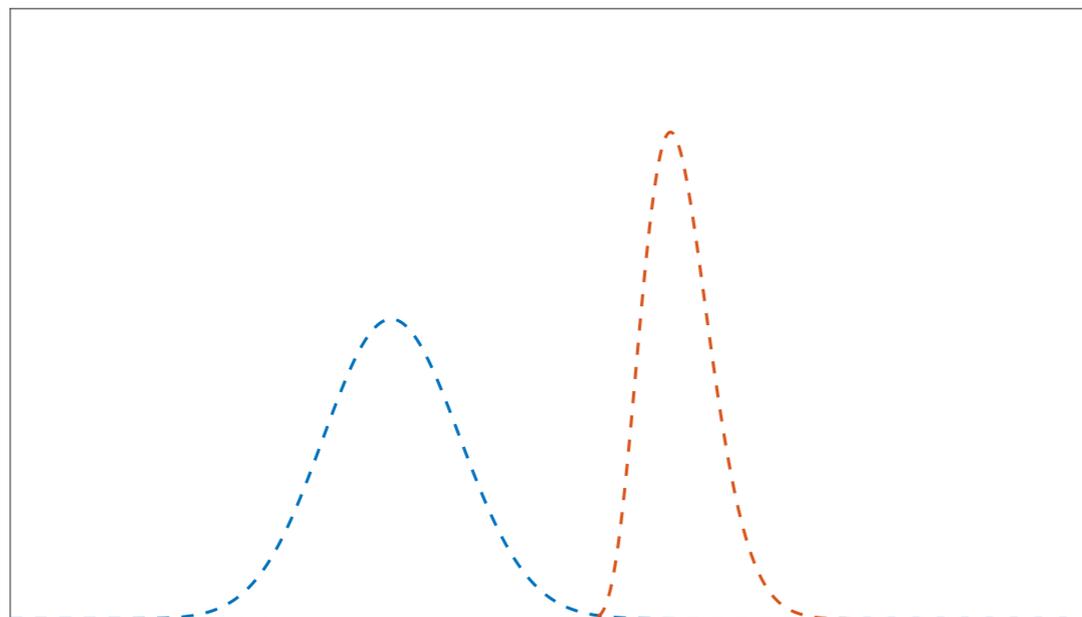
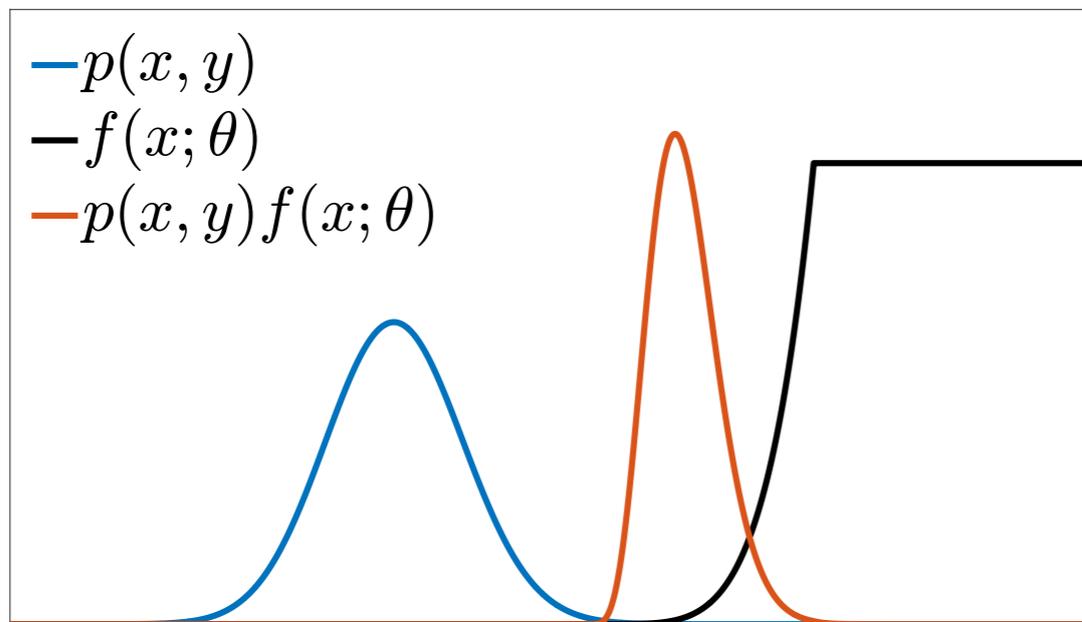
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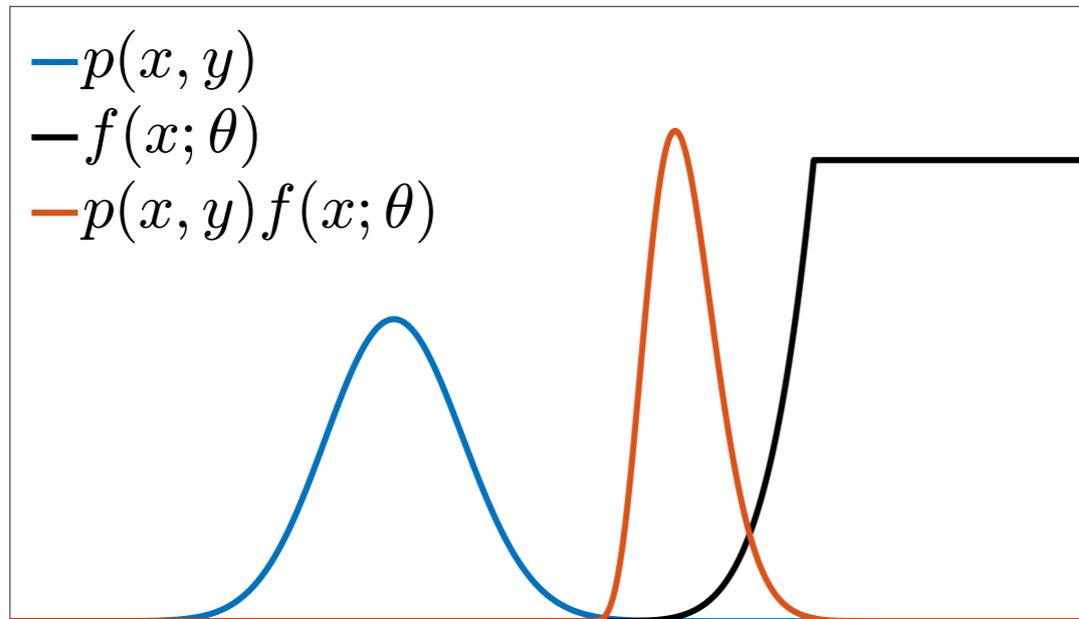
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x

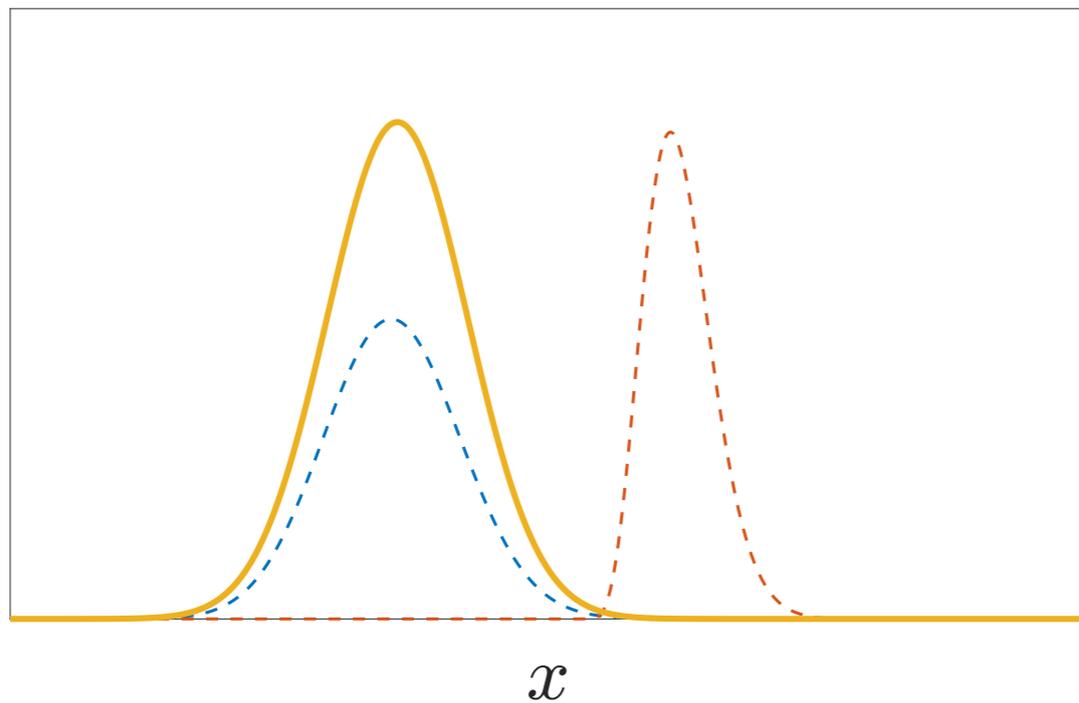
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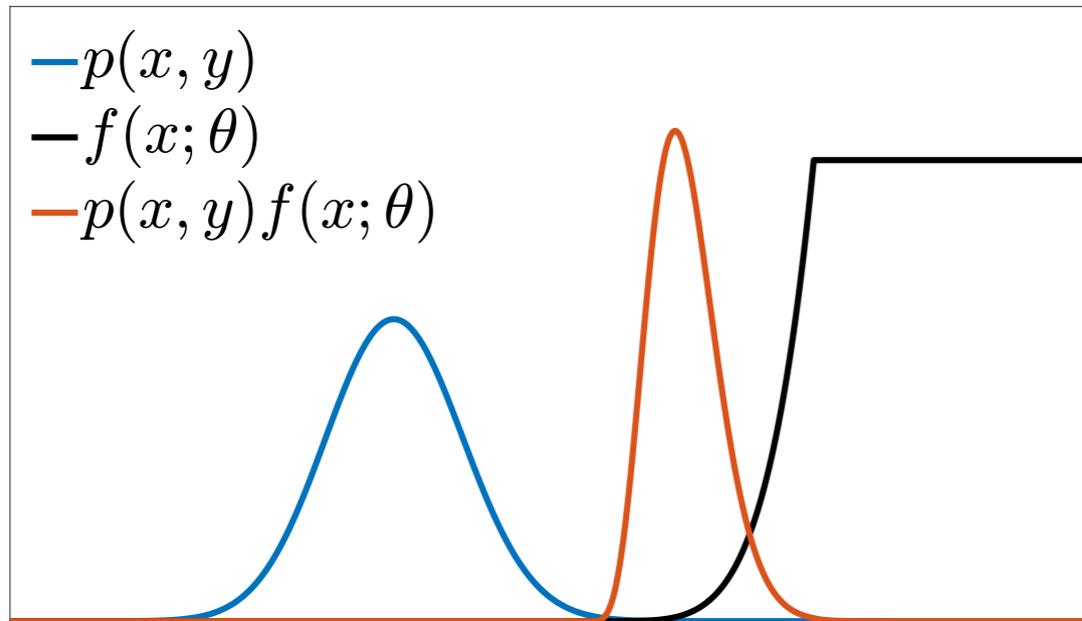


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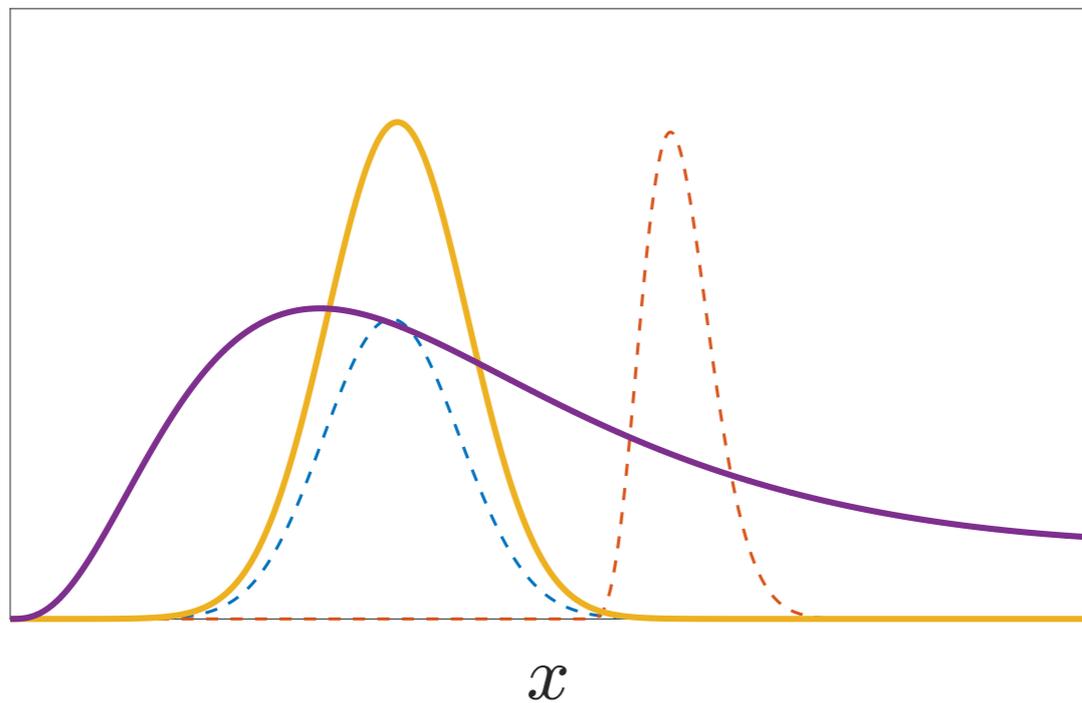


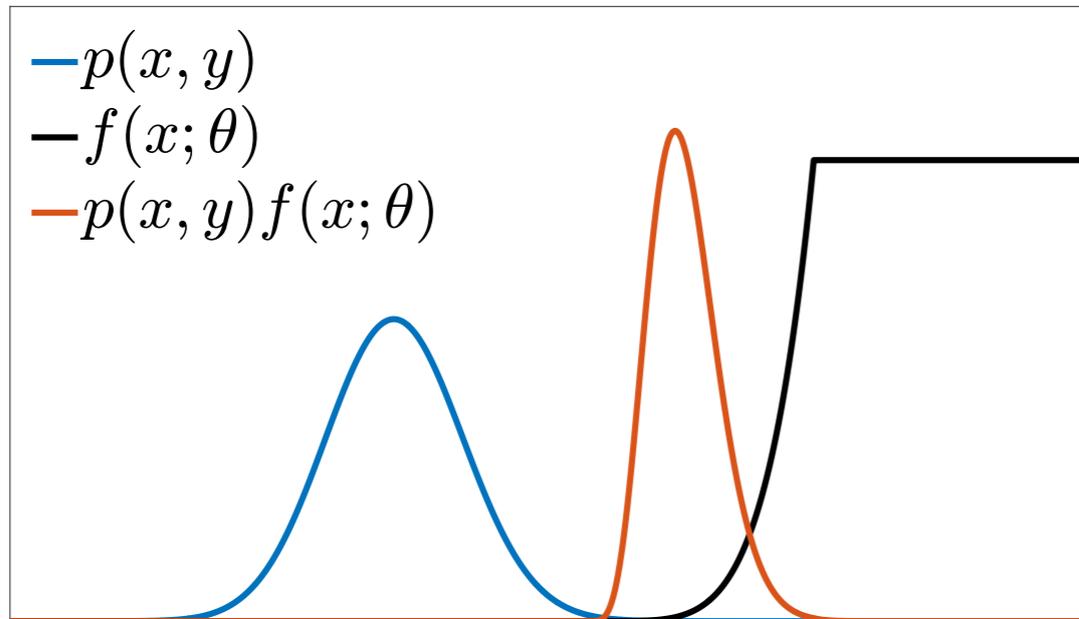
— $q(x)$



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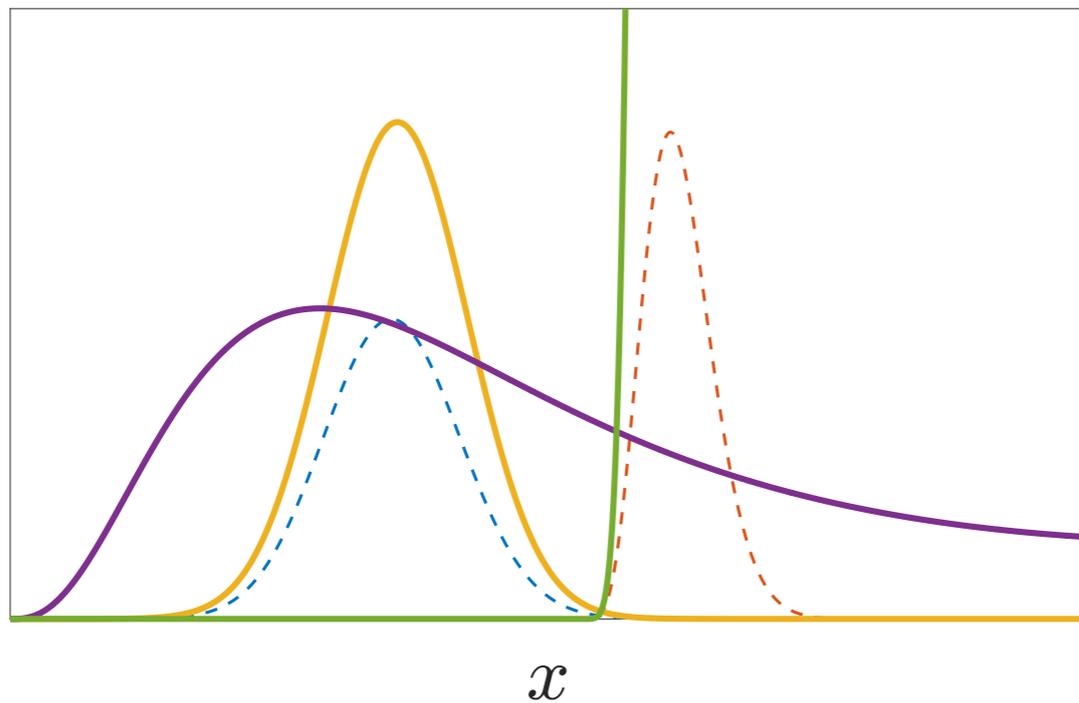
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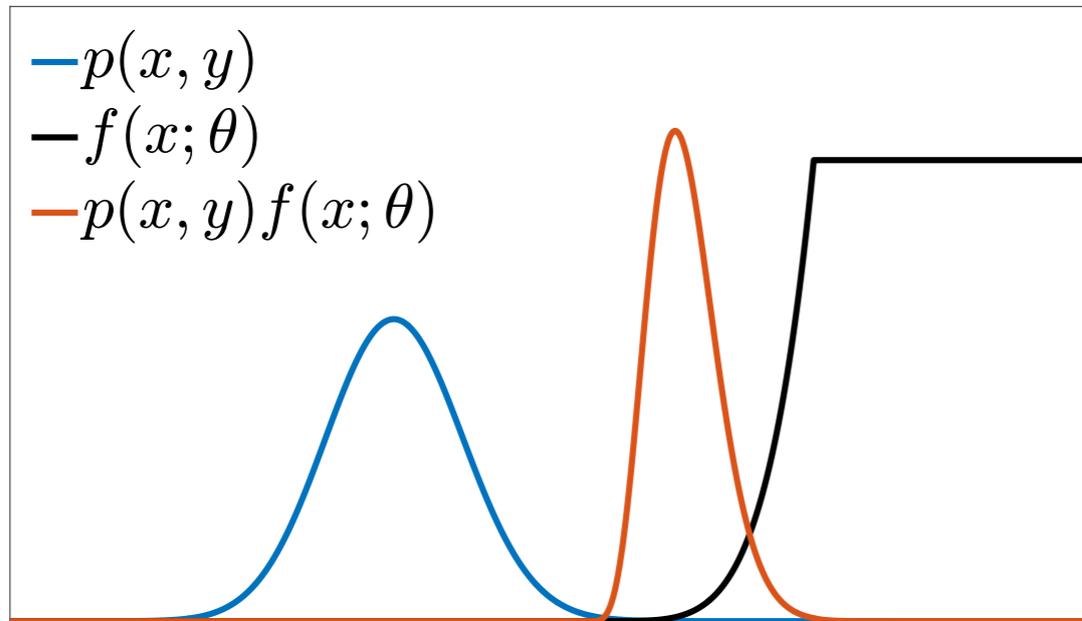




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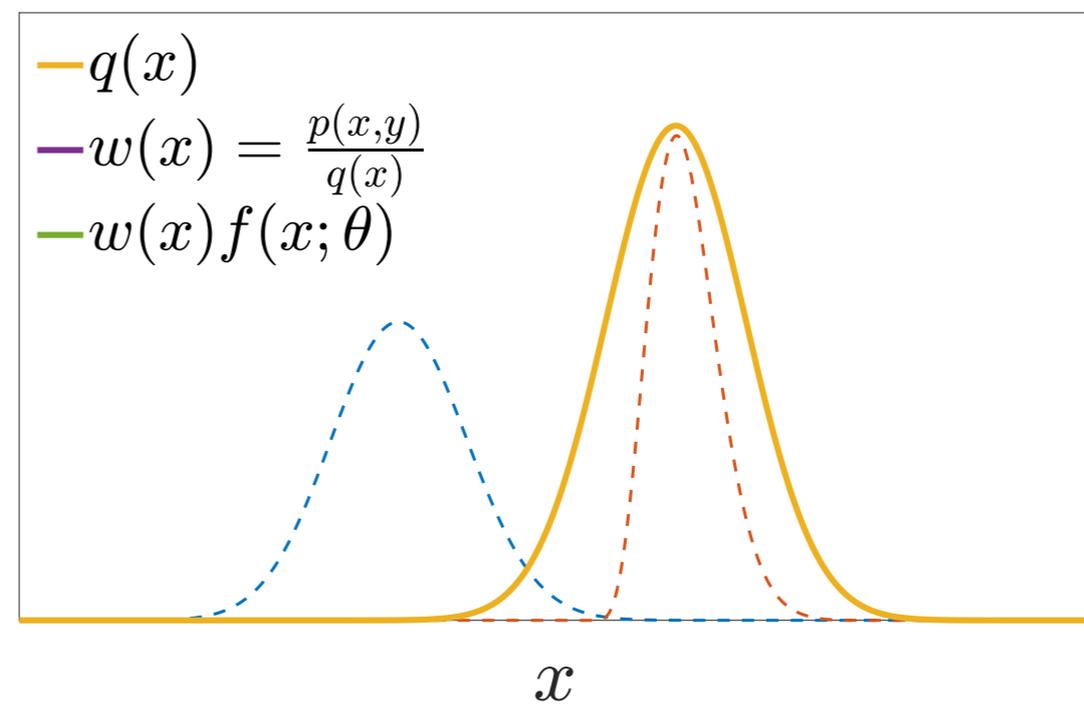
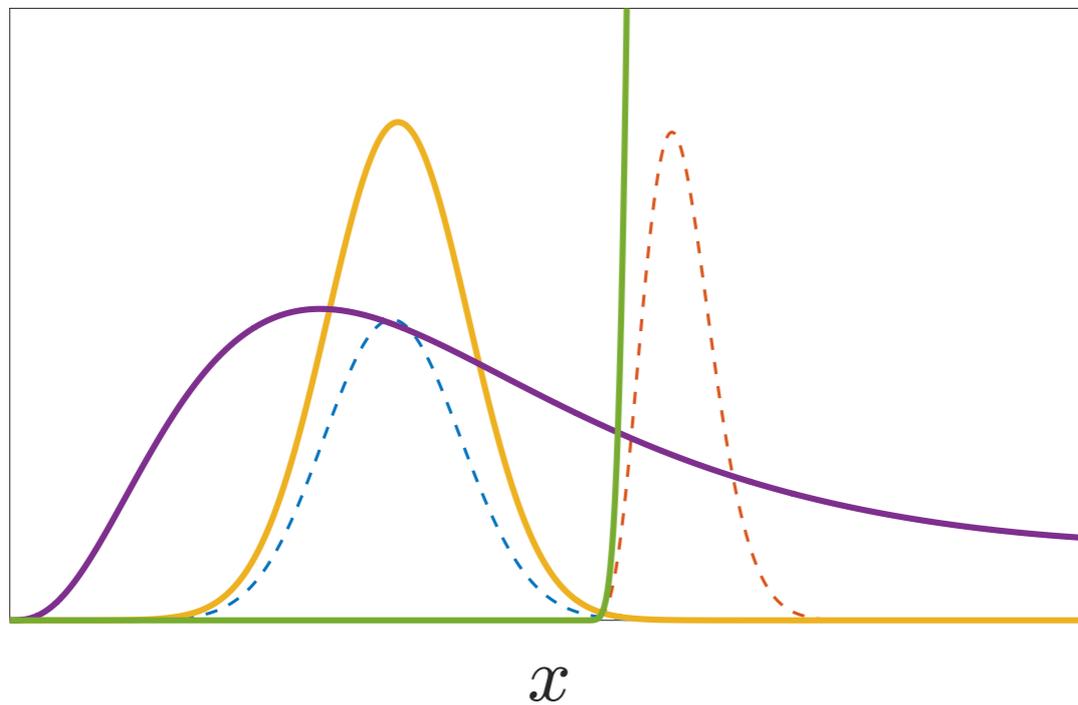
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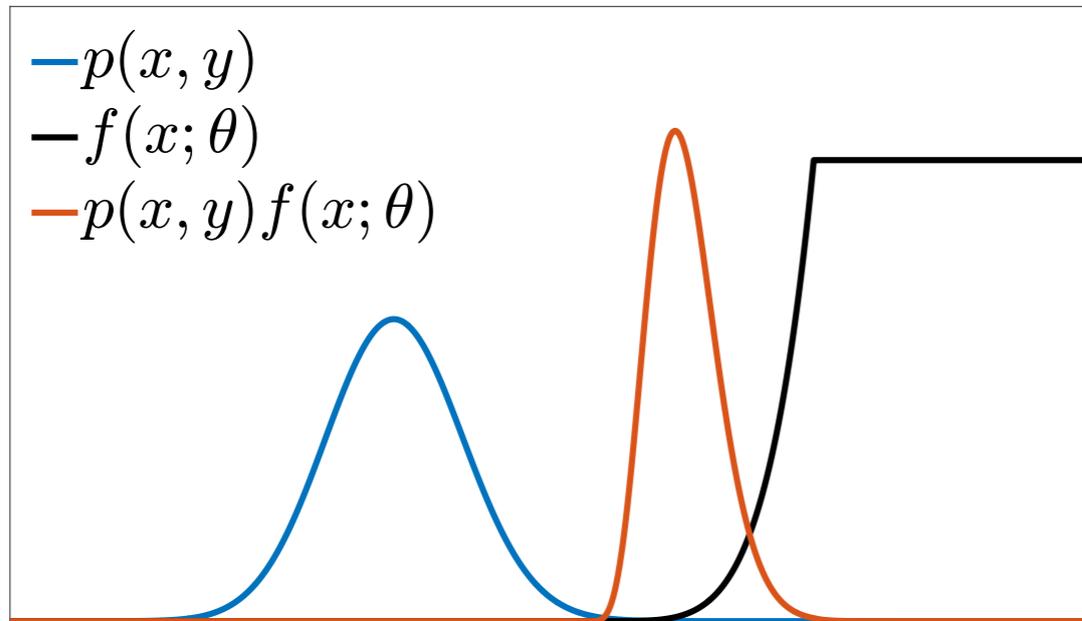




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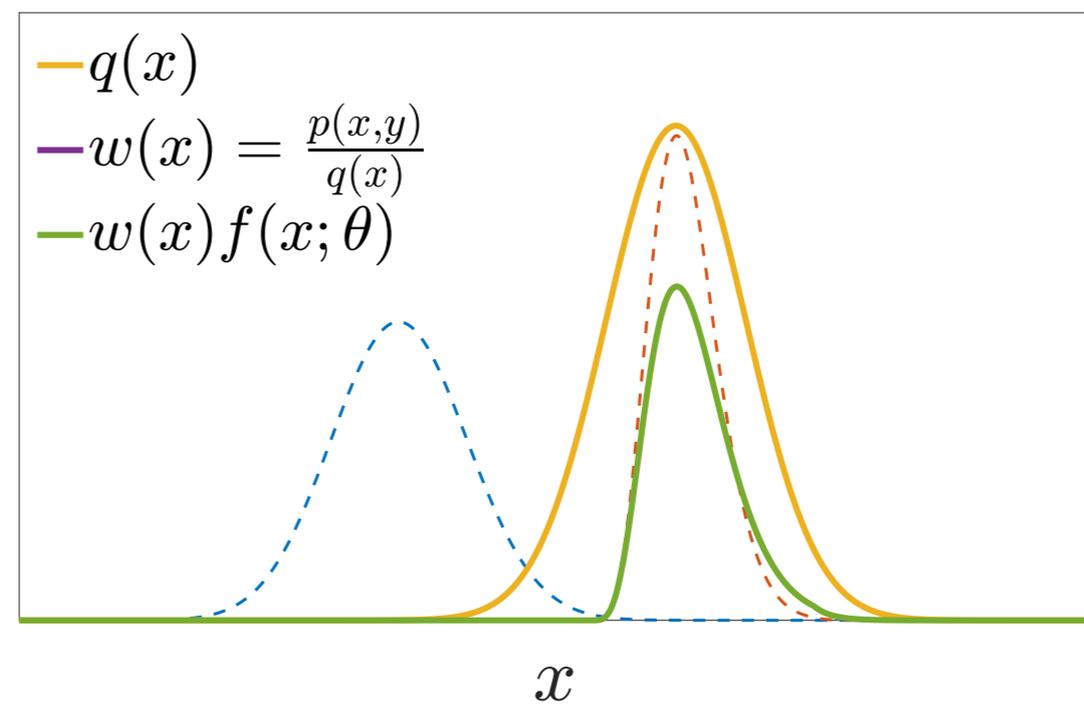
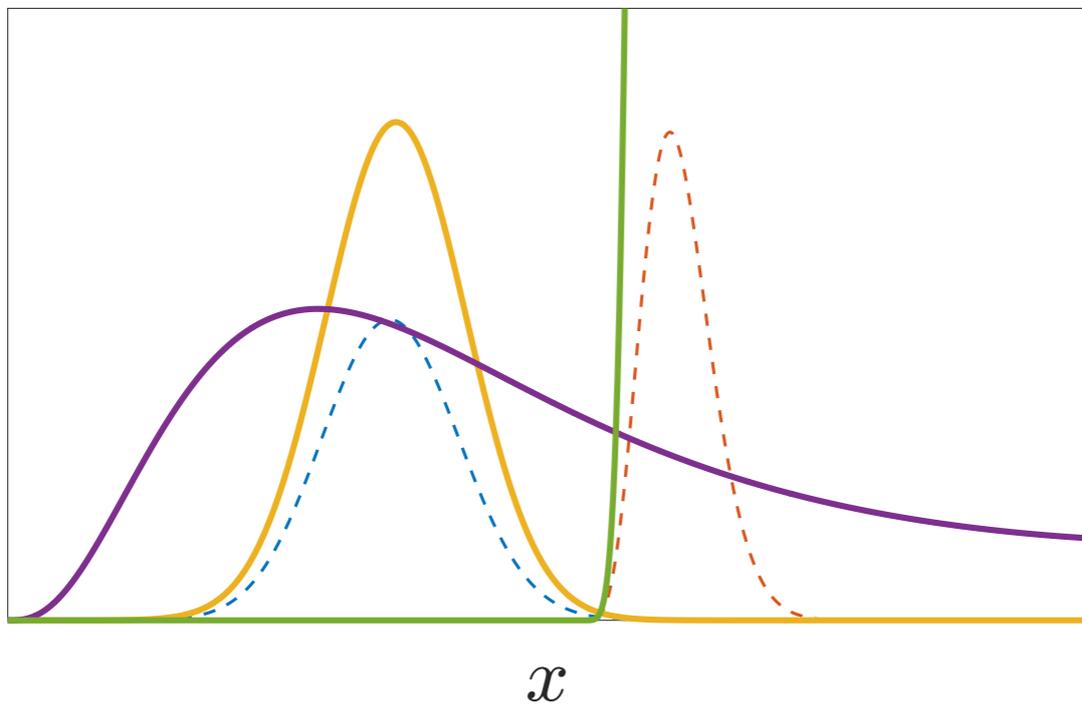
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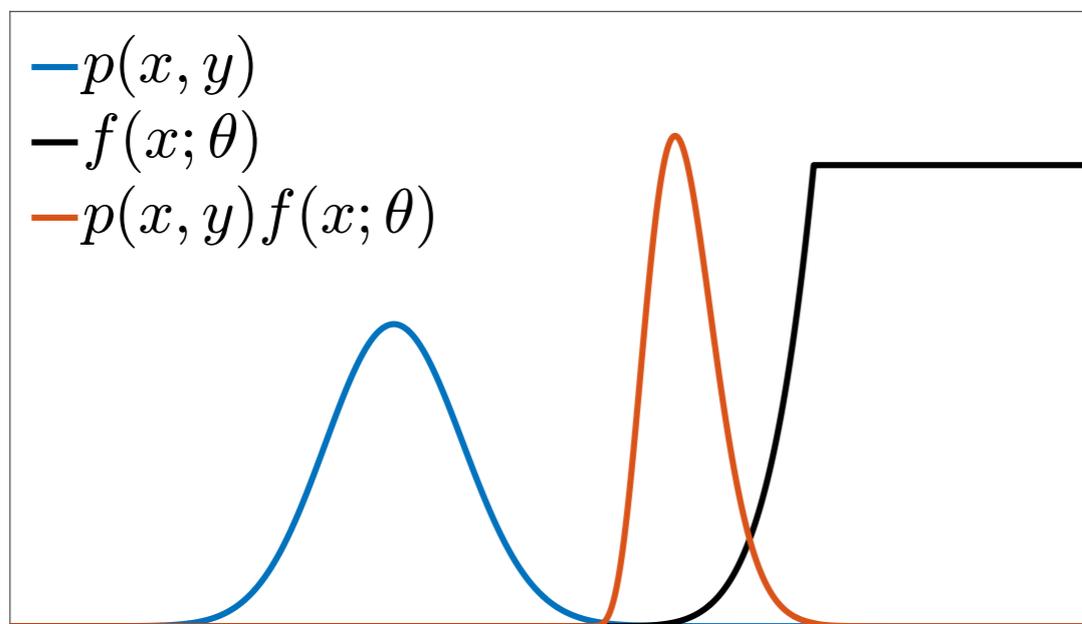




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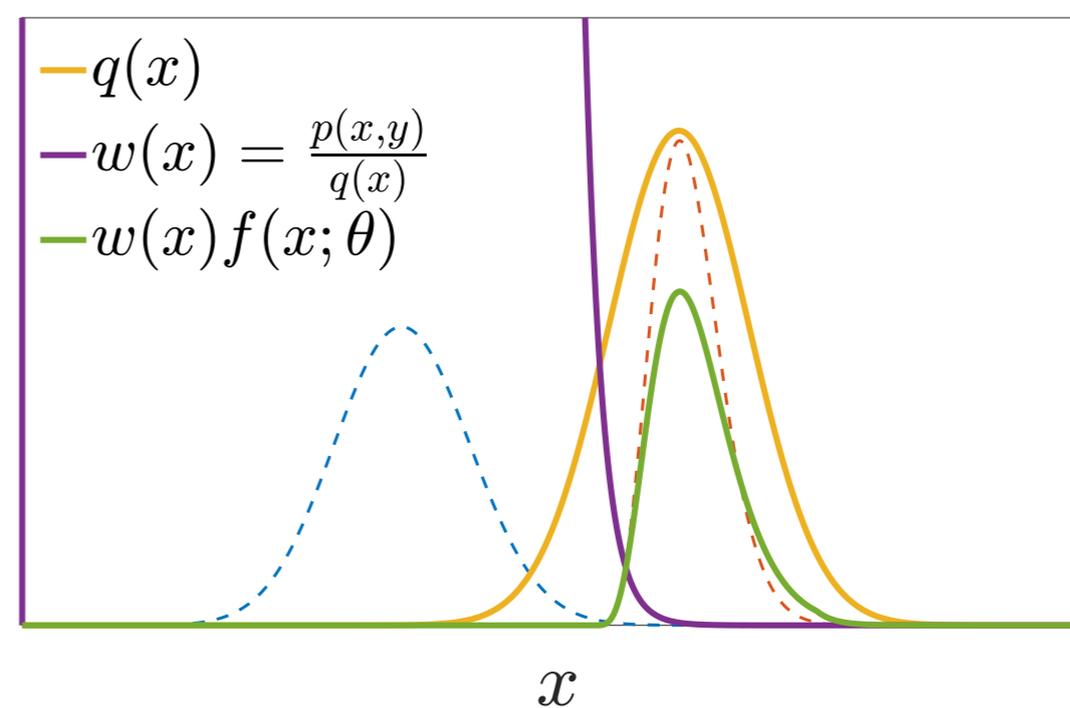
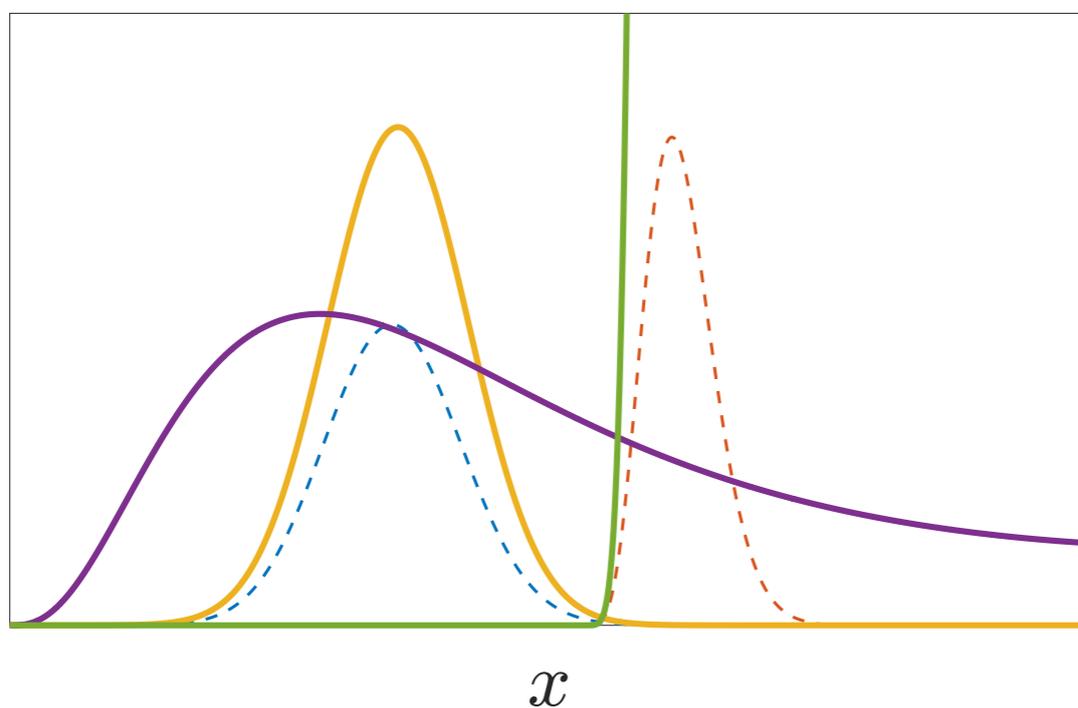
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$$\approx \frac{\frac{1}{N} \sum_{n=1}^N f(x_n) w_n}{\frac{1}{N} \sum_{n=1}^N w_n}$$



Self-Normalized Importance Sampling (SNIS)

$$\text{Mean Squared Error} \geq \frac{1}{N} \left(\mathbb{E}_{p(x|y)} [|f(x) - \mathbb{E}_{p(x|y)}[f(x)]|] \right)^2$$



**Solution: Use Multiple
Proposals Targeting Different
Aspects of the Problem**

The AMCI Estimator

$$\mathbb{E}_{p(x|y)} [f(x; \theta)] = \frac{\mathbb{E}_{p(x)} [f(x; \theta) p(y|x)]}{\mathbb{E}_{p(x)} [p(y|x)]}$$

The AMCI Estimator

$$f^+(x; \theta) = \max(f(x; \theta), 0)$$

$$f^-(x; \theta) = -\min(f(x; \theta), 0)$$

$$f(x; \theta) = f^+(x; \theta) - f^-(x; \theta)$$

$$\mathbb{E}_{p(x|y)}[f(x; \theta)] = \frac{\mathbb{E}_{p(x)}[f(x; \theta)p(y|x)]}{\mathbb{E}_{p(x)}[p(y|x)]}$$

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The AMCI Estimator

$$E_2 = \mathbb{E}_{p(x)} [p(y|x)]$$

$$E_1^+ = \mathbb{E}_{p(x)} [\max(f(x; \theta), 0)p(y|x)]$$

$$E_1^- = \mathbb{E}_{p(x)} [-\min(f(x; \theta), 0)p(y|x)]$$

The AMCI Estimator

$$E_2 = \mathbb{E}_{p(x)} [p(y|x)] \approx \hat{E}_2 = \frac{1}{M} \sum_{m=1}^M \frac{p(x_m, y)}{q_2(x_m; y)}$$

$$E_1^+ = \mathbb{E}_{p(x)} [\max(f(x; \theta), 0)p(y|x)] \approx \hat{E}_1^+ = \frac{1}{N} \sum_{n=1}^N \frac{f^+(x_n^+; \theta)p(x_n^+, y)}{q_1^+(x_n^+; y, \theta)}$$

$$E_1^- = \mathbb{E}_{p(x)} [-\min(f(x; \theta), 0)p(y|x)] \approx \hat{E}_1^- = \frac{1}{K} \sum_{k=1}^K \frac{f^-(x_k^-; \theta)p(x_k^-, y)}{q_1^-(x_k^-; y, \theta)}$$

AMCI Can Produce Perfect Estimates with a Single Sample from Each Proposal!

Theorem 1. *If $q_2(x; y) \propto p(x, y)$, $q_1^+(x; y, \theta) \propto f^+(x; \theta)p(x, y)$, and $q_1^-(x; y, \theta) \propto f^-(x; \theta)p(x, y)$, then the AMCI estimator $(\hat{E}_1^+ - \hat{E}_1^-) / \hat{E}_2$ is an exact estimator for $\mathbb{E}_{p(x|y)}[f(x; \theta)]$ even if $N = K = M = 1$*



Amortized Inference



Amortized Inference

$$D_{KL}[p(x|y) || q_2(x; y, \eta)]$$

Amortized Inference

$$\mathcal{J}_{q_2}(\eta) = \mathbb{E}_{p(y)} [D_{KL}[p(x|y) || q_2(x; y, \eta)]]$$



Amortized Inference

$$\begin{aligned}\mathcal{J}_{q_2}(\eta) &= \mathbb{E}_{p(y)} [D_{KL}[p(x|y) || q_2(x; y, \eta)]] \\ &= \mathbb{E}_{p(x,y)} [-\log q_2(x; y, \eta)] + \text{const wrt } \eta\end{aligned}$$



Amortizing Monte Carlo Integration



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To amortize over function parameters, we introduce a pseudo prior $p(\theta)$

Amortizing Monte Carlo Integration

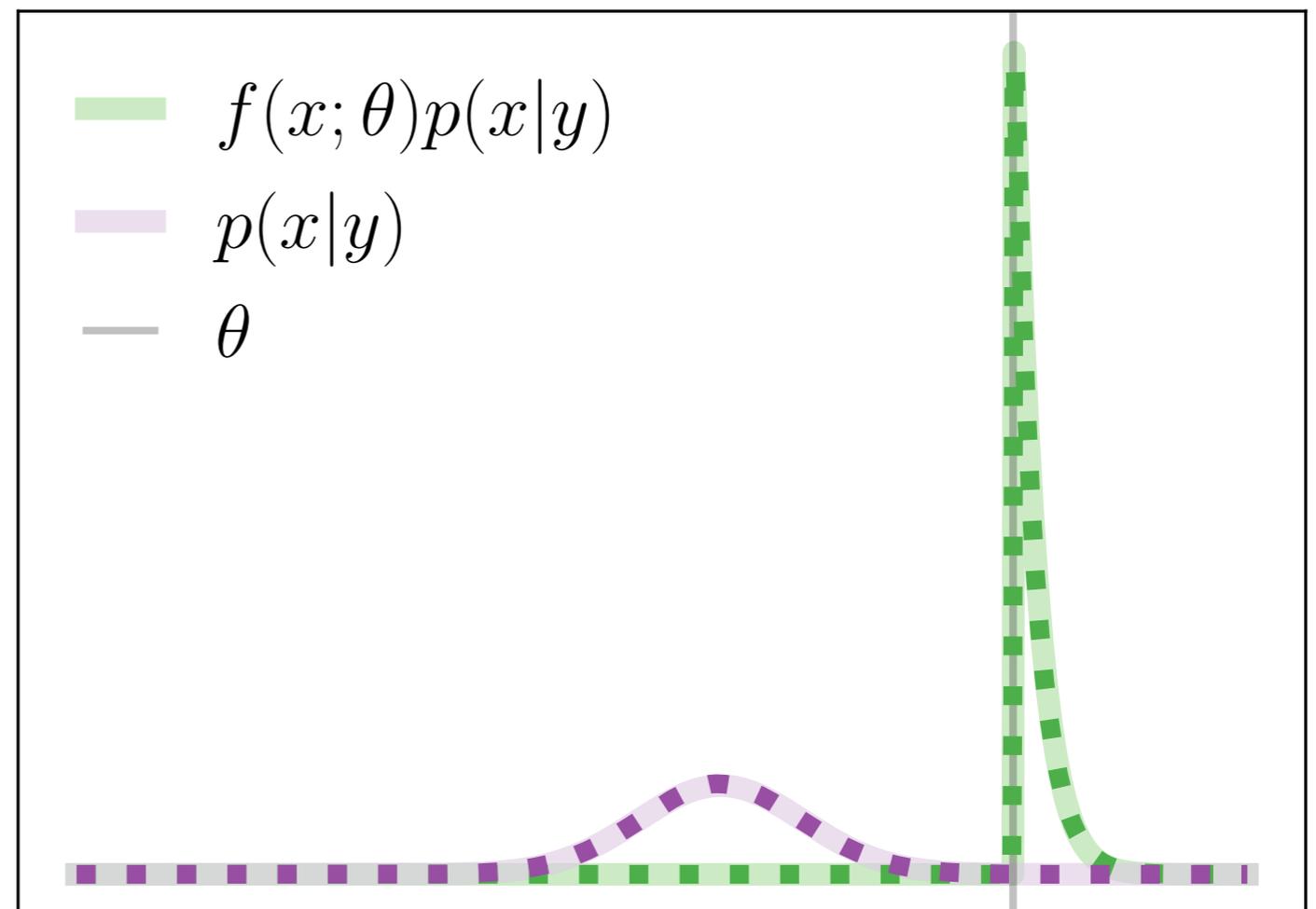
To amortize over function parameters, we introduce a pseudo prior $p(\theta)$

$$q_1^\pm \propto f^\pm(x; \theta) p(x, y)$$

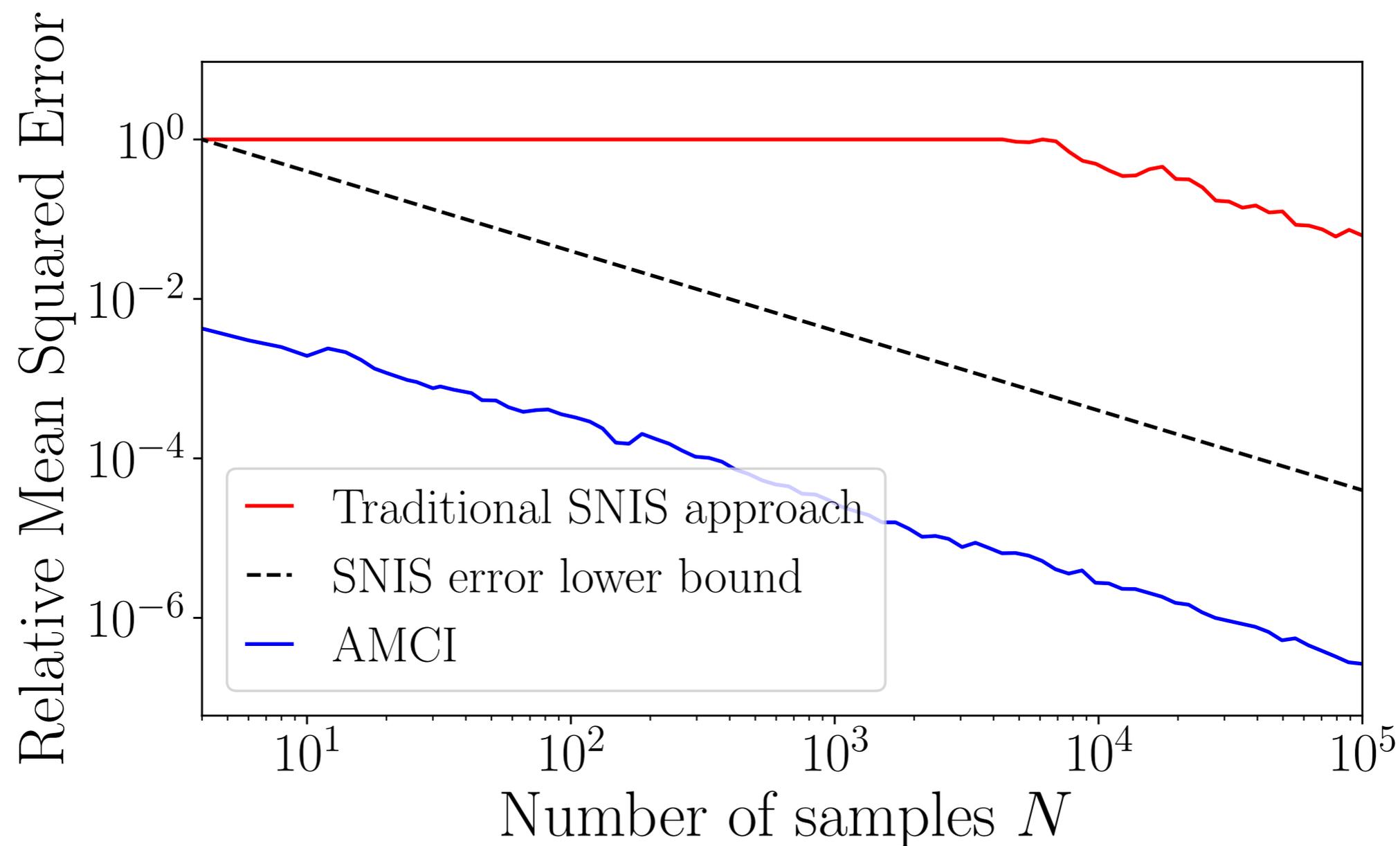
$$\mathcal{J}_{q_1^\pm}(\eta) = \mathbb{E}_{p(x, y) p(\theta)} \left[-f^\pm(x; \theta) \log q_1^\pm(x; y, \theta, \eta) \right] + \text{const}$$

Experiments: Gaussian Tail Integral

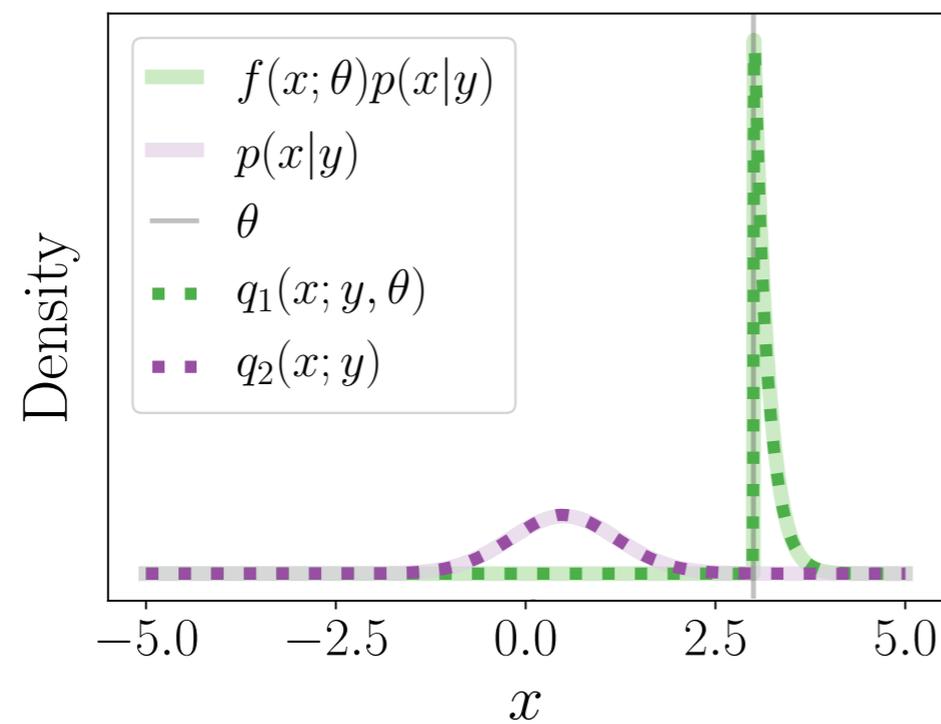
$$p(x) = \mathcal{N}(x; 0, 1)$$
$$p(y|x) = \mathcal{N}(y; x, 1)$$
$$f(x; \theta) = \mathbb{1}_{x > \theta}$$



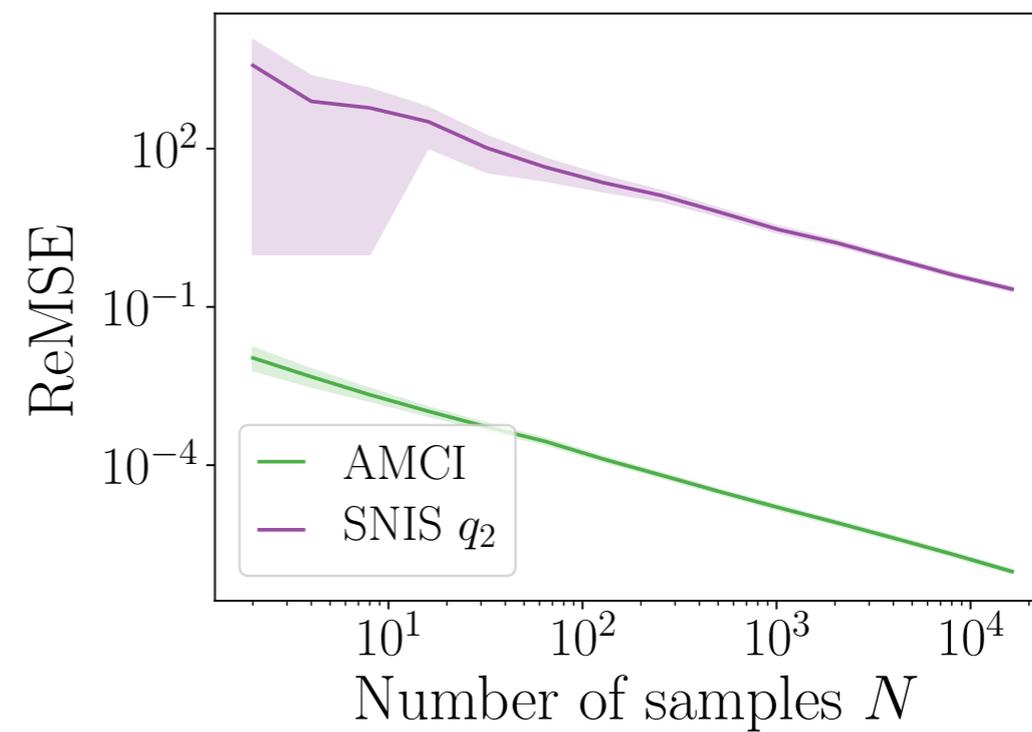
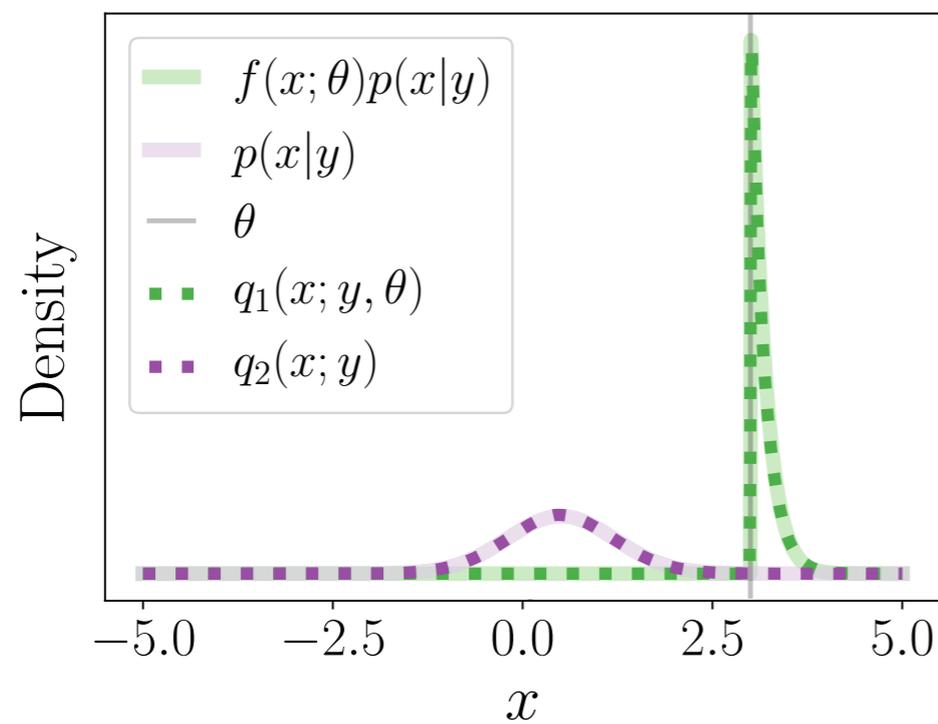
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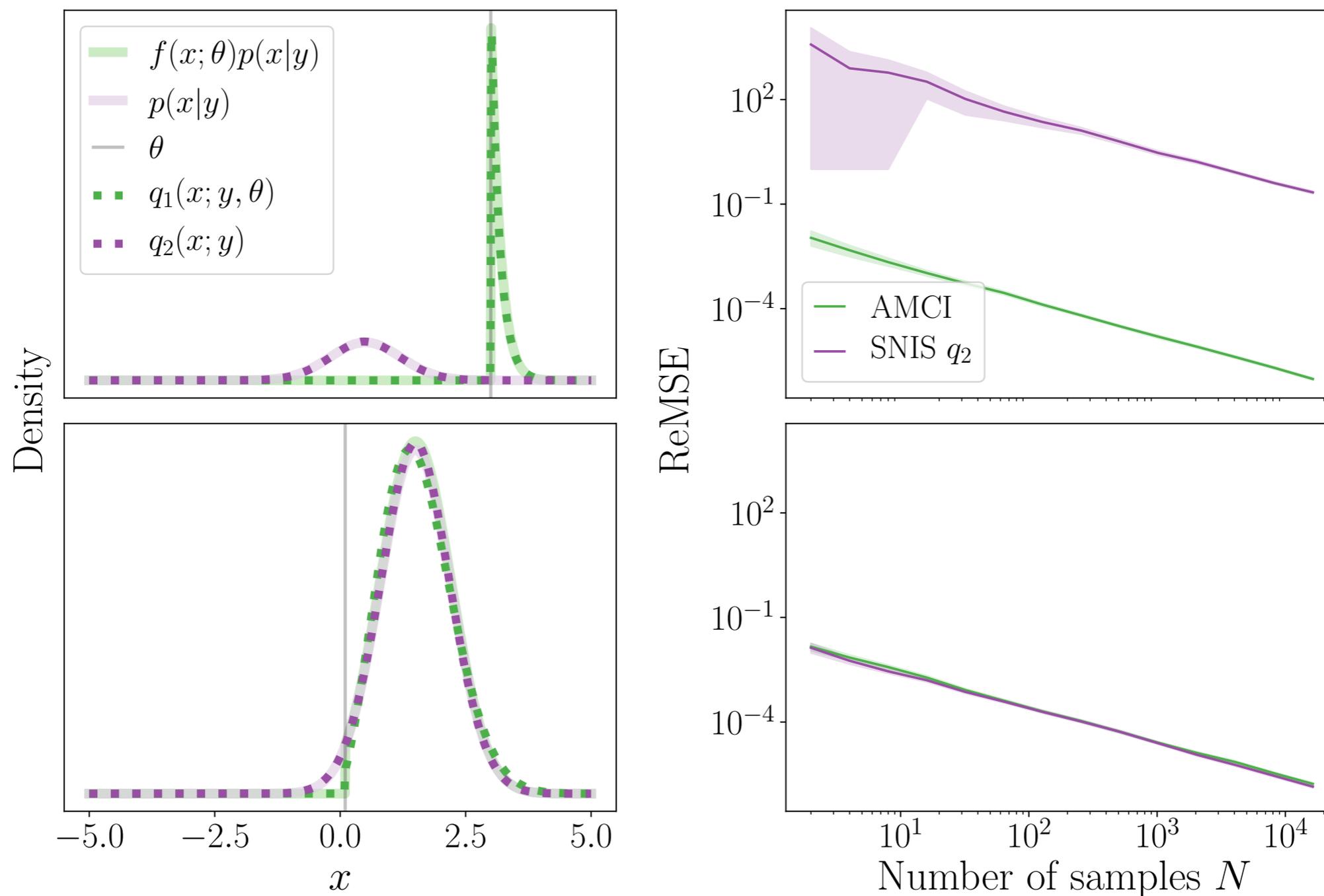
When Does AMCI Work Well in Practice?



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Recap

- ▶ Amortized inference focuses on approximating the posterior $p(x|y)$, later using this to estimate expectation(s) $\mathbb{E}_{p(x|y)}[f(x; \theta)]$
- ▶ This pipeline is inefficient if $f(x; \theta)$ is known upfront
- ▶ AMCI instead targets $\mathbb{E}_{p(x|y)}[f(x; \theta)]$ directly, allowing amortization over datasets y and/or function parameters θ
- ▶ It can give exact estimates for any expectation with only a single sample from each of three separate amortized proposals
- ▶ It can empirically outperform the theoretically optimal self-normalized importance sampler, even in non-amortized settings



Adam Goliński

 @adam_golinski



Frank Wood

 @frankdonaldwood



Tom Rainforth

 @tom_rainforth



Come see us at poster #999
today at 6.30pm!

When Does AMCI Work Well in Practice?

κ is a measure of relative performance of top and bottom estimators
For AMCI, we can control κ , for SNIS we cannot

$$\text{MSE} \approx \frac{\sigma_2^2}{E_2^2} \cdot \left((\kappa - \text{Corr}[\xi_1, \xi_2])^2 + 1 - \text{Corr}[\xi_1, \xi_2]^2 \right)$$

Intractability in the naively adjusted objective

$$E_1(y) := \mathbb{E}_{p(x)} [f(x)p(y|x)]$$

$$g(x|y) := \frac{f(x)p(x,y)}{E_1(y)}$$

$$\begin{aligned} \mathcal{J}'_{q_1}(\eta) &= \mathbb{E}_{p(y)} [D_{KL}(g(x|y) || q_1(x; y, \eta))] \\ &= \mathbb{E}_{p(y)} \left[- \int_{\mathcal{X}} \frac{f(x)p(x,y)}{E_1(y)} \log q_1(x; y, \eta) dx \right] + \text{const} \end{aligned}$$

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$$h(y) \propto p(y)E_1(y)$$

$$\begin{aligned} \mathcal{J}_{q_1}(\eta) &= \mathbb{E}_{h(y)} [D_{KL}(g(x|y) || q_1(x; y, \eta))] \\ &= \frac{1}{\text{const}} \mathbb{E}_{p(x,y)} [-f(x) \log q_1(x; y, \eta)] + \text{const} \end{aligned}$$

Experiments: Cancer Treatment Planning

